

**Environmental Assessment of a
Marine Geophysical Survey by the R/V *Marcus G. Langseth*
in the Pacific Ocean off Costa Rica,
April–May 2011**

Draft

Prepared for

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20 October 2010
Revised 1 November 2010

LGL Report TA4926-1

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ABSTRACT

Lamont-Doherty Earth Observatory (L-DEO), with research funding from the U.S. National Science Foundation (NSF), plans to conduct a marine seismic survey in the eastern tropical Pacific Ocean (ETP) off Costa Rica during April–May 2011. The survey will take place in the Exclusive Economic Zone (EEZ) of Costa Rica in water depths from <100 m to >2500 m. The airgun array will consist of two subarrays of 18 airguns firing alternately, each with a total volume of ~3300 in³.

NSF, as the funding and action agency, has a mission to “promote the progress of science; to advance the national health, prosperity, and welfare; to secure the national defense...”. The proposed seismic survey is part of a research proposal recommended for funding by an expert review panel. It will provide data integral to advancing scientific understanding of the structure and geometry of a major thrust fault that is capable of generating very powerful earthquakes and tsunamis, the physical conditions along the fault and their down dip variability, and the structures overlying the fault.

L-DEO is requesting an Incidental Harassment Authorization (IHA) from the U.S. National Marine Fisheries Service (NMFS) to authorize the incidental, i.e., not intentional, harassment of small numbers of marine mammals should this occur during the seismic survey. The information in this Environmental Assessment (EA) supports the IHA application process and provides information on marine species that are not addressed by the IHA application, including birds, sea turtles, invertebrates, and fish. The EA addresses the requirements of Executive Order 12114, “Environmental Effects Abroad of Major Federal Actions”. Alternatives addressed in this EA consist of a corresponding program at a different time, along with issuance of an associated IHA; and the no action alternative, with no IHA and no seismic survey.

Numerous species of cetaceans and pinnipeds inhabit the ETP. Several of these species are listed as *endangered* under the ESA, including the humpback, sei, fin, blue, and sperm whales. Other species of special concern that could occur in the study area are the *endangered* leatherback and hawksbill turtles, the *threatened* loggerhead, green, and olive ridley turtles, and the *endangered* California least tern.

Potential impacts of the seismic survey on the environment would be primarily a result of the operation of the airgun array. A multibeam echosounder and a sub-bottom profiler will also be operated. Impacts would be associated with increased underwater noise, which may result in avoidance behavior by marine mammals, sea turtles, and fish, and other forms of disturbance. An integral part of the planned survey is a monitoring and mitigation program designed to minimize impacts of the proposed activities on marine animals present during the proposed research, and to document as much as possible the nature and extent of any effects. Injurious impacts to marine mammals and sea turtles have not been proven to occur near airgun arrays, and also are not likely to be caused by the other types of sound sources to be used. However, given the high levels of sound emitted by a large array of airguns, a precautionary approach is warranted. The planned monitoring and mitigation measures would reduce the possibility of injurious effects.

Protection measures designed to mitigate the potential environmental impacts to marine mammals and turtles will include the following: ramp ups, minimum of one dedicated observer maintaining a visual watch during all daytime airgun operations, two observers 30 min before and during ramp ups during the day and at night (and when possible at other times), no start ups during poor visibility or at night unless at least one airgun has been operating, passive acoustic monitoring (PAM) via towed hydrophones during both day and night to complement visual monitoring, and power downs (or if necessary shut downs) when marine mammals or sea turtles are detected in or about to enter designated exclusion zones. L-DEO and its contractors are committed to apply these measures in order to minimize effects on marine mammals and sea turtles and other environmental impacts.

With the planned monitoring and mitigation measures, unavoidable impacts to each species of marine mammal and turtle that could be encountered are expected to be limited to short-term, localized changes in behavior and distribution near the seismic vessel. At most, effects on marine mammals may be interpreted as falling within the U.S. Marine Mammal Protection Act (MMPA) definition of “Level B Harassment” for those species managed by NMFS. No long-term or significant effects are expected on individual marine mammals, sea turtles, the populations to which they belong, or their habitats.

LIST OF ACRONYMS

~	approximately
AAPA	American Association of Port Authorities
ACOPAC	Central Pacific Conservation Area
ACOSA	Osa Conservation Area
ACS	American Cetacean Society
CITES	Convention on International Trade in Endangered Species
CPA	Closest Point of Approach
CPUE	Catch per Unit Effort
CRC	Cascadia Research Collective
CRD	Costa Rica Dome
CRFR	Costa Rica Fishing Report
CRTG	Costa Rica Travel Guide
CRTTB	Costa Rica Tourism and Travel Bureau
CV	Coefficient of Variation
CW	Continuous wave
CZMA	Coastal Zone Management Act
DFO	Fisheries and Oceans Canada
DoD	Department of Defense
DoN	U.S. Department of the Navy
EA	Environmental Assessment
EEZ	Exclusive Economic Zone
EFH	Essential Fish Habitat
ESA	(U.S.) Endangered Species Act
ETP	Eastern Tropical Pacific
FAO	Food and Agriculture Organization
FM	Frequency modulated
ft	feet
$\text{gCm}^{-2}\text{d}^{-1}$	grams of Carbon per meter squared per day
GIS	Geographic Information System
GT	Gross Tonnes
h	hour
ha	hectare
hp	horsepower
IAGC	International Association of Geophysical Contractors
IATTC	Inter-American Tropical Tuna Commission
IHA	Incidental Harassment Authorization (under U.S. MMPA)
in	inch
IUCN	International Union for the Conservation of Nature
IWC	International Whaling Commission
kHz	kilohertz
kt	knot
L-DEO	Lamont-Doherty Earth Observatory of Columbia University
<i>Langseth</i>	<i>R/V Marcus G. Langseth</i>
LME	Large Marine Ecosystem
m	meter
MBES	Multibeam echosounder
mi	mile
min	minute

PSO	Marine Mammal Observer
MMPA	(U.S.) Marine Mammal Protection Act
ms	millisecond
n.mi.	nautical mile
n.d.	no date
NECC	North Equatorial Countercurrent
NEPA	(U.S.) National Environmental Policy Act
NMFS	(U.S.) National Marine Fisheries Service
NMSA	National Marine Sanctuary Act
NOAA	(U.S.) National Oceanic and Atmospheric Administration
NRC	(U.S.) National Research Council
NSF	(U.S.) National Science Foundation
NVD	Night Vision Device
PAM	Passive Acoustic Monitoring
PAMC	Protected Area Management Categories (IUCN)
PCC	Proyecto Cetacea-Cimar
pk	peak
PL	Propagation Loss
psi	pounds per square inch
PTS	Permanent Threshold Shift
RL	Received Level
R/V	Research Vessel
rms	root-mean-square
rpm	rotations per minute
s	second
SBP	Sub-Bottom Profiler
SE	southeast
SEL	Sound Exposure Level (a measure of acoustic energy)
SERDP	DoD Strategic Environmental Research and Development Program
SL	Source Level
SPL	sound pressure level
SOSUS	Sound Surveillance System
SWFSC	Southwest Fisheries Science Center
t	tonnes
TEU	twenty-foot equivalent unit
TTS	Temporary Threshold Shift
UNEP	United Nations Environment Program
U.S.	United States of America
USCG	United States Coast Guard
USFWS	U.S. Fish and Wildlife Service
USN	U.S. Navy
vs.	versus
WCMC	World Conservation Monitoring Centre

I. PURPOSE AND NEED

Lamont-Doherty Earth Observatory (L-DEO), a part of Columbia University, operates the oceanographic research vessel *Marcus G. Langseth* under a cooperative agreement with the U.S. National Science Foundation (NSF). L-DEO plans to conduct a seismic survey in the eastern tropical Pacific Ocean (ETP) off Costa Rica from ~7 April–9 May 2011. The marine seismic survey will take place within the Exclusive Economic Zone (EEZ) of Costa Rica.

NSF, as the funding and action agency, has a mission to “promote the progress of science; to advance the national health, prosperity, and welfare; to secure the national defense...”. The proposed seismic survey is part of a research proposal recommended for funding by an expert review panel. The proposed survey will provide data integral to advancing scientific understanding of the structure and geometry of a major thrust fault that is capable of generating very powerful earthquakes and tsunamis, the physical conditions along the fault and their down dip variability, and the structures overlying the fault.

The purpose of this Environmental Assessment (EA) is to provide the information needed to assess the potential environmental impacts associated with the use of 18-airgun subarrays during the proposed study. The EA was prepared under Executive Order 12114, “Environmental Effects Abroad of Major Federal Actions”. The EA addresses potential impacts of the proposed seismic survey on marine mammals, as well as other species of concern in and near the study area, including seabirds, sea turtles, fish, and invertebrates. The EA will also provide useful information in support of the application for an Incidental Harassment Authorization (IHA) from the National Marine Fisheries Service (NMFS). The requested IHA would, if issued, allow the non-intentional “take by harassment” of small numbers of marine mammals during the proposed seismic survey by L-DEO during April–May 2011.

To be eligible for an IHA under the U.S. Marine Mammal Protection Act (MMPA), the proposed “taking” (with mitigation measures in place) must not cause serious physical injury or death of marine mammals, must have negligible impacts on the species and stocks, must “take” no more than small numbers of those species or stocks, and must not have an unmitigable adverse impact on the availability of the species or stocks for legitimate subsistence uses.

Numerous species of cetaceans and pinnipeds inhabit the ETP. Several of these species are listed as *endangered* under the ESA, including the humpback, sei, fin, blue, and sperm whales. Other species of special concern that could occur in the study area are the *endangered* leatherback and hawksbill turtles, the *threatened* loggerhead, green, and olive ridley turtles, and the *endangered* California least tern.

Protection measures designed to mitigate the potential environmental impacts are also described in this EA as an integral part of the planned activities. With these mitigation measures in place, any impacts on marine mammals and sea turtles are expected to be limited to short-term, localized changes in behavior of small numbers of animals. No long-term or significant effects are expected on individual mammals, turtles, or their populations. The proposed project would also have little impact on fish resources, and the only effect on fish habitat would be short-term disturbance that could lead to temporary relocation of pelagic fish species or their food. Impacts of seismic sounds on some seabirds are possible, although none are expected to be significant to individual birds or their populations.

II. ALTERNATIVES INCLUDING PROPOSED ACTION

Three alternatives are evaluated: (1) the proposed seismic survey and issuance of an associated IHA, (2) a corresponding seismic survey at an alternative time, along with issuance of an associated IHA, and (3) no action alternative.

Proposed Action

The project objectives and context, activities, and mitigation measures for L-DEO's planned seismic survey are described in the following subsections.

(1) Project Objectives and Context

L-DEO plans to use 3D seismic reflection techniques to image the structures along a major plate-boundary fault off Costa Rica that has a history of generating large earthquakes and tsunamis. The 3D seismic reflection data will be used to determine the fault structure and the properties of the rocks that lie along the fault zone. These properties evolve with depth into the subduction zone and change the earthquake behavior of the fault. The main goal is to map the down dip variation in the properties to assess the property changes along the fault and determine where the large stress accumulations that lead to large earthquakes occur along the fault zone.

The target depths to the seismogenic zone are 2–9 km below the seafloor, which makes these earthquake generating zones very inaccessible; the only feasible means to assess the physical characteristics of deep fault zones where earthquakes are generated is by remote sensing using seismic techniques. This subduction zone setting is typical of numerous locations around the world, and the results of the proposed survey will have broad application. These are settings that generate the world's largest and most destructive earthquakes and tsunamis, and the study results will have broad implications for geohazards.

(2) Proposed Activities

(a) Location of the Activities

The survey will encompass the area 8.5–9°N, 83.75–84.25°W (Fig. 1). Water depths in the survey area range from <100 m to >2500 m. The seismic survey will be conducted in the EEZ of Costa Rica. The closest that the vessel will approach to the coast is ~30 km (Fig. 1).

(b) Description of the Activities

The procedures to be used for the survey will be similar to those used during previous seismic surveys by L-DEO and will use conventional seismic methodology. The survey will involve one source vessel, the R/V *Marcus G. Langseth*. The *Langseth* will deploy a 36-airgun array as an energy source. Two identical two-string subarrays will be firing alternately, so that no more than 18 airguns will be firing at any time. The maximum discharge volume will be 3300 in³. The receiving system will consist of four 6-km long hydrophone streamers. As the airgun array is towed along the survey lines, the hydrophone streamer will receive the returning acoustic signals and transfer the data to the on-board processing system. Two or three small fishing vessels will be in the water in front of and behind the *Langseth* to ensure that other vessels do not entangle the streamers.

The survey is a multichannel seismic (MCS) reflection survey in a 3D configuration. The survey will consist of a racetrack configuration with a total of 19 loops that will cover an area of ~57 x 12 km (Fig. 1). The lines will be spaced 300 m apart. The planned seismic survey will consist of ~2145 km of transect lines, with an additional 365 km of turns. The array will be powered down to one 40-in³ airgun during turns. There will be additional operations associated with equipment testing, startup, line changes, and repeat coverage of any areas where initial data quality is sub-standard. In our calculations (see § IV(3)), 25% has been added for those additional operations. If the planned contingency time is not used up, an additional 12 lines 300 m apart will be surveyed to the southeast side of the original survey area. These contingency lines will consist of ~675 km of transect lines, with an additional 30 km of turns.

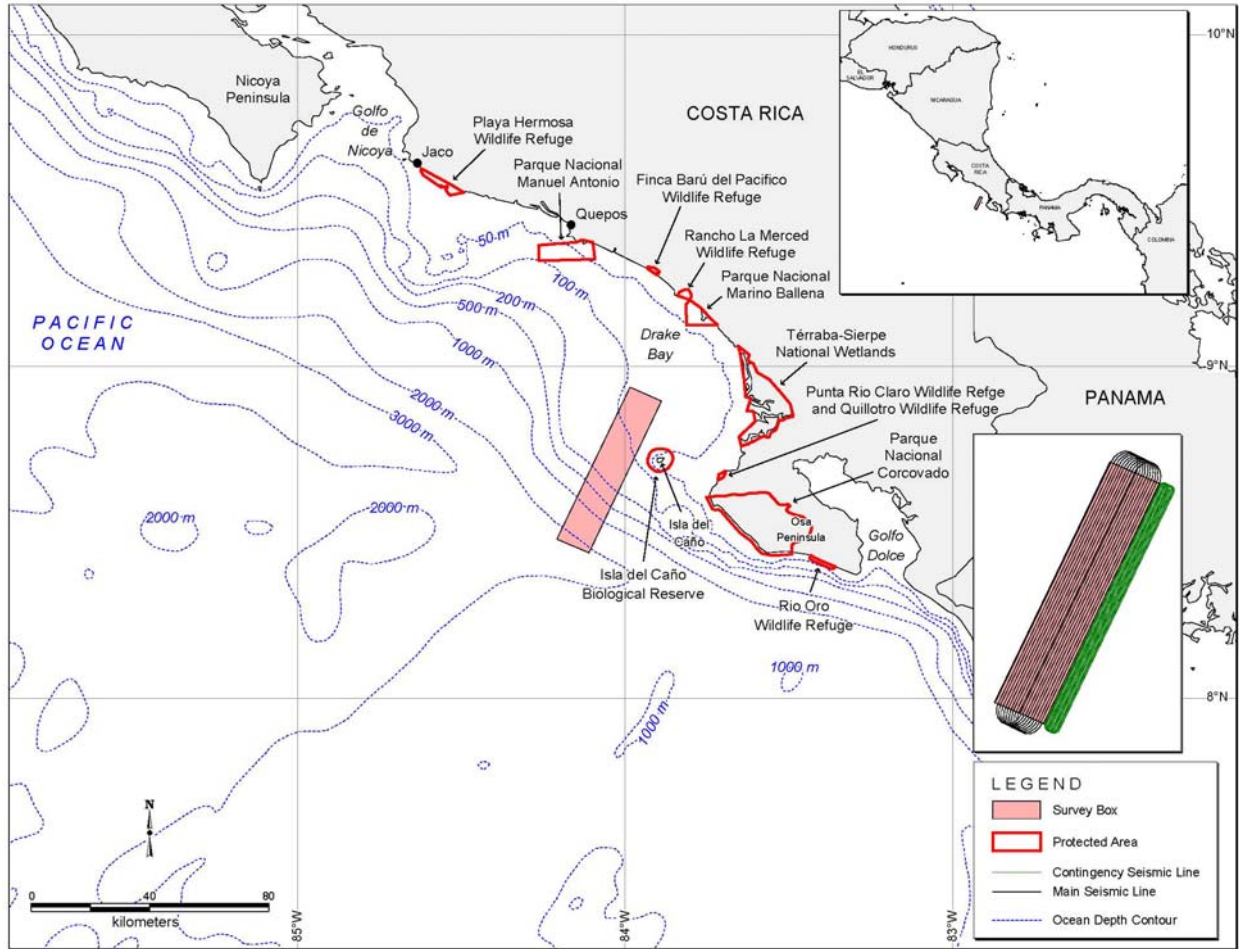


FIGURE 1. Study area, protected areas near the survey area, and proposed seismic transect lines for the L-DEO survey planned for April–May 2011 in the ETP off Costa Rica.

Survey effort including turns and contingency will be 835, 1360, and 1020 km in water depths >1000 m, 100–1000 m, and <100 m, respectively, for a total of 3215 km.

In addition to the operations of the airgun array, a multibeam echosounder (MBES) and a sub-bottom profiler (SBP) will also be operated from the *Langseth* continuously throughout the cruise. All planned geophysical data acquisition activities will be conducted by L-DEO with on-board assistance by the scientists who have proposed the study. The Principal Investigators are Drs. Nathan Bangs and Kirk McIntosh (Institute for Geophysics, University of Texas) and Dr. Eli Silver (University of California at Santa Cruz). The vessel will be self-contained, and the crew will live aboard the vessel for the entire cruise. As noted above, small vessels will accompany the *Langseth* to protect the streamers.

(c) Schedule

The *Langseth* will depart from Puerto Caldera on 7 April and return there on 9 May 2011. Seismic operations will be carried out for an estimated 25–26 (maximum 28) days. Some minor deviation from these dates is possible, depending on logistics and weather.

(d) Source Vessel Specifications

The R/V *Marcus G. Langseth* will be used as the source vessel. The *Langseth* will tow the airgun array and four streamers along predetermined lines (Fig. 1). When the *Langseth* is towing the airgun

array and the hydrophone streamers, the turning rate of the vessel is limited to five degrees per minute. Thus, the maneuverability of the vessel is limited during operations with the streamers.

The *Langseth* has a length of 71.5 m, a beam of 17.0 m, and a maximum draft of 5.9 m. The *Langseth* was designed as a seismic research vessel, with a propulsion system designed to be as quiet as possible to avoid interference with the seismic signals. The ship is powered by two Bergen BRG-6 diesel engines, each producing 3550 hp, which drive the two propellers directly. Each propeller has four blades, and the shaft typically rotates at 750 revolutions per minute (rpm). The vessel also has an 800 hp bow-thruster, which is not used during seismic acquisition. The operation speed during seismic acquisition will be ~8.5 km/h. When not towing seismic survey gear, the *Langseth* can cruise at 20–24 km/h. The *Langseth* has a range of 25,000 km.

The *Langseth* will also serve as the platform from which vessel-based protected species observers (PSOs) will watch for animals before and during airgun operations, as described in § II(3), below.

Other details of the *Langseth* include the following:

Owner:	National Science Foundation
Operator:	Lamont-Doherty Earth Observatory of Columbia University
Flag:	United States of America
Date Built:	1991 (Refitted in 2006)
Gross Tonnage:	3834
Accommodation Capacity:	55 including ~35 scientists

(e) Airgun Description

During the survey, the airgun array to be used will consist of two subarrays of 18 airguns, each with a total volume of ~3300 in³. The airgun array will consist of a mixture of Bolt 1500LL and Bolt 1900LLX airguns. The airguns in each subarray will be configured as two identical linear arrays or “strings” (Fig. 2). Each string will have ten airguns; the first and last airguns in the strings are spaced 16 m apart. Nine airguns in each string will be fired simultaneously, whereas the tenth is kept in reserve as a spare, to be turned on in case of failure of another airgun. The subarrays will be fired alternately during the survey. Each of the two subarrays will be towed ~140 m behind the vessel and will be distributed across an area of ~12×16 m behind the *Langseth*, offset by 75 m. The shot interval will be 25 m during the study. The firing pressure of the subarrays is 1900 psi. During firing, a brief (~0.1 s) pulse of sound is emitted. The airguns will be silent during the intervening periods.

The tow depth of the array will be ~7 m. Because the actual source is a distributed sound source (18 airguns) rather than a single point source, the highest sound levels measurable at any location in the water will be less than the nominal source level. In addition, the effective source level for sound propagating in near-horizontal directions will be substantially lower than the nominal source level applicable to downward propagation because of the directional nature of the sound from the airgun array.

18-Airgun Array (2 Strings) Specifications

Energy Source	Eighteen 2000 psi Bolt airguns of 40–360 in ³
Source output (downward)	0-pk is 42 bar-m (252 dB re 1 μPa·m); pk-pk is 87 bar-m (259 dB)
Towing depth of energy source	~7 m
Air discharge volume	~3300 in ³
Dominant frequency components	0–188 Hz

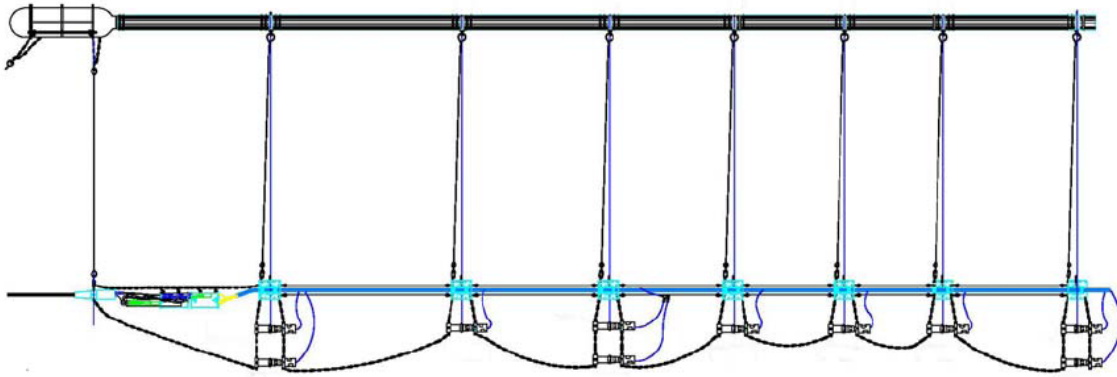


FIGURE 2. One linear airgun array or string with ten airguns, nine of which would be operating.

(f) Multibeam Echosounder and Sub-bottom Profiler

Along with the airgun operations, two additional acoustical data acquisition systems will be operated during the survey. The ocean floor will be mapped with the Kongsberg EM 122 MBES and a Knudsen 320B SBP. These sound sources will be operated from the *Langseth* continuously throughout the cruise.

The Kongsberg EM 122 MBES operates at 10.5–13 (usually 12) kHz and is hull-mounted on the *Langseth*. The transmitting beamwidth is 1 or 2° fore–aft and 150° athwartship. The maximum source level is 242 dB re 1 $\mu\text{Pa} \cdot \text{m}_{\text{rms}}$. Each “ping” consists of eight (in water >1000 m deep) or four (<1000 m) successive fan-shaped transmissions, each ensonifying a sector that extends 1° fore–aft. Continuous-wave (CW) pulses increase from 2 to 15 ms long in water depths up to 2600 m, and frequency-modulated (FM) chirp pulses up to 100 ms long are used in water >2600 m. The successive transmissions span an overall cross-track angular extent of about 150°, with 2-ms gaps between the pulses for successive sectors.

The Knudsen 320B SBP is normally operated to provide information about the sedimentary features and the bottom topography that is being mapped simultaneously by the MBES. The energy from the SBP is directed downward by a 3.5-kHz transducer in the hull of the *Langseth*. The maximum output is 1000 watts (204 dB), but in practice, the output varies with water depth. The pulse interval is 1 s, but a common mode of operation is to broadcast five pulses at 1-s intervals followed by a 5-s pause.

Langseth Sub-bottom Profiler Specifications

Maximum source output (downward)	204 dB re 1 $\mu\text{Pa} \cdot \text{m}$; 800 watts
Dominant frequency components	3.5 kHz
Bandwidth	1.0 kHz with pulse duration 4 ms 0.5 kHz with pulse duration 2 ms 0.25 kHz with pulse duration 1 ms
Nominal beam width	30 degrees
Pulse duration	1, 2, or 4 ms

(3) Monitoring and Mitigation Measures

Numerous species of marine mammals are known to occur in the proposed study area. However, the number of individual animals expected to be approached closely during the proposed activities will be relatively small in relation to regional population sizes. With the proposed monitoring and mitigation provisions, effects on most if not all individuals are expected to be limited to minor behavioral disturbance. Those effects are expected to have negligible impacts both on individual marine mammals and on the associated species and stocks.

To minimize the likelihood that impacts will occur to the species and stocks, airgun operations will be conducted in accordance with all applicable U.S. federal regulations and IHA requirements.

The following subsections provide more detailed information about the monitoring and mitigation measures that are an integral part of the planned activities. The procedures described here are based on protocols used during previous L-DEO seismic research cruises as approved by NMFS, and on best practices recommended in Richardson et al. (1995), Pierson et al. (1998), and Weir and Dolman (2007).

(a) Visual Monitoring

PSOs will watch for marine mammals and turtles near the seismic source vessel during all daytime airgun operations and during any start ups of the airguns at night. Airgun operations will be suspended when marine mammals or turtles are observed within, or about to enter, designated exclusion zones [see subsection (d) below] where there is concern about effects on hearing or other physical effects. PSOs will also watch for marine mammals and turtles near the seismic vessel for at least 30 min prior to the planned start of airgun operations after an extended shut down of the airguns. When feasible, observations will also be made during daytime periods when the *Langseth* is underway without seismic operations, such as during transits.

During seismic operations, at least three visual observers will be based aboard the *Langseth*. PSOs will be appointed by L-DEO with NMFS concurrence. At least one PSO, and when practical two PSOs, will monitor marine mammals and turtles near the seismic vessel during ongoing daytime operations and nighttime start ups of the airguns. Use of two simultaneous observers will increase the effectiveness of detecting animals near the source vessel. PSO(s) will be on duty in shifts of duration no longer than 4 h. Other crew will also be instructed to assist in detecting marine mammals and turtles and implementing mitigation requirements. Before the start of the seismic survey the crew will be given additional instruction regarding how to do so.

The *Langseth* is a suitable platform for marine mammal and turtle observations. When stationed on the observation platform, the eye level will be ~21.5 m above sea level, and the observer will have a good view around the entire vessel. During daytime, the PSO(s) will scan the area around the vessel systematically with reticle binoculars (e.g., 7×50 Fujinon), Big-eye binoculars (25×150), and with the naked eye. During darkness, night vision devices (NVDs) will be available (ITT F500 Series Generation 3 binocular-image intensifier or equivalent), when required. Laser rangefinding binoculars (Leica LRF 1200 laser rangefinder or equivalent) will be available to assist with distance estimation. Those are useful in training observers to estimate distances visually, but are generally not useful in measuring distances to animals directly; that is done primarily with the reticles in the binoculars.

When mammals or turtles are detected within or about to enter the designated exclusion zone, the airguns will immediately be powered down or shut down if necessary. The PSO(s) will continue to maintain watch to determine when the animal(s) are outside the exclusion zone. Airgun operations will not resume until the animal has left the exclusion zone.

The vessel-based monitoring will provide data to estimate the numbers of marine mammals exposed to various received sound levels, to document any apparent disturbance reactions or lack thereof, and thus to estimate the numbers of mammals potentially “taken” by harassment. It will also provide the information needed in order to power down or shut down the airguns at times when mammals or turtles are present in or near the exclusion zone. When a sighting is made, the following information about the sighting will be recorded:

1. Species, group size, age/size/sex categories (if determinable), behavior when first sighted and after initial sighting, heading (if consistent), bearing and distance from seismic vessel, sighting

cue, apparent reaction to the airguns or vessel (e.g., none, avoidance, approach, paralleling, etc.), and behavioral pace.

2. Time, location, heading, speed, activity of the vessel, sea state, visibility, and sun glare.

The data listed under (2) will also be recorded at the start and end of each observation watch, and during a watch whenever there is a change in one or more of the variables.

All observations and power downs or shut downs will be recorded in a standardized format. Data will be entered into an electronic database. The accuracy of the data entry will be verified by computerized data validity checks as the data are entered and by subsequent manual checking of the database. These procedures will allow initial summaries of data to be prepared during and shortly after the field program, and will facilitate transfer of the data to statistical, graphical, and other programs for further processing and archiving.

Results from the vessel-based observations will provide

1. The basis for real-time mitigation (airgun power down or shut down).
2. Information needed to estimate the number of marine mammals potentially taken by harassment, which must be reported to NMFS.
3. Data on the occurrence, distribution, and activities of marine mammals and turtles in the area where the seismic study is conducted.
4. Information to compare the distance and distribution of marine mammals and turtles relative to the source vessel at times with and without seismic activity.
5. Data on the behavior and movement patterns of marine mammals and turtles seen at times with and without seismic activity.

(b) Passive Acoustic Monitoring

Passive acoustic monitoring (PAM) will take place to complement the visual monitoring program. Visual monitoring typically is not effective during periods of poor visibility or at night, and even with good visibility, is unable to detect marine mammals when they are below the surface or beyond visual range. Acoustical monitoring can be used in addition to visual observations to improve detection, identification, and localization of cetaceans. The acoustic monitoring will serve to alert visual observers (if on duty) when vocalizing cetaceans are detected. It is only useful when marine mammals call, but it can be effective either by day or by night, and does not depend on good visibility. It will be monitored in real time so that the visual observers can be advised when cetaceans are detected.

The PAM system consists of hardware (i.e., hydrophones) and software. The “wet end” of the system consists of a towed hydrophone array that is connected to the vessel by a cable. The array will be deployed from a winch located on the back deck. A deck cable will connect from the winch to the main computer lab where the acoustic station and signal conditioning and processing system will be located. The lead-in from the hydrophone array is ~400 m long, and the active part of the hydrophone array is ~56 m long. The hydrophone array is typically towed at depths <20 m.

The towed hydrophones will ideally be monitored 24 h per day while at the seismic survey area during airgun operations, and during most periods when the *Langseth* is underway while the airguns are not operating. However, PAM may not be possible if damage occurs to the array during operations. One PSO will monitor the acoustic detection system at any one time, by listening to the signals from two channels via headphones and/or speakers and watching the real-time spectrographic display for frequency ranges produced by cetaceans. PSOs monitoring the acoustical data will be on shift for 1–6 h at a time. Besides the visual PSOs, an additional PSO with primary responsibility for PAM will also be aboard. All

PSOs are expected to rotate through the PAM position, although the most experienced with acoustics will be on PAM duty more frequently.

When a vocalization is detected while visual observations are in progress, the acoustic PSO will contact the visual PSO immediately, to alert him/her to the presence of cetaceans (if they have not already been seen), and to allow a power down or shut down to be initiated, if required. The information regarding the call will be entered into a database. The data to be entered include an acoustic encounter identification number, whether it was linked with a visual sighting, date, time when first and last heard and whenever any additional information was recorded, position and water depth when first detected, species or species group (e.g., unidentified dolphin, sperm whale), types and nature of sounds heard (e.g., clicks, continuous, sporadic, whistles, creaks, burst pulses, strength of signal, etc.), and any other notable information. The acoustic detection can also be recorded for further analysis.

(c) Reporting

A report will be submitted to NMFS and NSF within 90 days after the end of the cruise. The report will describe the operations that were conducted and sightings of marine mammals and turtles near the operations. The report will provide full documentation of methods, results, and interpretation pertaining to all monitoring. The 90-day report will summarize the dates and locations of seismic operations, and all marine mammal and turtle sightings (dates, times, locations, activities, associated seismic survey activities). The report will also include estimates of the number and nature of exposures that could result in “takes” of marine mammals by harassment or in other ways.

(d) Proposed Exclusion Zones

Acoustic Measurement Units.— Received sound levels have been predicted by L-DEO in relation to distance and direction from the airguns for the 36-airgun array with 18 airguns firing (Fig. 3) and for a single 1900LL 40 in³ airgun, which will be used during power downs (Fig. 4). The maximum relevant depth (2000 m) applicable to marine mammals was used for predicting exclusion zones (see below). A detailed description of the modeling effort is provided in Appendix A.

The predicted sound contours are shown as sound exposure levels (SEL) in decibels (dB) re 1 $\mu\text{Pa}^2 \cdot \text{s}$. SEL is a measure of the received energy in the pulse and represents the sound pressure level (SPL) that would be measured if the pulse energy were spread evenly across a 1-s period. Because actual seismic pulses are less than 1 s in duration in most situations, this means that the SEL value for a given pulse is usually lower than the SPL calculated for the actual duration of the pulse (see Appendix B). The advantage of working with SEL is that the SEL measure accounts for the total received energy in the pulse, and biological effects of pulsed sounds are believed to depend mainly on pulse energy (Southall et al. 2007). In contrast, SPL for a given pulse depends greatly on pulse duration. A pulse with a given SEL can be long or short depending on the extent to which propagation effects have “stretched” the pulse duration. The SPL will be low if the duration is long and higher if the duration is short, even though the pulse energy (and presumably the biological effects) are the same.

Although SEL is now believed to be a better measure than SPL when dealing with biological effects of pulsed sound, SPL is the measure that has been most commonly used in studies of marine mammal reactions to airgun sounds and in NMFS guidelines concerning levels above which “taking” might occur. SPL is often referred to as rms or “root mean square” pressure, averaged over the pulse duration. As noted above, the rms received levels that are used as impact criteria for marine mammals are not directly comparable to pulse energy (SEL). At the distances where rms levels are 160–190 dB re 1 μPa , the difference between the SEL and SPL values for the same pulse measured at the same location usually average ~10–15 dB, depending on the propagation characteristics of the location (Greene 1997; McCauley et al. 1998, 2000a; Appendix B). In this EA, we assume that rms pressure levels of received seismic pulses

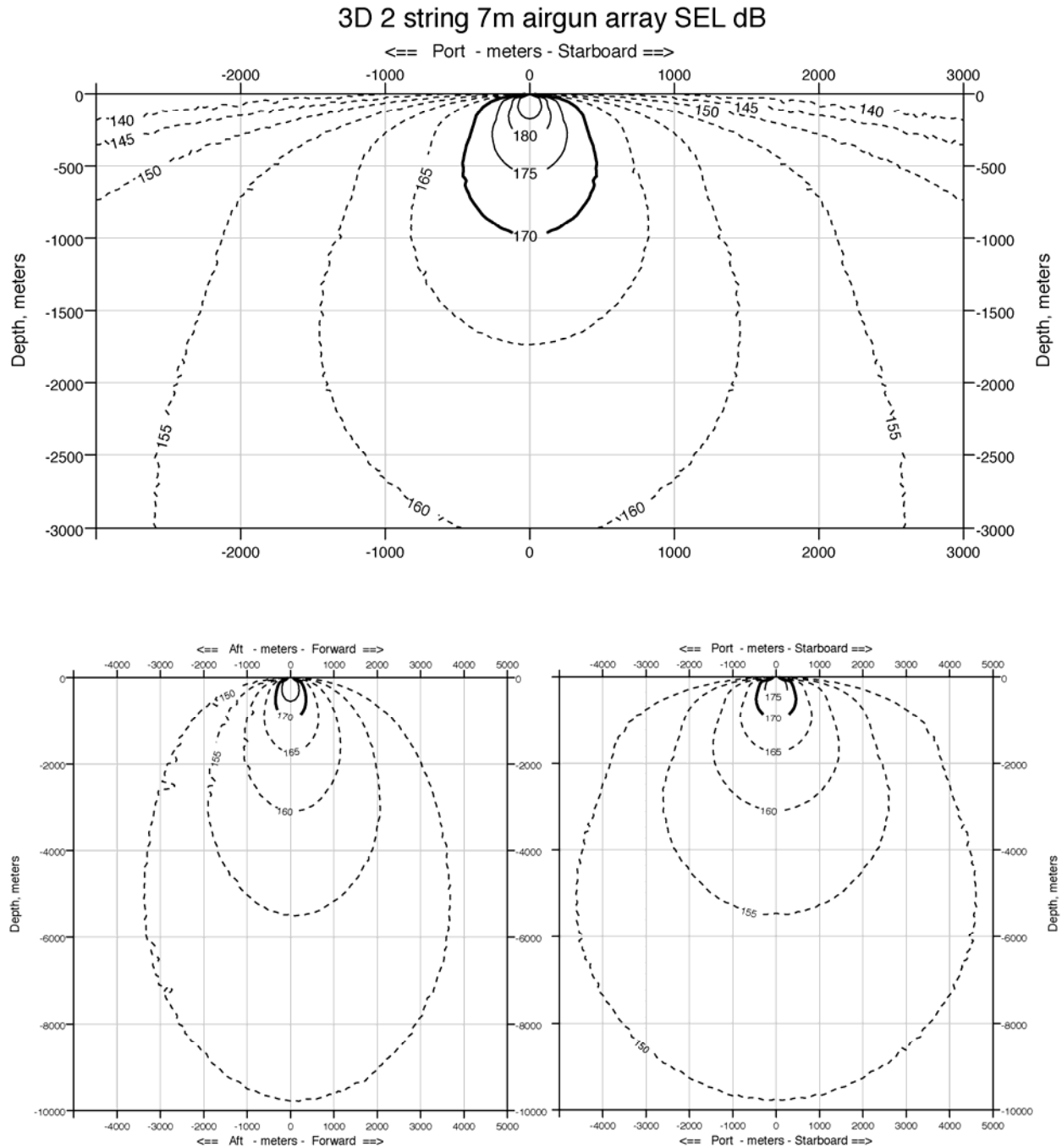


FIGURE 3. Modeled received sound levels (SELs) from the 18-airgun subarray planned for use during the survey in the ETP during 2011, at a 7-m tow depth. Received rms levels (SPLs) are expected to be ~10 dB higher.

will be 10 dB higher than the SEL values predicted by L-DEO’s model. Thus, we assume that 170 dB SEL \approx 180 dB re $1 \mu\text{Pa}_{\text{rms}}$. It should be noted that neither the SEL nor the SPL (=rms) measure is directly comparable to the peak or peak-to-peak pressure levels normally used by geophysicists to characterize source levels of airguns. Peak and peak-to-peak pressure levels for airgun pulses are always higher than the rms dB referred to in much of the biological literature (Greene 1997; McCauley et al. 1998, 2000a). For example, a measured received level of 160 dB re $1 \mu\text{Pa}_{\text{rms}}$ in the far field typically would correspond to a

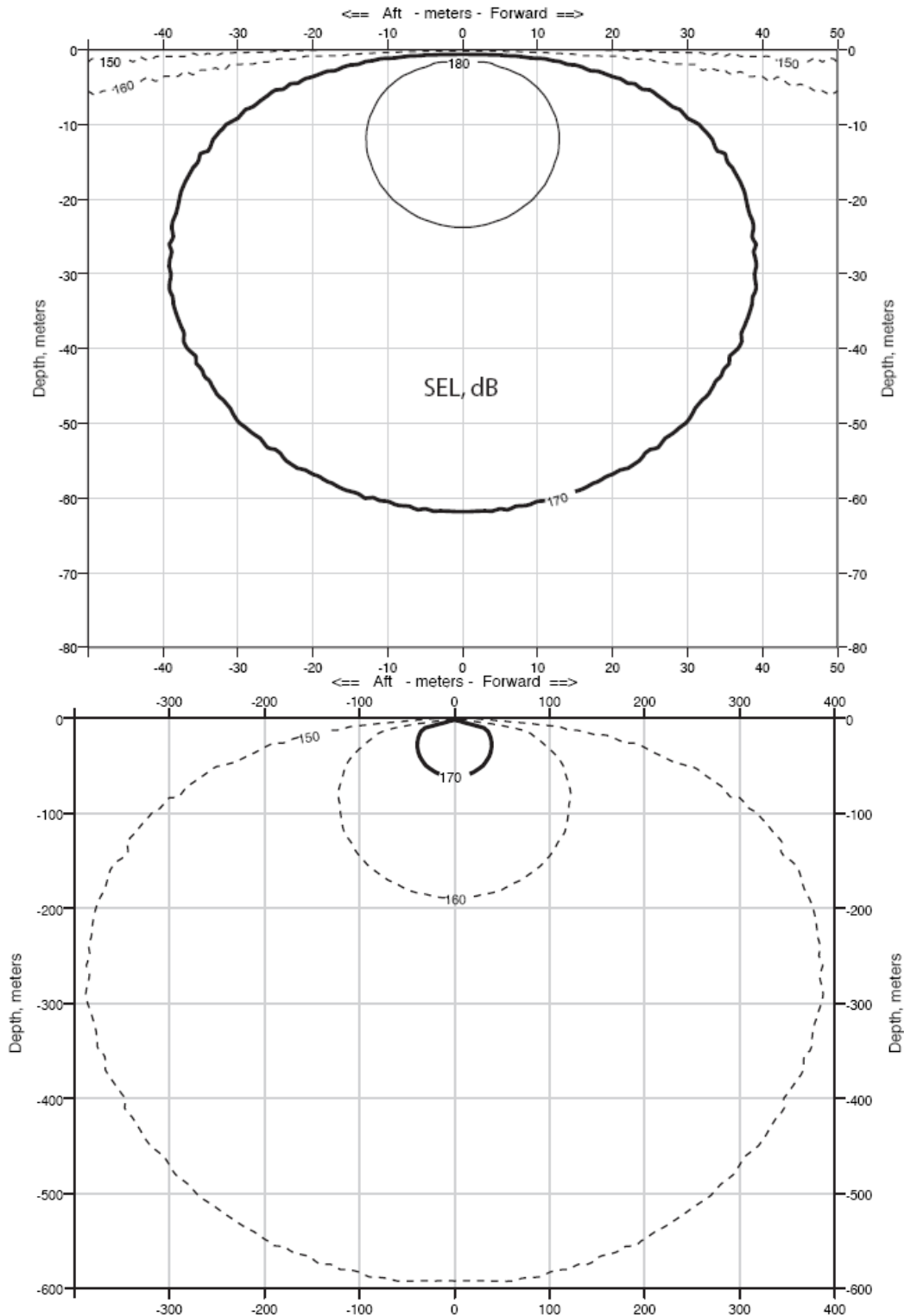


FIGURE 4 Modeled received sound levels (SELs) from a single 40-in³ airgun operating in deep water, which is planned for use as a mitigation gun during the proposed survey during April–May 2011. Received rms levels (SPLs) are expected to be ~10 dB higher.

peak measurement of ~170–172 dB re 1 μPa , and to a peak-to-peak measurement of ~176–178 dB re 1 μPa , as measured for the same pulse received at the same location (Greene 1997; McCauley et al. 1998, 2000a). (The SEL value for the same pulse would normally be 145–150 dB re 1 $\mu\text{Pa}^2 \cdot \text{s}$). The precise difference between rms and peak or peak-to-peak values for a given pulse depends on the frequency content and duration of the pulse, among other factors. However, the rms level is always lower than the peak or peak-to-peak level and (for an airgun-type source at the ranges relevant here) higher than the SEL value.

Empirical data concerning propagation distances in deep (~1600 m) and shallow (~50 m) water were acquired for the 36-airgun, 6600-in³ array during the acoustic calibration study of the R/V *Marcus G. Langseth* in the Gulf of Mexico in 2007–2008 (Tolstoy et al. 2009). The results showed that radii around the array where the received levels were 190, 180, 170, and 160 dB re 1 $\mu\text{Pa}_{\text{rms}}$ varied with water depth. The L-DEO model does not allow for bottom interactions, and thus is most directly applicable to deep water and to relatively short ranges. During the proposed study, survey effort including contingency will be 835, 1360, and 1020 km in water depths >1000 m, 100–1000 m, and <100 m, respectively.

- The empirical data indicated that, for **deep water** (>1000 m), the L-DEO model (as applied to the *Langseth's* 36-airgun array) **overestimated** the measured received sound levels at a given distance (Tolstoy et al. 2009). However, to be conservative, the modeled distances shown in Figure 3 for the *Langseth's* 18-airgun subarray will be applied to deep-water areas during the proposed study (Table 1). As very few, if any, mammals are expected to occur below 2000 m, this depth was used as the maximum relevant depth.
- Empirical measurements for the *Langseth* indicated that in **shallow water** (<100 m), the L-DEO model **underestimates** actual levels. For the 36-airgun array, the distances measured in shallow-water to the 160–190 dB isopleths ranged from 1.7 to 5.2 \times higher than the distances in deep-water (Tolstoy et al. 2009). During the proposed cruise, the same factors will be applied to derive appropriate shallow-water radii from the modeled deep-water radii for the *Langseth's* 18-airgun subarray (Table 1).
- Empirical measurements of sounds from the *Langseth's* airgun array were not acquired for **intermediate depths** (100–1000 m). On the expectation that results will be intermediate between those from shallow and deep water, a correction factor of 1.5 \times will be applied to the estimates provided by the model for the 18-airgun subarray operating in deep-water situations to obtain estimates for intermediate-depth sites (Table 1).

Modeling conducted for a previous L-DEO survey off Costa Rica using site-specific data on sound velocity profiles in the water column and bottom composition at a depth of 65 m in Drake Bay (at the proposed survey area) and a depth of 340 m ~100 km north of there resulted in much smaller radii than those in Table 1 (288–2121 m and 295–4511 m, respectively). This suggests that the radii estimated in Table 1 for shallow and intermediate depth ranges are overestimates, and thus precautionary. Also, the estimated 160-dB distance for the 18-gun subarray in water depths <100 m (Table 1) is higher than the measured distance for the 36-gun array (17.5 km; Tolstoy et al. 2009), again suggesting that the estimates are precautionary.

Table 1 shows the distances at which four rms sound levels are expected to be received from the 18-airgun subarray and a single airgun. The 180- and 190-dB re 1 $\mu\text{Pa}_{\text{rms}}$ distances are the safety criteria as specified by NMFS (2000) and are applicable to cetaceans and pinnipeds, respectively. The 180-dB distance will also be used as the exclusion zone for sea turtles, as required by NMFS in most other recent seismic projects (e.g., Smultea et al. 2004; Holst et al. 2005a,b; Holst and Beland 2008; Holst and

TABLE 1. Predicted distances to which sound levels ≥ 190 , 180, 170, and 160 dB re $1 \mu\text{Pa}_{\text{rms}}$ could be received during the proposed survey during April–May 2011 using an 18-airgun, 3300-in³ subarray towed at a depth of 7 m. Radii are based on Figures 3 and 4, assuming that received levels on an RMS basis are, numerically, 10 dB higher than the SEL values shown in Figures 3 and 4.

Source and Volume	Water Depth	Predicted RMS Radii (m)			
		190 dB	180 dB	170 dB	160 dB
Single Bolt airgun (40 in ³)	>1000 m	12	40	120	385
	100–1000 m	18	60	180	578
	<100 m	150	296	500	1050
18-airgun subarray (3300 in ³)	>1000 m	140	450	1400	3800
	100–1000 m	210	675	2100	5700
	<100 m	235	1030	4550	19,500 ¹

¹ This is likely an overestimate, as the measured distance for the 36-gun array operating in shallow waters of the northern Gulf of Mexico was 17.5 km .

Smultea 2008). If marine mammals or turtles are detected within or about to enter the appropriate exclusion zone, the airguns will be powered down (or shut down if necessary) immediately.

Southall et al. (2007) made detailed recommendations for new science-based noise exposure criteria. L-DEO will be prepared to revise its procedures for estimating numbers of mammals “taken”, exclusion zones, etc., as may be required by any new guidelines that result. However, currently the procedures are based on best practices noted by Pierson et al. (1998) and Weir and Dolman (2007). As yet, NMFS has not specified a new procedure for determining exclusion zones.

(e) Mitigation During Operations

Mitigation measures that will be adopted during the survey include (1) power-down procedures, (2) shut-down procedures, and (3) ramp-up procedures.

Power-down Procedures.—A power down involves decreasing the number of airguns in use such that the radius of the 180-dB (or 190-dB) zone is decreased to the extent that marine mammals or turtles are no longer in or about to enter the exclusion zone. A power down of the airgun array will also occur when the vessel is turning from one seismic line to another. During a power down for mitigation, one airgun will be operated. The continued operation of one airgun is intended to alert marine mammals and turtles to the presence of the seismic vessel in the area. In contrast, a shut down occurs when all airgun activity is suspended.

If a marine mammal or turtle is detected outside the exclusion zone but is likely to enter the exclusion zone, the airguns will be powered down before the animal is within the exclusion zone. Likewise, if a mammal or turtle is already within the safety zone when first detected, the airguns will be powered down immediately. During a power down of the airgun array, the 40-in³ airgun will be operated. If a marine mammal or turtle is detected within or near the smaller exclusion zone around that single airgun (Table 1), it will be shut down (see next subsection).

Following a power down, airgun activity will not resume until the marine mammal or turtle has cleared the exclusion zone for the full array. The animal will be considered to have cleared the exclusion zone if

- it is visually observed to have left the exclusion zone, or
- it has not been seen within the zone for 15 min in the case of small odontocetes (or pinnipeds), or

- it has not been seen within the zone for 30 min in the case of mysticetes and large odontocetes, including sperm, pygmy sperm, dwarf sperm, and beaked whales, or
- the vessel has moved outside the exclusion zone for turtles, e.g., if a turtle is sighted close to the vessel and the ship speed is 8.5 km/h, it would take the vessel from ~3 min in deep water to ~7.5 min in shallow water to leave the turtle behind.

During airgun operations following a power down (or shut down) whose duration has exceeded the limits specified above, the airgun array will be ramped up gradually. Ramp-up procedures are described below.

Shut-down Procedures.—The operating airgun(s) will be shut down if a marine mammal or turtle is seen within or approaching the exclusion zone for the single airgun. Shut downs will be implemented (1) if an animal enters the exclusion zone of the single airgun after a power down has been initiated, or (2) if an animal is initially seen within the exclusion zone of the single airgun when more than one airgun (typically the full array) is operating. Airgun activity will not resume until the marine mammal or turtle has cleared the safety zone, or until the PSO is confident that the animal has left the vicinity of the vessel. Criteria for judging that the animal has cleared the safety zone will be as described in the preceding subsection.

Ramp-up Procedures.—A ramp-up procedure will be followed when the airgun array begins operating after a specified period without airgun operations or when a power down has exceeded that period. It is proposed that, for the present cruise, this period would be ~3 min. This period is based on the deep-water 180-dB radius for the 18-airgun subarray (450 m) in relation to the planned speed of the *Langseth* while shooting (8.5 km/h). Similar periods were used during previous L-DEO surveys.

Ramp up will begin with the smallest airgun in the array (40 in³). Airguns will be added in a sequence such that the source level of the array will increase in steps not exceeding 6 dB per 5-min period over a total duration of ~30 min. During ramp up, the PSOs will monitor the exclusion zone, and if marine mammals or turtles are sighted, a power down or shut down will be implemented as though the full array were operational.

If the complete exclusion zone has not been visible for at least 30 min prior to the start of operations in either daylight or nighttime, ramp up will not commence unless at least one airgun (40 in³ or similar) has been operating during the interruption of seismic survey operations. Given these provisions, it is likely that the airgun array will not be ramped up from a complete shut down at night or in thick fog, because the outer part of the safety zone for that array will not be visible during those conditions. If one airgun has operated during a power-down period, ramp up to full power will be permissible at night or in poor visibility, on the assumption that marine mammals and turtles will be alerted to the approaching seismic vessel by the sounds from the single airgun and could move away if they choose. Ramp up of the airguns will not be initiated if a sea turtle or marine mammal is sighted within or near the applicable exclusion zones during the day or at night.

Alternative Action: Another Time

An alternative to issuing the IHA for the period requested and to conducting the project then is to issue the IHA for another time and to conduct the project at that alternative time. The proposed time for the cruise (April–May 2011) is the most suitable time logistically for the *Langseth* and the participating scientists. If the IHA is issued for another period, it could result in significant delay and disruption not only of the proposed cruise, but of subsequent geophysical studies that are planned by L-DEO for 2011 and beyond. An evaluation of the effects of this alternative action is given in § IV.

No Action Alternative

An alternative to conducting the proposed activities is the "No Action" alternative, i.e., do not issue an IHA and do not conduct the research operations. If the research is not conducted, the "No Action" alternative would result in no disturbance to marine mammals attributable to the proposed activities.

The proposed survey will provide data integral to advancing scientific understanding of the structure and geometry of a major thrust fault that is capable of generating very powerful earthquakes and tsunamis, the physical conditions along the fault and their down dip variability, and the structures overlying the fault. Under the "No Action" alternative, this valuable scientific information would not become available.

In addition to forcing cancellation of the planned seismic survey, the "No Action" alternative could also, in some circumstances, result in significant delay of other geophysical studies that are planned by L-DEO for 2011 and beyond, depending on the timing of the decision. The entire proposal, based on the premise of collecting these data, would be compromised. Cancellation (no action) for this cruise would decrease available data and support for the academic institutions involved. Data collection is an essential first step for a much greater effort to analyze and report information concerning the scientifically significant topics indicated. The field effort will provide material for years of analyses involving multiple professors, students, and technicians. The lost opportunity to collect valuable scientific information would be compounded by lost opportunities for support of research infrastructure, training, and professional career growth.

III. AFFECTED ENVIRONMENT

Oceanography

The proposed survey area lies within the Central American Coastal Province of the Pacific Coastal Biome (Longhurst 2007) and the Pacific Central American Coastal Large Marine Ecosystem (LME; Heileman 2008). The coast is an active continental margin, so the continental shelf is narrow. For example, the 4000-m depth contour lies only 75–150 km from the coast.

The survey area lies between the westward-flowing South and North Equatorial currents, which are fed by the Peru and California currents, respectively. Between the equatorial currents at 3–10°N is the eastward-flowing North Equatorial Countercurrent (NECC), part of which turns north and becomes the Costa Rica Current when it reaches Central America, and flows along the coast until it turns west off the coast of Mexico and joins the North Equatorial Current. Longshore currents in the survey area are variable, although generally dominated by the reflux of the NECC (Longhurst 2007). The pattern of cyclonic flow exists only in summer–fall, when it flows around the Costa Rica Dome (CRD). The NECC does not extend east of 100°W during February–April (Fiedler 2002).

The CRD is a shoaling of the generally strong and shallow thermocline of the ETP. The mean position of the CRD is near 9°N, 90°W; it is 300–500 km in diameter and centered 300 km off the coast between Nicaragua and Costa Rica (Balance et al. 2006). The ridge and the CRD extend below the thermocline, to a depth >300 m. Increased biological productivity has been observed at the CRD and attributed to upwelling (Wyrski 1964; Fiedler et al. 1991; Rodríguez-Fonseca 2001; Fiedler 2002). This is the largest concentration of plankton known in the tropical Pacific Ocean and is highly important for the dynamics of the food resources in the region (Wyrski 1964, 1967; Wade and Friedrichsen 1979; Fiedler et al. 1991). Several studies have correlated zones of high productivity with concentrations of cetaceans (Volkov and Moroz 1977; Reilly and Thayer 1990; Wade and Gerrodette 1993; Balance et al. 2006).

This LME is considered a Class I, high (>300 gC/m²/yr) productivity ecosystem (Heileman 2008), with a mean productivity of 668 mgC/m²/day in the coastal region (Sea Around Us Project 2010a). Interannual variation in the oceanography of the ETP is greater than in any other area of the world because of the quasi-periodic El Niño–Southern Oscillation (Fiedler and Talley 2006). Interannual variation usually exceeds any seasonal variation in the equatorial and upwelling zones, but is comparable to seasonal variations to the north of the Intertropical Convergence Zone (Fiedler and Talley 2006; Pennington et al. 2006).

Protected Areas

The Osa Conservation Area (ACOSA) and the Central Pacific Conservation Area (ACOPAC) are two of 11 areas of Costa Rica designated as conservation areas by the National System of Conservation Areas, part of The Ministry of the Environment and Energy. The ACOSA and the ACOPAC cover large area of the central and southern Pacific Coast of Costa Rica. There are three National Parks, several wildlife refuges, and protected zones that include sea turtle nesting beaches, many of which are monitored and have conservation programs. These protected areas are described below. None of these protected areas occurs in the survey area, and the *Langseth* will not enter any protected area.

Playa Hermosa Wildlife Refuge protects a nesting beach of the olive ridley turtle and is located ~100 km north of the proposed survey area. It was established in 1999 and covers an area of 3698 ha of beach and 3654 ha of marine water (CCSA 2005; Triana 2009).

Parque Nacional Manuel Antonio is located ~50 km north of the proposed survey area. It includes beaches, offshore islands (bird sanctuaries for marine species), and rainforest habitats. It was established in 1972. The terrestrial area covers 682 ha and the total marine area covers 42,016 ha. It is listed as Class II under the IUCN Protected Area Management Categories (PAMC) (Triana 2009; CRTTB 2010a).

Finca Barú del Pacífico Wildlife Refuge protects tropical forest areas on the Pacific Coast, near Dominical, Aguirre Costa Rica (~9° 15" N; 83° 52" W). It was established in 1995 and encompasses an area of 332 ha (CCSA 2009a). It is listed as Class IV under the IUCN PAMC (Triana 2009).

Parque Nacional Marino Ballena is located ~45 km north of Osa Peninsula. Created in 1992, the park covers an area of 346 ha of beach and coast and 5229 ha of marine waters out to ~9 km from shore (CCSA 2009b; Triana 2009). Snorkeling is popular in the area. The southernmost offshore boundary of the park includes Las Tres Hermanas and Isla Ballena (Costa Rica 2010), ~15 km east of the northern boundary of the proposed survey area. The islands are nesting grounds for frigate birds, white ibis, and brown pelicans. The park harbors important mangroves and the largest coral reef on the Pacific coast of Central America, green marine iguanas, and nesting olive ridley and hawksbill turtles (May–November) (Costa Rica 2010). Common, bottlenose, and spinner dolphins occur offshore (Hoyt 2005), and the bay is the southernmost mating site for the humpback whale (December–April). The area is also used by killer and sperm whales (Hoyt 2005). It is listed as Class II under the IUCN PAMC (Triana 2009).

Rancho La Merced Wildlife Refuge protects forested and beach areas near Parque Nacional Marino Ballena. It was established in 1995 and covers 508 terrestrial ha (CCSA 2009c). It is listed as Class IV under the IUCN PAMC (Triana 2009).

Térraba-Sierpe National Wetlands protects the extensive river mouth delta systems, estuaries, and wetlands between the Térraba River and the Sierpe River, ~30 km east of the proposed survey area. It was established in 1994 and covers 30,654 ha (CCSA 2009d). It has been recognized as an important site under the RAMSAR convention on Wetlands (Triana 2009).

Parque Nacional Corcovado is located on the upper two thirds of the Osa Peninsula. It encompasses 8 main habitats and 13 or more distinct vegetation habitats, from mangrove swamp and jolillo palm grove to mountain forest and cloud forest. The park protects 367 species of birds, 117 amphibians and reptile species, and 140 mammal species (CRTTB 2010b). Four sea turtle species—green, olive ridley, hawksbill, and leatherback—nest on its beaches. The park was created in 1975. The park covers an area of 44,513 terrestrial ha and 2044 marine ha (Triana 2009). The marine area encompasses a 500-m wide seaward extension from the coastline of the Park (CRTTB 2010b).

Punta Río Claro Wildlife Refuge and Quillotro Wildlife Refuge are on the northwest coast of the Osa Peninsula, 6.5 km north of Parque Nacional Corcovado. The two refuges cover an area of 324 terrestrial ha and 210 marine ha, protecting forested and beach areas (CCSA 2009e,f). The first is listed as Class IV under the IUCN PAMC (Triana 2009).

Río Oro Wildlife Refuge protects river mouth and beach areas on the southern Osa Peninsula and covers an area of ~40 ha (CCSA 2009g).

Isla del Caño Biological Reserve protects forested and beach areas on an island ~20 km off the Osa Peninsula, adjacent to the proposed survey area. It was established in 1976 and covers an area of 200 terrestrial ha and 5207 marine ha (Triana 2009). The island rises 110 m above sea level and is covered by virgin tropical wet forests. It is of interest primarily for its inshore coral reefs and its importance as a Pre-Colombian burial ground. Marine life is abundant in the general vicinity of the island. Olive ridley sea turtles are commonly observed in the surrounding waters, dolphins are encountered daily, and humpback whales are seasonally present (CRTG 2010). Scuba diving is popular around this island, and five dive sites are open to the public (CRTTB 2010c). The Reserve is listed as Class Ia under the IUCN PAMC (Triana 2009).

Marine Mammals

Twenty-eight species of marine mammals, including 20 odontocetes, 6 mysticetes, and 2 pinnipeds are known to occur in Costa Rican Pacific waters (May-Collado 2009). Five of the 26 cetacean species are listed under the Endangered Species Act (ESA) as **Endangered**: the sperm, humpback, blue, fin, and sei whales. Two pinniped species could potentially occur in the proposed survey area on rare occasions (Table 2). These include the California and Galápagos sea lions, which have been documented off western Costa Rica (Acevedo-Gutierrez 1994; Cubero-Parado and Rodríguez 2000; Rodríguez-Herrera et al. 2002; May-Collado 2008).

Information on the occurrence, distribution, population size, and conservation status for each of the 26 cetacean species and 2 pinniped species that may occur in the proposed survey area is presented in Table 2. The status of these species is based on the U.S. ESA, the IUCN Red List, the Convention on International Trade in Endangered Species (CITES), and NatureServe (an international network of biological inventories that provides conservation status ranks for Latin America).

Several studies of marine mammal distribution and abundance have been conducted in the wider ETP. The most extensive regional distribution and abundance data that encompass the study area come primarily from multi-year vessel surveys conducted in the wider ETP between July and December by the NMFS Southwest Fisheries Science Center (SWFSC). Information on the distribution of cetaceans inhabiting the ETP has been summarized in several studies (e.g., Polacheck 1987; Wade and Gerrodette 1993; Ferguson and Barlow 2001; Gerrodette et al. 2008). However, for some species, abundance in the proposed seismic survey area could be quite different from that of the wider ETP, depending on local variation in oceanographic conditions and seasonal distribution. In addition, procedures used during the various surveys that are cited have differed somewhat, and those differences could affect the results.

TABLE 2. The habitat, regional abundance, and conservation status of marine mammals that could occur in or near the proposed seismic survey areas in the ETP.

Species	Occurrence in survey area during April–May	Habitat	Abundance in the ETP ¹	ESA ²	IUCN ³	CITES ⁴	Nature Serve ⁵
Mysticetes							
Humpback whale	Very rare	Mainly nearshore waters and banks	NE Pacific 1392 ⁶ , SE Pacific 2900 ⁷	EN	LC	I	G4
Common minke whale	Very rare	Coastal	N.A.	NL	LC	I	G5
Bryde's whale	Uncommon	Pelagic and coastal	13,000 ⁸	NL	DD	I	G4
Sei whale	Very rare	Mostly pelagic	N.A.	EN	EN	I	G3
Fin whale	Very rare	Slope, mostly pelagic	2636 ⁶	EN	EN	I	G3G4
Blue whale	Rare	Pelagic and coastal	1415 ⁹	EN	EN	I	G3G4
Odontocetes							
Sperm whale	Uncommon	Usually deep pelagic, steep topography	26,053 ¹⁰	EN	VU	I	G3G4
Pygmy sperm whale	Very rare	Deep waters off shelf	N.A. ¹¹	NL	DD	II	G4
Dwarf sperm whale	Rare	Deep waters off shelf	11,200 ¹²	NL	DD	II	G4
Cuvier's beaked whale	Uncommon	Slope and pelagic	20,000 ⁹	NL	LC	II	G4
Pygmy beaked whale	Very rare	Pelagic	25,300 ¹³	NL	DD	II	GNR
Ginkgo-toothed beaked whale	Very rare	Pelagic	25,300 ¹³	NL	DD	II	G3
Blainville's beaked whale	Rare	Pelagic	25,300 ¹³	NL	DD	II	G4
Rough-toothed dolphin	Common	Mainly pelagic	107,633	NL	LC	II	G4
Bottlenose dolphin	Very common	Coastal, shelf, pelagic	335,834	NL	LC	II	G5
Pantropical spotted dolphin	Very common	Coastal and pelagic	1,575,247 ¹⁴	NL	LC	II	G5
Spinner dolphin	Common	Coastal and pelagic	1,797,716 ¹⁴	NL	DD	II	G5
Striped dolphin	Uncommon	Off continental shelf	964,362	NL	LC	II	G5
Fraser's dolphin	Rare	Pelagic	289,300 ⁹	NL	LC	II	G4
Short-beaked common dolphin	Common	Shelf, pelagic, high relief	3,127,203	NL	LC	II	G5
Risso's dolphin	Common	Shelf, slope, seamounts	110,457	NL	LC	II	G5
Melon-headed whale	Rare	Pelagic	45,400 ⁹	NL	LC	II	G4
Pygmy killer whale	Rare	Pelagic	38,900 ⁹	NL	DD	II	G4
False killer whale	Uncommon	Pelagic	39,800 ⁹	NL	DD	II	G4
Killer whale	Rare	Widely distributed	8500 ¹⁵	NL	DD	II	G4G5
Short-finned pilot whale	Common	Mostly pelagic, high-relief	589,315 ¹⁶	NL	DD	II	G5
Pinnipeds							
California sea lion	Very rare	Coastal, shelf	238,000 ¹⁷	NL	LC	NL	G5
Galápagos sea lion	Very rare	Coastal	14,000-16,000 ¹⁸	NL	EN	NL	GNR

N.A. Not available or not assessed.

¹ Abundance from Gerrodette et al. (2008) unless otherwise stated.

² U.S. Endangered Species Act: EN = Endangered, T = Threatened, NL = Not listed

³ Codes for IUCN classifications: EN = Endangered; VU = Vulnerable; NT = Near Threatened; LC = Least Concern; DD = Data Deficient. Classifications are from the 2010 IUCN *Red List of Threatened Species* (IUCN 2010).

⁴ Convention on International Trade in Endangered Species of Wild Fauna and Flora (UNEP-WCMC 2010); NL = Not listed.

⁵ NatureServe Status (NatureServe 2009); GNR = unranked, G2 = Imperiled, G3 = Vulnerable, G4 = Apparently secure; G5 = Secure.

⁶ U.S. west coast (Carretta et al. 2010).

⁷ Southeast Pacific; Félix et al. (2005).

⁸ This estimate is mainly for *Balaenoptera edeni* but may include some *B. borealis* (Wade and Gerrodette 1993).

⁹ ETP (Wade and Gerrodette 1993).

¹⁰ Eastern temperate North Pacific (Whitehead 2002).

¹¹ California/Oregon/Washington (Carretta et al. 2010).

¹² This abundance estimate is mostly for *K. sima* but may also include some *K. breviceps* (Wade and Gerrodette 1993).

¹³ This estimate includes all species of the genus *Mesoplodon* in the ETP (Wade and Gerrodette 1993).

¹⁴ For all stocks in ETP.

¹⁵ ETP (Ford 2002).

¹⁶ This estimate is for *G. macrorhynchus* and *G. melas* in the ETP (Gerrodette and Forcada 2002).

¹⁷ U.S. stock (Carretta et al. 2010).

¹⁸ Galapagos Islands (Alava and Salazar 2006).

For example, Ferguson and Barlow (2001, 2003) calculated cetacean densities in the ETP based on summer/ fall research surveys in 1986–1996. Their densities are corrected for both changes in

detectability of species with distance from the survey track line [$f(0)$], and for perception and availability bias [$g(0)$]. Gerrodette et al. (2008) calculated dolphin abundance in the ETP based on summer/fall research surveys in 1986–1990, 1998–2000, 2003, and 2006. Their estimates are corrected for $f(0)$ but not $g(0)$.

Additional sighting records are available from recent surveys in the ETP. Jackson et al. (2008) described cetacean sightings data collected during a survey from 28 July to 7 December 2006. The survey area extended from 30°N to 18°S from the coastline to 153°W, overlapping with the proposed seismic survey area. Rasmussen et al. (2004), Rasmussen (2006), and Calambokidis et al. (2010) described cetacean sightings resulting from the Cascadia Research Collective (CRC) humpback whale surveys off Costa Rica (Drake Bay and Papagayo Bay, north of the Nicoya Peninsula) from January to March in 1996–2003 and 2010. May-Collado et al. (2005) summarized cetacean sightings in Costa Rican waters based on the SWFSC survey data (from 1979 to 2000), the CRC survey data (from 1996 to 2001), and Proyecto Cetacea-Cimar (PCC) monthly surveys north of the Nicoya Peninsula from 1998 to 2001. Recent at-sea monitoring for L-DEO in the ETP also provided sighting records for cetaceans during seismic programs. A seismic monitoring program took place from Costa Rica to El Salvador in November–December 2004, mainly within ~100 km of the coast in water depths extending to 5000 m. The seismic monitoring program occurred north of the Nicoya Peninsula, but transit to the area traversed the proposed survey area (Holst et al. 2005a). A second seismic monitoring program took place from Costa Rica to Nicaragua, including the proposed survey area, from 19 March–16 April 2008, up to ~200 km from the coast in water depths extending to 5000 m (Holst and Smultea 2008).

(1) Mysticetes

Humpback Whale (*Megaptera novaeangliae*)

The humpback whale is listed as *Endangered* under the U.S. ESA and *Least Concern* on the 2010 IUCN Red List of Threatened Species (IUCN 2010), and is listed in CITES Appendix I (UNEP-WCMC 2010). The worldwide population of humpback whales is divided into various northern and southern ocean populations (Mackintosh 1965). Geographical overlap of these populations has been documented only off Central America (Acevedo and Smultea 1995; Rasmussen et al. 2004, 2007; Rasmussen 2006). The humpback whale is one of the most abundant cetaceans off the Pacific coast of Costa Rica during the winter breeding season of northern hemisphere humpbacks. Humpbacks are also observed off the coast of Costa Rica during the winter breeding period for southern hemisphere humpbacks (e.g., Rasmussen et al. 2004; Rasmussen 2006). The estimate of abundance for the California/Oregon/Washington humpback whale stock is 1392 (Carretta et al. 2010), and the estimated abundance for the southeast Pacific stock is ~2900 (Félix et al. 2005)

Humpback whales occur worldwide, migrating from tropical breeding areas to polar or sub-polar feeding areas (Jefferson et al. 2008). Although the humpback whale is considered mainly a coastal species, it often traverses deep pelagic areas while migrating (Clapham and Mattila 1990; Norris et al. 1999; Calambokidis et al. 2001). Some males occur in waters >3000 m deep and up to 57 km from the coast in the Caribbean Sea (Swartz et al. 2003). Humpbacks were found primarily in water depths ≤ 50 m in the Pacific Ocean off southern Costa Rica during 1996–2004 surveys (Rasmussen et al. 2004).

Humpback whales are often sighted singly or in groups of two or three, but while on breeding and feeding grounds they may occur in groups of >20 (Leatherwood and Reeves 1983; Jefferson et al. 2008). Rasmussen (2006) reported a group size of 1.7 for coastal surveys conducted off the northwest side of the Osa Peninsula between 1996 and 2004. Based on NMFS vessel-based surveys in the ETP in July–December 2006, Jackson et al. (2008) reported a mean group size of 1.5 ($n = 11$). The diving behavior of humpback whales is related to time of year and whale activity (Clapham and Mead 1999). In summer

feeding areas, humpbacks typically forage in the upper 120 m of the water column, with a maximum recorded dive depth of 500 m (Dolphin 1987; Dietz et al. 2002). On winter breeding grounds, humpback dives have been recorded at depths >100 m (Baird et al. 2000).

Humpback whales are seasonally abundant in Costa Rica Pacific waters (May-Collado 2009). Northern hemisphere humpback whales are commonly observed from January to April, and southern hemisphere humpbacks are observed from July to October (Rasmussen 2006; May-Collado 2009). By spring, most of the northeast Pacific humpbacks have migrated north to summer feeding grounds off the coast of California (Steiger et al. 1991; Urbán et al. 2000; Rasmussen et al. 2004; May-Collado et al. 2005). By late fall, most of the southern hemisphere humpback whales in Costa Rica have migrated south to feeding grounds off the Antarctic Peninsula (Rasmussen 2006). However, humpback whale sightings in Costa Rica waters have been reported in all months of the year (T. Gerrodette, pers. comm. in Rasmussen 2006).

Rasmussen et al. (2004) reported 40 humpback whale sightings around the Osa Peninsula based on survey effort from January to mid March 2001–2003. Whales were most often found around the northwestern edge of the Peninsula. Calambokidis et al. (2010) recorded 56 humpback whale sightings during a two-week survey along the Osa Peninsula in January–February 2010. May-Collado et al. (2005) reported 186 sightings of 246 humpbacks in 1979–2001 off Costa Rica, primarily during January–March, all close to shore and concentrated in Drake Bay and the northern Osa Peninsula.

Two sightings of individual humpback whales were observed ~100 km northeast of the proposed survey area along the 50-m depth contour during an L-DEO seismic program off Costa Rica and Nicaragua in February–March 2008 (Holst and Smultea 2008).

Humpback whales are likely to be very rare in the proposed survey area at the time of the survey (mid April to mid May).

Minke Whale (*Balaenoptera acutorostrata*)

The minke whale inhabits all oceans of the world from the high latitudes to near the equator (Jefferson et al. 2008). In the Northern Hemisphere, minke whales are usually seen in coastal areas but can be seen in pelagic waters during northward migrations in spring and summer and southward migration in autumn (Stewart and Leatherwood 1985). There is no estimate of abundance available for the ETP.

Minke whales are relatively solitary, but may occur in aggregations of up to 100 where food resources are concentrated (Jefferson et al. 2008). Based on SWFSC vessel surveys from 1991 to 2005, Barlow and Forney (2007) reported a mean group size of 1.6 ($n = 4$) off southern California. No mean group size information is available for the ETP. Little is known about the diving behavior of minke whales, but they are not known to make prolonged deep dives (Leatherwood and Reeves 1983).

The general distribution of minke whales includes the offshore and coastal waters of the study area (e.g., Reeves et al. 2002), and the species has been found off the coast of Costa Rica on occasion (Rodríguez-Herrera et al. 2002). However, minke whales are likely to be rare in the survey area. Rasmussen et al. (2004) did not report any minke whale sightings in annual winter surveys (1996–2003) off Costa Rica. May-Collado et al. (2005) also did not report any minkes in Costa Rica waters based on surveys from 1979–2001, nor have minkes been reported among compiled strandings off Costa Rica (Rodríguez-Fonseca and Cubero-Pardo 2001).

Neither Jackson et al. (2004) nor Jackson et al. (2008) positively identified minke whales in or near the proposed survey area during surveys conducted during July–December. No minke whales were observed during L-DEO seismic surveys off Costa Rica or Nicaragua in November–December 2004 or

February–March 2008 (Holst et al. 2005a; Holst and Smultea 2008). Minke whales are unlikely to occur in the proposed survey area, thus no encounters are expected and no takes are requested.

Bryde's Whale (*Balaenoptera edeni/brydei*)

Bryde's whale occurs in tropical and subtropical waters, generally between 40°N and 40°S (Jefferson et al. 2008). Long confused with sei whales (*Balaenoptera borealis*), *B. edeni* was named in 1913 and *B. brydei* was named in 1950, although it is still uncertain whether the two are distinct species or subspecies. Here, we follow Kato (2002) in recognizing the uncertainty and using *B. edeni/brydei*.

Bryde's whale is common throughout the ETP, with a concentration near the equator east of 110°W, decreasing west of 140°W (Lee 1993; Wade and Gerrodette 1993). Wade and Gerrodette (1993) estimated Bryde's whale population size in the ETP at 13,000, based on data collected during 1986–1990. This species has also been sighted off Columbia and Ecuador (Gallardo et al. 1983), and may occur around the Galápagos Islands (Clarke and Aguayo 1965 in Gallardo et al. 1983). The International Whaling Commission (IWC) recognizes a cross-equatorial or Peruvian stock of Bryde's whale (Donovan 1991).

Bryde's whale is known to occur in both shallow coastal and deeper offshore waters (Jefferson et al. 2008). It does not undertake long migrations, although there is a general pattern of movement toward the equator in winter and toward higher latitudes in summer (Kato 2002). Bryde's whales are usually solitary or in pairs, although groups of 10–20 are known from feeding grounds (Jefferson et al. 2008). Romero et al. (2001) reported that 78% of all sightings off Venezuela were of single animals. Wade and Gerrodette (1993) reported a mean group size of 1.7 (n = 109) for the ETP. The durations of Bryde's whale dives are 1–20 min (Cummings 1985).

Based on the SWFSC surveys and model used to calculate densities in the project area in § IV(3), Bryde's whale is the most common mysticete in the survey area. Off Costa Rica, May-Collado et al. (2005) reported at least 16 and possibly up to 24 sightings of at least 32 (possibly up to 43) Bryde's whales in 1979–2001; these numbers are uncertain because it is now surmised that early reports of Bryde's/sei whales in this region were most likely Bryde's whales. Both Bryde's whale and Bryde's/sei whale sightings occurred from coastal to oceanic waters off Costa Rica. Rasmussen et al. (2004) reported one sighting of a Bryde's whale in January–March in annual surveys (1996–2003) off Costa Rica and from 2001 to 2003 off Panama. Jackson et al. (2008) did not encounter Bryde's whales near the project area during July–December 2006 surveys. One Bryde's whale stranding on the central Pacific coast at Playa Bandera was reported during 1966–1999 (Rodríguez-Fonseca and Cubero-Pardo 2001).

No Bryde's whales were sighted during L-DEO seismic surveys off Costa Rica or Nicaragua in November–December 2004 or February–March 2008 (Holst et al. 2005a; Holst and Smultea 2008).

Sei Whale (*Balaenoptera borealis*)

The sei whale is listed as *Endangered* under the U.S. ESA and on the 2010 IUCN Red List of Threatened Species (IUCN 2010), and is listed in CITES Appendix I (UNEP-WCMC 2010). Sei whale populations were depleted by whaling, and the current status is generally uncertain (Horwood 1987). The global population size is unknown but thought to be small.

The sei whale has a nearly cosmopolitan distribution, with a marked preference for temperate oceanic waters, and is rarely seen in coastal waters (Gambell 1985a). In the open ocean, sei whales generally migrate from temperate zones occupied in winter to higher latitudes in the summer, where most feeding takes place (Gambell 1985a). Sei whales appear to prefer regions of steep bathymetric relief such as the continental shelf break, seamounts, and canyons (Kenney and Winn 1987; Gregr and Trites 2001).

On feeding grounds, they associate with oceanic frontal systems (Horwood 1987) such as the cold eastern currents in the North Pacific (Perry et al. 1999).

Sei whales are frequently seen in groups of 2–5 (Leatherwood et al. 1988; Jefferson et al. 2008), although larger groups sometimes form on feeding grounds (Gambell 1985a). Based on NMFS vessel surveys in the ETP during July–December 2006, Jackson et al. (2008) reported mean group sizes for tentative sei whale sightings (may have been Bryde’s whales, see above) of 1.3 (n = 21). Sei whales generally do not dive deeply, and dive durations are 15 min or longer (Gambell 1985a).

Sei whales may have been sighted during surveys in the ETP (Wade and Gerrodette 1993; Kinzey et al. 1999, 2000, 2001); however, it is difficult to distinguish sei whales from Bryde’s whales at sea. Because sei whales generally have a more northerly and temperate distribution (Leatherwood et al. 1988), Wade and Gerrodette (1993) classified any tentative sei whale observations in the ETP as Bryde’s whale sightings. Sei whales may also have been sighted near the Galápagos Islands (Clarke 1962 *in* Gallardo et al. 1983), although Clarke and Aguayo (1965 *in* Gallardo et al. 1983) suggested that those sightings could have been Bryde’s whales. Although the occurrence of sei whale is documented off Costa Rica (Rodríguez-Herrera et al. 2002), the reliability of the identification is uncertain.

Sei whales are likely to be very rare in the survey area. Neither Ferguson and Barlow (2001) nor Jackson et al. (2004, 2008) positively identified sei whales in or near the proposed survey area during surveys conducted during July–December. Similarly, Rasmussen et al. (2004) did not report sei whales in annual surveys off Costa Rica. No sei whales were detected during L-DEO seismic surveys off Costa Rica in November–December 2004 or February–March 2008 (Holst et al. 2005a; Holst and Smultea 2008).

Fin Whale (*Balaenoptera physalus*)

The fin whale is listed as *Endangered* under the U.S. ESA and on the 2010 IUCN Red List of Threatened Species (IUCN 2010), and is listed in CITES Appendix I (UNEP-WCMC 2010). Based on 2001 and 2005 surveys, the California/Oregon/Washington Stock of fin whales was estimated at 2636 (Carretta et al. 2010).

Fin whales are widely distributed in all the world’s oceans in coastal, shelf, and oceanic waters, but typically occur in temperate and polar regions (Gambell 1985b; Perry et al. 1999; Greg and Trites 2001; Jefferson et al. 2008). The North Pacific population summers from the Chukchi Sea to California, and winters from California southward (Gambell 1985b). Fin whales from the Southern Hemisphere are usually distributed south of 50°S in the austral summer (Gambell 1985b). The Chile–Peruvian stock of the Southern Hemisphere fin whale population winters west of northern Chile and Peru from 110°W to 60°W (Gambell 1985b). If fin whales occur in the project area, they would probably be from the North Pacific population.

The species appears to have complex seasonal movements and is likely a seasonal migrant. Mating and calving occurs in temperate waters during winter, followed by migration to northern latitudes to feed during the summer (Mackintosh 1966; Gambell 1985b; Jefferson et al. 2008). However, some evidence suggests that there is a resident population of fin whales in the Gulf of California (Tershy et al. 1993). Thus, some individuals or populations may not undertake the typical long-distance migrations that characterize this species. Sergeant (1977) suggested that fin whales tend to follow steep slope contours, either because they detect them readily or because biological productivity is high along steep contours because of tidal mixing and perhaps current mixing.

Fin whales are typically observed alone or in pairs, but also in groups of up to seven or more, with the largest aggregations occurring on feeding grounds (Jefferson et al. 2008). Based on NMFS vessel-

based surveys in the ETP in July–December 2006, Jackson et al. (2008) reported a mean group size of 1.2 ($n = 8$); all sightings were near Baja California. Croll et al. (2001) reported a mean dive depths and times of 98 m and 6.3 min for foraging fin whales, and 59 m and 4.2 min for non-foraging individuals. Dive depths of >150 m coinciding with the diel migration of krill were reported by Panigada et al. (1999).

Fin whales are considered very rare in the proposed survey area. No confirmed fin whale sightings were made near the proposed survey area during 10 years of survey effort in July–December by Ferguson and Barlow (2001) or by Jackson et al. (2008) during July–December surveys in 2006. Despite >30 years of SWFSC other surveys and stranding records from the Pacific coast of Costa Rica, there have been no confirmed records of fin whales (May-Collado et al. 2005). A possible sighting of a fin whale in this region occurred off the Osa Peninsula in 1997; however, the species was not confirmed (May-Collado et al. 2005). Rodríguez-Herrera et al. (2002) list the fin whale as having been documented off Costa Rica.

No fin whales were detected during L-DEO seismic surveys off Costa Rica or Nicaragua in November–December 2004 or February–March 2008 (Holst et al. 2005a; Holst and Smultea 2008).

Blue Whale (*Balaenoptera musculus*)

The blue whale is listed as *Endangered* under the U.S. ESA and on the 2010 IUCN Red List of Threatened Species (IUCN 2010), and is listed in CITES Appendix I (UNEP-WCMC 2010). Blue whale abundance has been estimated at 2300 for the Southern Hemisphere (IWC 2010), up to 1000 in the central and northeast Atlantic (Pike et al. 2009), and ~2842 for the eastern North Pacific (Carretta et al. 2010). Blue whale calls monitored from the U.S. Navy Sound Surveillance System (SOSUS) and other offshore hydrophones suggest that separate populations occur in the eastern and western North Pacific (Stafford et al. 1999a,b, 2001, 2007; Watkins et al. 2000; Stafford 2003). The blue whale population in the ETP in the summer/fall was estimated at 1415 (Wade and Gerrodette 1993).

The blue whale is widely distributed throughout most of the world's oceans, occurring in coastal, shelf, and pelagic waters (Jefferson et al. 2008), and is most often found in cool, productive waters where upwelling occurs (Reilly and Thayer 1990). Generally, blue whales are seasonal migrants between high latitudes in the summer, where they feed, and low latitudes in winter, where they mate and give birth (Lockyer and Brown 1981). Little is known about the movements and wintering grounds of the stocks (Mizroch et al. 1984). Some individuals may stay in low or high latitudes throughout the year (Reilly and Thayer 1990; Watkins et al. 2000). Broad-scale acoustic monitoring indicates that blue whales of the Eastern North Pacific Stock may range from the ETP along the coast of North America to Canada, and offshore at least 500 km (Stafford et al. 2001).

Blue whales are typically found singly or in groups of two or three (Yochem and Leatherwood 1985; Jefferson et al. 2008). They commonly form scattered aggregations on feeding grounds (Jefferson et al. 2008), and apparently single whales are likely part of a large, dispersed group (Wade and Friedrichsen 1979). Based on NMFS vessel surveys in the ETP in July–December 2006, Jackson et al. (2008) reported a mean group size of 1.9 ($n = 57$). Four satellite-radio-tagged blue whales in the northeast Pacific Ocean spent 94% of their time underwater, 72% of dives were <1 min long, and “true” dives (>1 min) were 4.2–7.2 min long. Shallow (<16-m) dives were most common (75%), and the average depth of deep (>16-m) dives was 105 m (Lagerquist et al. 2000). Croll et al. (2001) reported mean dive depths and times of 140 m and 7.8 min for foraging blue whales, and 68 m and 4.9 min for non-foraging individuals. Dives of up to 300 m were recorded for tagged blue whales (Calambokidis et al. 2003).

In the ETP, blue whales have been sighted offshore from Costa Rica, particularly the CRD, throughout the year (Wade and Friedrichsen 1979; Reilly and Thayer 1990; Mate et al. 1999; Chandler and Calambokidis 2004; Branch et al. 2006). The CRD is centered at 9°N, 90°W, ~630 km west of the northern offshore boundary of the proposed survey area. Reilly and Thayer (1990) suggested that blue

whales that occur in the CRD may be migrant animals from the northern or southern hemispheres or they may be a resident population. Reilly and Thayer (1990) also suggested that the whales seen along the equator are likely part of the southeast Pacific population, which occupies the coastal shelf of South America and the Antarctic (Mackintosh 1966). However, the whales could also be resident in the area, exploiting food resources in the CRD and near the South American coastline (Mate et al. 1999; Palacios 1999). Based on call similarities, Stafford et al. (1999b) linked the whales near the CRD to the population that feeds off California at the same time of year. A recent satellite-tagging study confirmed that some blue whales off California migrate south in the fall to an area west of the CRD at 9°N; the area is considered an important winter feeding area for blue whales (Bailey et al. 2009).

Sightings of blue whales in the ETP, including equatorial waters, may include the pygmy blue whale (Berzin 1978; Donovan 1984). Berzin (1978) reported that the distribution of the pygmy blue whale is much wider than previously thought; however, this subspecies is difficult to distinguish from the larger blue whale (Donovan 1984).

Blue whales are rare in the proposed survey area. May-Collado et al. (2005) reported three groups of four blue whales off Costa Rica based on compiled sightings from 1979 to 2001. One sighting was in deep oceanic waters ~200 km west of the proposed survey area. Jackson et al. (2008) also sighted one blue whale ~250 km northwest of the Nicoya Peninsula during surveys in July–December 2006. No blue whales were detected during L-DEO seismic surveys off Costa Rica or Nicaragua in November–December 2004 or February–March 2008 (Holst et al. 2005a; Holst and Smultea 2008).

(2) Odontocetes

Sperm Whale (*Physeter macrocephalus*)

The sperm whale is listed as *Endangered* under the U.S. ESA and *Vulnerable* on the 2010 IUCN Red List of Threatened Species (IUCN 2010), and is listed in CITES Appendix I (UNEP-WCMC 2010). Wade and Gerrodette (1993) estimated sperm whale abundance in the ETP at 22,666. Whitehead (2002) updated that estimate to 26,053.

It is not clear whether sperm whales seen in the ETP are part of the Northern or Southern Hemisphere stocks, or whether they should be considered a separate stock (Rice 1998). Sperm whales occurring off the Galápagos Islands and near the coast of Ecuador are thought to belong to two different populations (Dufault and Whitehead 1995). Whitehead and Waters (1990) suggested that those in the Galápagos may be part of the Northern Hemisphere stock, and those off Ecuador part of the Southern Hemisphere stock, based on the timing of their breeding seasons. Both populations are considered part of the Southern Hemisphere stock for management purposes (Donovan 1991).

Sperm whales range between the northern and southern edges of the polar pack ice, although they are most abundant in tropical and temperate waters >1000 m deep over the continental shelf edge and slope and in pelagic waters (e.g., Rice 1989; Gregor and Trites 2001; Waring et al. 2001). Adult females and juveniles generally occur year-round in tropical and subtropical waters, whereas males often move to higher latitudes outside the breeding season to forage (Best 1979; Watkins and Moore 1982; Arnborn and Whitehead 1989; Whitehead and Waters 1990). Sperm whales often associate with areas of high secondary productivity and steep underwater topography, such as volcanic islands (Jacquet and Whitehead 1996). Adult males may occur in water depths <100 m and as shallow as 40 m (Whitehead et al. 1992; Scott and Sadove 1997). Females almost always occur in water depths >1000 m (Whitehead 2002).

Sperm whales undertake some of the deepest-known dives for the longest durations among cetaceans. They can dive as deep as ~2 km and possibly deeper on rare occasions, for periods of over 1 h; however, most of their foraging occurs at depths of ~300–800 m for 30–45 min (Whitehead 2003). A recent study of

tagged male sperm whales off Norway found that foraging dives extended to highly variable maximum depths, ranging from 14 to 1860 m and with median 175 m (Teloni et al. 2008). During a foraging dive, sperm whales typically travel ~3 km horizontally and 0.5 km vertically (Whitehead 2003). At the Galápagos Islands, sperm whales typically forage at depths of ~400 m (Papastavrou et al. 1989; Whitehead 1989; Smith and Whitehead 2000). Whales typically dove for ~40 min and then spent 10 min at the surface (Papastavrou et al. 1989).

Sperm whales occur singly (older males) or in groups, with mean group sizes of 20–30 but as many as 50 (Whitehead 2003; Jefferson et al. 2008). May-Collado et al. (2005) reported a mean group size of 9.9 off Costa Rica. Based on NMFS vessel surveys in the ETP in 2006, Jackson et al. (2008) reported a mean group size of 6.1 (n = 24).

Sperm whales are uncommon in the proposed survey area. May-Collado et al. (2005) reported 35 sightings of 348 sperm whales in Costa Rica waters from 1979–2001, primarily concentrated in deep offshore waters off southeast Costa Rica, including waters near Isla del Cocos, although four sightings were reported within ~200 km of the proposed survey area. Rasmussen et al. (2004) reported one sperm whale sighting in deep offshore waters in annual surveys (1996–2003) off Costa Rica and Panama. Jackson et al. (2004) also recorded one sperm whale >200 km southeast of the proposed survey area during surveys in July–December 2003.

Polacheck (1987) and Wade and Gerrodette (1993) reported that during surveys in the summer and fall, sperm whales were widely distributed in the ETP, although they were generally more abundant in deep “nearshore” waters than far offshore. Rodríguez-Fonseca and Cubero-Pardo (2001) reported that the sperm whale is the cetacean species with the highest frequency of strandings in Costa Rica, with a reported seven strandings on the Pacific coast during a 33-year period. Twenty sperm whale strandings were also reported off the coast of Ecuador between 1987 and 1994 (Haase and Félix 1994).

No sperm whales were detected in or near the proposed survey area during an L-DEO seismic survey in November–December 2004, during which >3500 km of daytime visual effort and 5200 km of 24-h PAM effort took place (Holst et al. 2005a). Similarly, no sperm whales were detected during L-DEO seismic surveys off Costa Rica or Nicaragua in February–March 2008 (Holst and Smultea 2008).

Dwarf and Pygmy Sperm Whale (*Kogia sima* and *K. breviceps*)

Dwarf sperm whales (*Kogia sima*) and pygmy sperm whales (*K. breviceps*) are distributed widely throughout tropical and temperate seas, but their precise distributions are unknown. Much of what we know of the species comes from strandings (McAlpine 2002). They are difficult to sight at sea, because of their dive behavior and perhaps because of their avoidance reactions to ships and behavior changes in relation to survey aircraft (Würsig et al. 1998). The two species are often difficult to distinguish from one another when sighted (McAlpine 2002). Wade and Gerrodette (1993) estimated that the population of dwarf sperm whales in the ETP was 11,200.

Both *Kogia* species are sighted primarily along the continental shelf edge and slope and over deeper waters off the shelf (Hansen et al. 1994; Davis et al. 1998; Jefferson et al. 2008). Several studies have suggested that pygmy sperm whales live mostly beyond the continental shelf edge, whereas dwarf sperm whales tend to occur closer to shore, often over the continental shelf (Rice 1998; Wang et al. 2002; MacLeod et al. 2004). Barros et al. (1998), on the other hand, suggested that dwarf sperm whales might be more pelagic and dive deeper than pygmy sperm whales. Another suggestion is that the pygmy sperm whale is more temperate, and the dwarf sperm whale more tropical, based at least partially on live sightings at sea from a large database from the ETP (Wade and Gerrodette 1993). This idea is also supported by the distribution of strandings in South American waters (Muñoz-Hincapié et al. 1998).

Pygmy and dwarf sperm whales are usually found singly or in groups of less than six (Jefferson et al. 2008). May-Collado et al. (2005) reported a mean group size of 1.9 dwarf sperm whales off Costa Rica. Based on NMFS vessel-based surveys in the ETP, Jackson et al. (2008) reported a mean group size of 1.6 ($n = 31$) for dwarf sperm whales. In the Gulf of California, median dive and surface times for dwarf or unidentified *Kogia* sp. were 8.6 min and 1.2 min, and dives of up to 25 min and surface times up to 3 min were common (J. Barlow, pers. comm. in Willis and Baird 1998). Little is known about dive depths of *Kogia* spp. A satellite-tagged pygmy sperm whale released off Florida made longer dives (> 8 min and up to ~ 18 min) at night and on overcast days, and shorter dives (usually 2–5 min) on clear days, probably because of the distribution of their prey, vertically-migrating squid (Scott et al. 2001).

Both *Kogia* species distributions overlap with the proposed survey area, although dwarf sperm whales are likely to be rare and pygmy sperm whales are likely to be very rare. Rodríguez-Fonseca (2001) reported the presence of *Kogia* sp. off Costa Rica, but only the dwarf sperm whale has been positively identified as occurring in that area (Ferguson and Barlow 2001). Similarly, the dwarf sperm whale was the only confirmed *Kogia* species off Costa Rica based on sightings compiled from 1979 to 2001 by May-Collado et al. (2005). Most of the 32 groups of *Kogia sima* occurred in offshore waters, with frequent sightings ~ 100 – 150 km northeast of the Osa Peninsula. Jackson et al. (2008) reported one dwarf sperm whale ~ 200 km west of the proposed survey area and one *Kogia* sp. sighting off the Nicoya Peninsula during July–December surveys in 2006. Rodríguez-Fonseca and Cubero-Pardo (2001) reported a stranding of six *K. simus* in 1993 on the Pacific coast.

No *Kogia* sp. were detected during L-DEO seismic surveys off Costa Rica and Nicaragua in November–December 2004 (Holst et al. 2005a). During an L-DEO seismic survey off Costa Rica and Nicaragua in February–March 2008, one sighting of a dwarf sperm whale was made within 50 km of the proposed survey area in water ~ 2000 m deep, and a sighting of two *Kogia* sp. was made ~ 150 km west of the proposed survey area in waters 3500 m deep (Holst and Smultea 2008). The latter sighting was reported as probable pygmy sperm whales, but the sighting distance was 5.7 km (Holst and Smultea 2008).

Cuvier's Beaked Whale (*Ziphius cavirostris*)

Cuvier's beaked whale is probably the most widespread of the beaked whales, although it is not found in high-latitude polar waters (Heyning 1989). There are an estimated 20,000 Cuvier's beaked whales in the ETP (Wade and Gerrodette 1993).

Cuvier's beaked whale is found in deep water, but it appears to prefer steep continental slope waters (Jefferson et al. 2008), and is most common in water depths > 1000 m (Heyning 1989). Ferguson et al. (2006a) reported that in the ETP, the mean water depth where Cuvier's beaked whales were sighted was ~ 3.4 km. It is most commonly seen in groups of 2–7 but also up to 15, with a reported mean group size of 2.3 (MacLeod and D'Amico 2006; Jefferson et al. 2008). May-Collado et al. (2005) reported a mean group size of 2.6 off Costa Rica. In the ETP, group sizes range from one to seven (Heyning 1989). Wade and Gerrodette (1993) reported a mean group size of 2.2 ($n = 91$) and Jackson et al. (2008) reported a mean group size of 1.8 ($n = 16$). Cuvier's beaked whales make long (30–60 min), deep dives with reported maximum depths of 1267 m (Johnson et al. 2004) and 1450 m (Baird et al. 2006).

Cuvier's beaked was the most frequent beaked whale identified to species level (14 of 47 beaked whale sightings) in or near the proposed study area based on surveys in Costa Rica waters during 1979–2001; an additional 15 groups were recorded as unidentified beaked whales (May-Collado et al. 2005). Beaked whales occurred primarily in offshore deep waters (May-Collado et al. 2005). Rodríguez-Fonseca (2001) identified the waters by Isla del Cocos, and Isla del Caño and the outer part of the Osa Peninsula, as two important areas off western Costa Rica for the species, although the study of May-

Collado et al. (2005) “did not show patterns to support” the importance of Isla del Cocos for Cuvier’s beaked whale. Jackson et al. (2004) reported one Cuvier’s beaked whale sighting off the Nicoya Peninsula during surveys in July–December 2003. Jackson et al. (2008) also encountered beaked whales within ~200 km of the proposed survey area during surveys in July–December 2006.

No Cuvier’s beaked whales or other beaked whales were detected during L-DEO seismic surveys off Costa Rica or Nicaragua in November–December 2004 or February–March 2008 (Holst et al. 2005a; Holst and Smultea 2008).

Mesoplodont Beaked Whales (*Mesoplodon* spp.)

Mesoplodont beaked whales (*Mesoplodon* spp.) are difficult to distinguish in the field, and confirmed at-sea sightings are rare (Mead 1989; Caretta et al. 2010; Jefferson et al. 2008). Until better methods are developed for distinguishing the different *Mesoplodon* species from one another, the management unit for the U.S. west coast is defined to include all *Mesoplodon* populations (Caretta et al. 2010). Wade and Gerrodette (1993) estimated a population size of mesoplodont beaked whales at 25,300 for the ETP.

Mesoplodonts are distributed primarily in deep waters (>2000 m) and along continental slopes at depths 200–2000 m; they are rarely found in continental shelf waters (Pitman 2002). Most mesoplodonts identified to species are known from strandings involving single individuals (Jefferson et al. 2008), thus it is not possible to identify spatial or seasonal patterns in their distribution (Caretta et al. 2010). Dive depths of most of these species are undocumented.

Mean group sizes are unknown for many of the *Mesoplodon* spp. For the genus, May-Collado et al. (2005) reported a mean group size of 2.4 off Costa Rica, Wade and Gerrodette (1993) reported a mean group size of 3.0 (n = 128) for the ETP, and Jackson et al. (2008) reported a mean group size of 2.4 (n = 30) for the ETP during July–December surveys in 2006.

Mesoplodonts are uncommon in the proposed survey area based on 1979–2001 surveys in Costa Rica waters (May-Collado et al. 2005). May-Collado et al. (2005) reported five mesoplodont sightings, and Jackson et al. (2008) reported one mesoplodont sighting within ~200 km of the proposed survey area.

MacLeod and Mitchell (2006) identified the ETP as a key area for beaked whales. Three species are known to occur in or near the survey area: the pygmy, ginkgo-toothed, and Blainville’s beaked whale.

Pygmy Beaked Whale (*M. peruvianus*).—Information on the pygmy beaked whale is based on scattered sightings in the ETP and a small number of strandings (Jefferson et al. 2008). The pygmy beaked whale is thought to occur between latitudes of ~28°N and 30°S, from Baja California to Peru and Chile (Urbán-Ramírez and Auriolos-Gamboa 1992; Pitman and Lynn 2001; Jefferson et al. 2008). Reyes et al. (1991) reported 10 records of this species in south-central Peru. Pitman and Lynn (2001) reported that the species may have been known previously as *Mesoplodon* sp. “A”. The pygmy beaked whale is now believed to be widespread in the ETP, but concentrated off central Mexico (Pitman and Lynn 2001). Wade and Gerrodette (1993) reported several sightings for *M. peruvianus* as well as *Mesoplodon* sp. “A” in the ETP.

This species is known to inhabit deep warm temperate waters beyond the continental shelf (Jefferson et al. 2008). Most sightings have consisted of two but as many as five have been sighted, with a mean group size of 2.3 (Jefferson et al. 2008).

Ferguson and Barlow (2003) reported no pygmy beaked whale sightings and one *Mesoplodon* sp. “A” sighting in the survey block (138) that includes the proposed survey area during 10 years of surveys conducted in July–December. No pygmy (or *M. sp* “A”) beaked whales were reported off Costa Rica by May-Collado et al. (2005) or Rodríguez-Fonseca and Cubero-Pardo (2001) based on compiled sightings from 1979–2001 and strandings from 1966–1999, respectively. Jackson et al. (2004) reported two

sightings of *M. peruvianus* in offshore waters west of Nicoya Peninsula. Jackson et al. (2008) reported one sighting of *M. peruvianus* within ~200 km of the proposed project area during July–December surveys in 2006. Pygmy beaked whales are unlikely to occur in the proposed survey area.

Ginkgo-toothed Beaked Whale (*M. ginkgodens*).—The ginkgo-toothed beaked whale is only known from stranding records (Mead 1989). Strandings have been reported for the western and eastern North Pacific, South Pacific, and Indian oceans, and from the Galápagos Islands (Palacios 1996a). Two of the total 13 records reported by Mead (1989) were from the eastern North Pacific, one from Del Mar, California, and one from Baja California. The species is hypothesized to occupy relatively cool areas in the temperate and tropical Pacific, where upwelling is known to occur, such as in the California and Peru Currents and the equatorial front (Palacios 1996a).

No ginkgo-toothed beaked whales were reported off Costa Rica by May-Collado et al. (2005) based on compiled sightings from 1979–2001, or by Rodríguez-Fonseca and Cubero-Pardo (2001) using 1966–1999 stranding records.

Blainville's Beaked Whale (*M. densirostris*).—Blainville's beaked whale is the most widely distributed *Mesoplodon* species (Mead 1989), although it is generally limited to pelagic tropical and warmer temperate waters (Jefferson et al. 2008). Occasional occurrences in cooler, higher-latitude waters are presumably related to warm-water incursions (Reeves et al. 2002). Long-term habitat studies in the northern Bahamas found that Blainville's beaked whales preferred continental slope waters 200–1000 m deep characterized by intermediate depth gradients (MacLeod and Zuur 2005), where they spent most of their time along a canyon wall in waters <800 m deep (Claridge 2003; MacLeod et al. 2004; MacLeod and Zuur 2005). Studies elsewhere indicate that Blainville's beaked whales most frequently occurred in waters 300–1400 m deep (Society Islands, Gannier 2000) and 100–500 m deep (Canary Islands, Ritter and Brederlau 1999). This species may also occur in coastal areas, particularly where deep water gullies come close to shore (Jefferson et al. 2008).

The most commonly observed group size for this species is 1–2, with a maximum of 9 off Hawaii (Baird et al. 2006; Jefferson et al. 2008). MacLeod and D'Amico (2006) reported a mean group size of 3.5 ($n = 31$), and Ritter and Brederlau (1999) reported a mean group size of 3.4. The maximum known dive depth of tagged Blainville's beaked whales is 1408 m off Hawaii (Baird et al. 2006).

In the ETP, Blainville's beaked whales have been sighted in offshore as well as nearshore areas of Central and South America (Pitman et al. 1987; Pitman and Lynn 2001). The species was not sighted in the survey block (138) that includes the proposed study area but was sighted in survey blocks immediately to the south of it during 10 years of surveys conducted in July–December (Ferguson and Barlow (2003). Off Costa Rica, May-Collado et al. (2005) reported one sighting of three Blainville's beaked whales in deep offshore waters based on sightings during 1979–2001.

Rough-toothed Dolphin (*Steno bredanensis*)

The rough-toothed dolphin is distributed worldwide in tropical, subtropical, and warm temperate waters (Miyazaki and Perrin 1994). Wade and Gerrodette (1993) estimated rough-toothed dolphin abundance in the ETP at 145,900 based on data collected during 1986–1990. For 2006, the abundance estimate was 107,633 (Gerrodette et al. 2008).

Rough-toothed dolphins are generally seen in deep water and in shallower waters around islands. They are typically found in groups of 10–20, but groups of up to 300 have been seen (Jefferson 2002). May-Collado et al. (2005) reported a mean group size of 19.3 off Costa Rica based on sightings during 1979–2001. The mean group size in the ETP is 15.5 (Ferguson et al. 2006b). Rough-toothed dolphins are deep divers and can dive for up to 15 min (Reeves et al. 2002).

In the ETP, sightings of rough-toothed dolphins have been reported by Perrin and Walker (1975), Pitman and Ballance (1992), Wade and Gerrodette (1993), Kinzey et al. (1999, 2000, 2001), Ferguson and Barlow (2001), May-Collado et al. (2005), and Jackson et al. (2008).

Rough-toothed dolphins are common in the proposed survey area. May-Collado et al. (2005) documented 28 sightings of 513 individuals based on surveys in Costa Rica waters during 1979–2001. These sightings were distributed from nearshore to far offshore, with several occurring in the proposed survey area. Jackson et al. (2004, 2008) also reported rough-toothed dolphin sightings in or near the proposed survey area. No rough-toothed dolphins were detected during L-DEO seismic surveys off Costa Rica or Nicaragua in November–December 2004 or February–March 2008 (Holst et al. 2005a; Holst and Smultea 2008).

Bottlenose Dolphin (*Tursiops truncatus*)

The bottlenose dolphin occurs throughout the world's tropical, subtropical, and temperate waters, most commonly in coastal and continental shelf waters (Jefferson et al. 2008). Gerrodette et al. (2008) estimated the abundance of bottlenose dolphins in the ETP at 335,834 for 2006.

There are two distinct bottlenose dolphin types: a shallow water type mainly found in coastal waters and a deepwater type mainly found in oceanic waters (Duffield et al. 1983; Hoelzel et al. 1998; Walker et al. 1999). The nearshore dolphins usually inhabit shallow waters along the continental shelf and upper slope, at depths <200 m (Davis et al. 1998), whereas offshore dolphins show a preference for water <2000 m deep (Klatsky et al. 2007). Bottlenose dolphins are reported to regularly dive to depths >450 m for periods of >5 min, and even down to depths of 600–700 m for up to 12 min (Klatsky et al. 2007). They usually occur in groups of 2–20, although groups of >100 are occasionally seen in offshore areas (Shane et al. 1986; Jefferson et al. 2008). Off Costa Rica, May-Collado et al. (2005) reported a mean group size of 21.5 based on sightings during 1979–2001. For the ETP, Ferguson et al. (2006b) reported a mean group size of 24.1 and Jackson et al. (2008) reported a mean group size of 24.2 (n = 149).

In the ETP, bottlenose dolphins tend to be more abundant close to the coasts and islands (Scott and Chivers 1990); they also seem to occur more inshore than other dolphin species (Wade and Gerrodette 1993). Polacheck (1987) reported that the highest encounter rates for bottlenose dolphins in the ETP tended to be in nearshore areas.

Bottlenose dolphins are relatively common in the proposed survey area. Based on the SWFSC surveys and model used to calculate densities in the proposed survey area in § IV(3), they are the fifth-ranked species there. May-Collado et al. (2005) compiled 176 sightings of 3584 individuals in Costa Rica waters during 1979–2001. These sightings were distributed primarily in coastal waters but also in offshore oceanic waters; numerous sightings occurred in the proposed survey area. Jackson et al. (2004, 2008) reported sightings of bottlenose dolphins in the proposed survey area. Rasmussen et al. (2004) reported 49 sightings of bottlenose dolphins in annual surveys (1996–2003) off Costa Rica. Three sightings of bottlenose whales were reported during a two-week survey off Costa Rica in January–February 2010 (Calambokidis et al. 2010).

One group of bottlenose dolphins were identified near the proposed survey area in waters 1000 m deep during L-DEO seismic surveys off Costa Rica and Nicaragua in November–December 2004 (Holst et al. 2005a). Two groups of bottlenose dolphins were observed in the proposed survey area in waters 100 m deep during L-DEO seismic surveys in February–March 2008 (Holst and Smultea 2008).

Pantropical Spotted Dolphin (*Stenella attenuata*)

In the eastern Pacific, the pantropical spotted dolphin ranges from 25°N off Baja California, Mexico, to 17°S off southern Peru (Perrin and Hohn 1994). Au and Perryman (1985) reported that the

species occurs primarily north of the equator, off southern Mexico, and westward along 10°N. They also reported its occurrence in seasonal tropical waters south of the Galápagos Islands.

Dizon et al. (1994) identified three stocks of spotted dolphins in the ETP: the coastal stock (*S. a. grafmani*) and two offshore (*S. a. attenuata*) stocks (the northeast and the west/south stock). However, recent genetic evidence suggests that there may be nine genetically distinct stocks of this species in coastal areas from Baja California south to Ecuador (Rosales and Escorza-Trefiño 2005). The coastal stock occurs within ~200 km of the coastline (Dizon et al. 1994) and is the stock most likely to occur in the proposed survey area.

There was an overall stock decline of spotted dolphins in the ETP during 1960–1980 because of the purse-seine tuna fishery (Allen 1985). Gerrodette and Forcada (2005) reported that the population of offshore northeastern spotted dolphins has not yet recovered from the earlier population declines. For 1986–1990, Wade and Gerrodette (1993) reported a population estimate of 2.1 million for all three stocks based on data collected during 1986–1990. The abundance estimate of all spotted dolphin stocks in the ETP for 2006 was 1.6 million (Gerrodette et al. 2008). Off Costa Rica, May-Collado et al. (2005) reported a mean group size of 29.4 based on sightings during 1979–2001. For the ETP, Gerrodette et al. (2008) estimated a mean group size of 223.4 for coastal pantropical spotted dolphins.

Pantropical spotted dolphins are very common in the proposed survey area. Based on the SWFSC surveys and model used to calculate densities in the project area (see § IV[3]), they are the second-ranked species there. May-Collado et al. (2005) reported 525 sightings of 1311 pantropical spotted dolphins during 1979–2001. The majority of sightings were primarily in coastal waters around Osa Peninsula with numerous sightings occurring in the proposed survey area (May-Collado et al. 2005). Jackson et al. (2008) reported three sightings of pantropical spotted dolphins near the proposed survey area during July–December surveys in 2006. Rodríguez-Fonseca (2001) noted that the oceanic spotted dolphin was less common than the coastal spotted dolphin in Costa Rican waters. Rasmussen et al. (2004) reported 381 sightings of spotted dolphins in annual surveys during 1996–2003 off Costa Rica and during 2001–2003 off Panama. Thirty-one sightings of spotted dolphins were also recorded by Calambokidis et al. (2010) during a two-week survey off Costa Rica in January–February 2010. Two spotted dolphin strandings on the Pacific coast were included in a list of strandings for Costa Rica during 1966–1999 (Rodríguez-Fonseca and Cubero-Pardo 2001).

One group of pantropical spotted dolphins was observed in water depth ~1000 m near the proposed survey area and three additional groups were observed within ~100 km of the proposed survey area in water depth 2000 m during L-DEO seismic surveys off Costa Rica and Nicaragua in November–December 2004 (Holst et al. 2005a). One group of 40 pantropical spotted dolphins was identified ~90 km of the proposed survey area in water depth 70 m during L-DEO seismic surveys in February–March 2008 (Holst and Smultea 2008).

Spinner Dolphin (*Stenella longirostris*)

The spinner dolphin is distributed in oceanic and coastal waters and is associated with warm tropical surface water (Au and Perryman 1985; Reilly 1990; Reilly and Fiedler 1994). The total population of spinner dolphins in the ETP in 1979 was estimated at 0.8–0.9 million (Allen 1985). Wade and Gerrodette (1993) reported an abundance estimate of 1.7 million for spinner dolphins in the ETP based on data collected during 1986–1990. Gerrodette et al. (2008) estimated the abundance for spinner dolphins in the ETP for 2006 at 1,797,716.

In the ETP, three types of spinner dolphins have been identified and two of those are recognized as subspecies: the eastern spinner dolphin, *S. l. orientalis*, considered an offshore species, the Central American spinner, *S. l. centroamericana* (also known as the Costa Rican spinner), considered a coastal

species in Costa Rica (Perrin 1990; Dizon et al. 1991), and the ‘whitebelly’ spinner, which is thought to be a hybrid of the eastern spinner and Gray’s spinner (*S. l. longirostris*). Although there is a great deal of overlap between the ranges of eastern and whitebelly spinner dolphins, the eastern form generally occurs in the northeastern portion of the ETP, whereas the whitebelly spinner occurs in the southern portion of the ETP, ranging farther offshore (Wade and Gerrodette 1993; Reilly and Fiedler 1994). The Costa Rican spinner dolphin is typically seen within 150 km from shore (ACS 2005). The eastern spinner dolphin and the Costa Rica spinner dolphin subspecies are likely to occur in the proposed survey area.

Spinner dolphins tend to occur in large groups compared to most other cetaceans. May-Collado et al. (2005) reported a mean group size of 97 based on sightings during 1979–2001. Ferguson et al. (2006b) reported mean group sizes of 108.8 and 147.7 for eastern and unidentified spinner dolphins in the ETP, respectively, and Gerrodette and Forcada (2005) reported a mean group size of 112 for the eastern stock. Spinner dolphins usually dive to 600 m or deeper to feed (Perrin and Gilpatrick 1994).

Rasmussen et al. (2004) reported only one sighting of spinner dolphins in annual surveys from 1996 to 2003 off Costa Rica. May-Collado et al. (2005) reported spinner dolphins primarily in oceanic waters off Costa Rica during 1979–2001, with small numbers in coastal waters. Both *S. l. orientalis* and *S. l. centroamericana* sightings were reported once each in the proposed survey area (May-Collado et al. 2005). No sightings of eastern spinner dolphins were reported in or near the proposed survey area during July–December surveys in 2003 or in 2006 (Jackson et al. 2004, 2008).

During L-DEO seismic surveys off Costa Rica and Nicaragua in November–December 2004 and February–March 2008, one group of spinner dolphins was identified <50 km west of the Nicoya Peninsula in waters <1000 m deep, and one group of spinner dolphins was identified ~100 km southwest of the Nicoya Peninsula in waters ~3500 m deep (Holst et al. 2005a; Holst and Smultea 2008).

Striped Dolphin (*Stenella coeruleoalba*)

The striped dolphin has a cosmopolitan distribution in tropical to warm temperate waters from ~50°N to 40°S (Perrin et al. 1994a; Jefferson et al. 2008). Wade and Gerrodette (1993) estimated that the population in the ETP numbered 1.9 million based on data collected during 1986–1990. The population has declined; Gerrodette et al. (2008) estimated the abundance of striped dolphins in the ETP at 964,362 for 2006.

The striped dolphin’s preferred habitat seems to be cool, deep, oceanic waters (Davis et al. 1998) along the edge and seaward of the continental shelf, particularly convergence zones and upwelling areas (Au and Perryman 1985). Striped dolphin group sizes are typically several dozen to 500, although groups of thousands sometimes form (Jefferson et al. 2008). Off Costa Rica, May-Collado et al. (2005) reported a mean group size of 48.9 based on sightings during 1979–2001. For the ETP, Wade and Gerrodette (1993) reported a mean group size of 61, and Jackson et al. (2008) reported a mean group size of 51.8 (n = 137). Striped dolphins are believed to be capable of diving to depths of 200–700 m based on stomach content analyses (Archer and Perrin 1999).

The striped dolphin is very common in the proposed survey area. Based on the SWFSC surveys and model used to calculate densities in the project area (see § IV[3]), it is the third-ranked species there. The striped dolphin was also the third most sighted species in Costa Rica waters during 1979–2000, although the species was reported nearly exclusively from oceanic waters (May-Collado et al. 2005). All sightings reported occurred >150 km of the proposed survey area (Jackson et al. 2004, 2008; May-Collado et al. 2005).

During L-DEO seismic surveys off Costa Rica and Nicaragua in February–March 2008, one sighting of 40 striped dolphins was made in waters ~2000 m deep and ~25 km from the proposed survey area (Holst and Smultea 2008). None were observed in November–December 2004 (Holst et al. 2005a).

Fraser's Dolphin (*Lagenodelphis hosei*)

Fraser's dolphin is a tropical species that rarely occurs in temperate regions, and then only in relation to temporary oceanographic anomalies such as El Niño events (Perrin et al. 1994b). Wade and Gerrodette (1993) reported a mainly equatorial distribution in the ETP, and estimated its abundance in the area at 289,300 based on data collected during 1986–1990.

Fraser's dolphins typically occur in water at least 1000 m deep. They dive to depths of at least 250–500 m to feed (Dolar 2002). They travel in groups ranging from just a few animals to hundreds or even thousands (Perrin et al. 1994b), often mixed with other species (Culik 2002). For the ETP, Wade and Gerrodette (1993) reported a mean group size of 395, and Ferguson et al. (2006b) reported a mean group size of 440.

Fraser's dolphin are rare in the proposed survey area. May-Collado et al. (2005) reported only one sighting of 158 Fraser's dolphins in deep oceanic waters during SWFSC, CRC, and PCC surveys in Costa Rica waters during 1979–2001. No Fraser's dolphins were reported in the ETP during July–December surveys in 2003 or in 2006 (Jackson et al. 2004, 2008). Similarly, no Fraser's dolphins were detected during L-DEO seismic surveys off Costa Rica or Nicaragua in November–December 2004 or February–March 2008 (Holst et al. 2005a; Holst and Smultea 2008). No encounters are expected during the proposed survey and no takes are requested.

Short-beaked Common Dolphin (*Delphinus delphis*)

Common dolphins are found in tropical and temperate oceans around the world (Evans 1994). There are two species of common dolphin, the more coastal long-beaked dolphin (*Delphinus capensis*) and the more offshore short-beaked dolphin (*D. delphis*). The short-beaked common dolphin is widely distributed compared to the long-beaked common dolphin (Heyning and Perrin 1994). Only the short-beaked common dolphin is expected to occur in the ETP. Three stocks of *D. delphis* are recognized in the ETP: northern, central, and southern (Dizon et al. 1994). Individuals present in the proposed survey area would be from the central stock.

Gerrodette et al. (2005) reported an abundance estimate for short-beaked common dolphins of 1.1 million for 2003. However, abundance estimates of common dolphins have fluctuated from <1 million to >3 million from 1986 to 2000 (Gerrodette and Forcada 2002). The abundance estimate for 2006 was ~3,130,000 (Gerrodette et al. 2008).

The common dolphin's distribution is associated with prominent underwater topography, such as seamounts (Evans 1994). Short-beaked common dolphins are widely distributed from the coast to at least 550 km from shore (Carretta et al. 2010). In the ETP, common dolphin distribution is associated with cool, upwelling areas along the equator and off Baja California, Central America, and Peru (Au and Perryman 1985; Reilly 1990; Reilly and Fiedler 1994). Reilly (1990) reported no seasonal changes in common dolphin distribution, although Reilly and Fiedler (1994) observed interannual changes in distribution that were likely attributable to El Niño events.

Common dolphins travel in groups of ~10 to >10,000 (Jefferson et al. 2008). Off Costa Rica, May-Collado et al. (2005) reported a mean group size of 220.7 based on sightings during 1979–2001. For the ETP, Ferguson et al. (2006b) reported a mean group size of 230, and Jackson et al. (2008) reported a mean group size of 217 (n = 123). Most dives of a radio-tagged common dolphin off southern California were to depths 9–50 m, and the maximum reported depth was ~200 m (Evans 1994).

This species is abundant in the proposed survey area. May-Collado et al. (2005) reported 82 sightings of 17,875 individuals during 1979–2001 off Costa Rica, mostly in oceanic waters; numerous sightings occurred in and near the proposed survey area. Based on the SWFSC surveys and model used

to calculate densities in the proposed survey area (see § IV[3]), they are the first-ranked species there. Jackson et al. (2004, 2008) reported 2 and 3 sightings of common dolphins within ~200 km of the proposed survey area during July–December surveys in 2003 and 2008, respectively. Rasmussen et al. (2004) reported one sighting of common dolphins in annual surveys from 1996 to 2003 off Costa.

During L-DEO seismic surveys off Costa Rica and Nicaragua in November–December 2004, one group of 45 short-beaked common dolphins was identified and one group of 15 common dolphins (species unidentified) was sighted <150 km and ~25 km, respectively, from the proposed survey area (Holst et al. 2005a). Two groups of common dolphins were identified <50 km from the proposed survey area in waters ≥2000 m deep in February–March 2008 (Holst and Smultea 2008).

Risso's Dolphin (*Grampus griseus*)

Risso's dolphin is primarily a tropical and mid-temperate species distributed worldwide between 60°N and 60°S, where surface water temperatures are ~10°C (Kruse et al. 1999). Gerrodette et al. (2008) reported an abundance estimate of 110,457 Risso's dolphins for the ETP.

Risso's dolphins usually occur over steeper sections of the upper continental slope in waters 400–1000 m deep (Baumgartner 1997; Davis et al. 1998), and are known to frequent seamounts and escarpments (Kruse et al. 1999; Baird 2002a). Risso's dolphins occur individually or in small- to moderate-sized groups, normally ranging in numbers from 10 to 100 but up to as many as 4000 (Jefferson et al. 2008). May-Collado et al. (2005) reported a mean group size of 11.6 off Costa Rica. For the ETP, Ferguson et al. (2006b) reported a mean group size of 18.64, and Jackson et al. (2008) reported a mean group size of 18.5 (n = 48). Risso's dolphin can remain underwater up to 30 min (Kruse et al. 1999).

Risso's dolphins are relatively common in the proposed survey area; based on the SWFSC surveys and model used to calculate densities in the proposed survey area (see § IV[3]), they are the sixth-ranked species there. May-Collado et al. (2005) documented 76 sightings of 880 individuals based on surveys in Costa Rica waters during 1979–2001, several occurring in within ~200 km of the proposed survey area. No Risso's dolphin sightings were reported near the proposed survey area during July–December surveys in 2003 or in 2006 (Jackson et al. 2004, 2008) or during annual surveys from 1996 to 2003 off Costa Rica (Rasmussen et al. 2004).

During L-DEO seismic surveys off Costa Rica and Nicaragua, one sighting of 25 Risso's dolphins in waters ~2000 m deep was made ~25 km from the proposed survey area in November–December 2004 (Holst et al. 2005a), but none were observed in February–March 2008 (Holst and Smultea 2008).

Melon-headed Whale (*Peponocephala electra*)

The melon-headed whale is a pantropical and pelagic species (Perryman 2002). It occurs mainly between 20°N and 20°S; occasional occurrences in temperate regions are likely associated with warm currents (Perryman 2002; Reeves et al. 2002). Au and Perryman (1985) and Perryman et al. (1994) reported that the melon-headed whale occurs primarily in equatorial waters, although Wade and Gerrodette (1993) reported its occurrence in non-equatorial waters. Wade and Gerrodette (1993) estimated the abundance of this species in the ETP at 45,400 based on data collected during 1986–1990.

Melon-headed whales are oceanic, occurring in offshore areas or nearshore areas where deep water occurs near the coast (Perryman 2002). Mullin et al. (1994) reported that they are usually sighted in water >500 m deep, and away from the continental shelf. Melon-headed whales tend to travel in groups of 100–500, but have also been seen in groups of 1500–2000. Ferguson et al. (2006b) reported a mean group size of 258 in the ETP.

Melon-headed whales are rare in the proposed survey area. May-Collado et al. (2005) reported two sightings of 445 animals during 1979–2001, one of which was ~170 km southwest of the Osa Peninsula.

Three melon-headed whale strandings occurred on the Pacific coast of Costa Rica during 1966–1999; >200 individuals stranded on the Nicoya Peninsula in 1976, and two individual strandings occurred on the northern coast in 1970 (Rodríguez-Fonseca and Cubero-Pardo 2001). No melon-headed whales were reported near the proposed survey area during July–December surveys in 2003 or 2006 (Jackson et al. 2004, 2008) or during annual surveys from 1996 to 2003 off Costa Rica (Rasmussen et al. 2004).

During L-DEO seismic surveys off Costa Rica and Nicaragua, two sightings of 55 ‘blackfish’ were made ~120 km west of the proposed survey area in waters >3000 m deep in February–March 2008 (Holst and Smultea 2008). These animals were reported as probable melon-headed whales, although the sighting distances were >1800 m. No melon-headed whales were observed in November–December 2004 (Holst et al. 2005a).

Pygmy Killer Whale (*Feresa attenuata*)

The pygmy killer whale is pantropical (Ross and Leatherwood 1994; Rice 1998). The species has been sighted in the ETP (Van Waerebeek and Reyes 1988; Pitman and Ballance 1992; Wade and Gerrodette 1993) and appears to occur sporadically along the equator and the coast of Central America (Wade and Gerrodette 1993). Wade and Gerrodette (1993) estimated the abundance of this species in the ETP at 39,800 based on data collected during 1986–1990.

Pygmy killer whales tend to travel in groups of 15–50, although groups of a few hundred have been sighted (Ross and Leatherwood 1994). In the ETP, Wade and Gerrodette (1993) reported a mean group size of 28, and Ferguson et al. (2006b) reported a mean group size of 30. In warmer water, they are usually seen close to the coast (Wade and Gerrodette 1993), but they are also found in deep waters.

Pygmy killer whales are rare off Costa Rica. May-Collado et al. (2005) reported no sightings of this species based on surveys during 1979–2001, and none were reported during annual surveys from 1996 to 2003 (Rasmussen et al. 2004). No pygmy killer whales were reported near the proposed study area during July–December surveys in 2006 in the ETP (Jackson et al. 2008).

No pygmy killer whales were observed during L-DEO seismic surveys off Costa Rica in November–December 2004 (Holst et al. 2005a). However, during L-DEO seismic surveys off Costa Rica and Nicaragua in February–March 2008, a sighting of 10 ‘blackfish’ was made ~150 km from the proposed survey area in water depths >3000 m (Holst and Smultea 2008). This sighting was made at a distance of 1.6 km and was reported as probable pygmy killer whales (Holst and Smultea 2008).

False Killer Whale (*Pseudorca crassidens*)

The false killer whale is widely distributed, though not abundant anywhere (Jefferson et al. 2008). It is found in all tropical and warmer temperate oceans, especially in deep offshore waters (Odell and McClune 1999). Wade and Gerrodette (1993) estimated their abundance in the ETP at 39,800 based on data collected during 1986–1990.

False killer whales have been sighted in the ETP, where they chase or attack *Stenella* and *Delphinus* dolphins during tuna fishing operations (Perryman and Foster 1980). They travel in groups of 20–100 (Baird 2002b), although groups of several hundred are sometimes observed. Off Costa Rica, May-Collado et al. (2005) reported a mean group size of 36.2, and Martínez-Fernández et al. (2005) reported a mean group size of 13.2. For the ETP, Wade and Gerrodette (1993) and Ferguson et al. (2006b) reported a mean group size of 11, and Jackson et al. (2008) reported a mean group size of 11.8 (n = 16). False killer whales are usually seen far offshore, although sightings have been reported for both shallow (<200 m) and deep (>2000 m) waters (Wade and Gerrodette 1983).

False killer whales are uncommon in the proposed survey area. May-Collado et al. (2005) compiled nine sightings of 253 animals during 1979–2001; one sighting occurred in the proposed survey

area, four other sightings occurred nearshore off the west coast of Osa Peninsula. Martínez-Fernandez et al. (2005) observed four groups off Costa Rica during monthly strip-transect surveys during December 2004–June 2005. None were reported in the ETP during July–December surveys in 2006 (Jackson et al. 2008). Rasmussen et al. (2004) reported eight sightings of false killer whales in annual surveys (1996–2003) off Costa Rica.

No false killer whales were reported off Costa Rica during L-DEO seismic surveys in November–December 2004 or in February–March 2008 (Holst et al. 2005a; Holst and Smultea 2008).

Killer Whale (*Orcinus orca*)

The killer whale is cosmopolitan and widely distributed; it has been observed in all oceans of the world (Ford 2009). Killer whales are segregated socially, genetically, and ecologically into three distinct groups: resident, transient, and offshore animals. Offshore whales do not appear to mix with the other types of killer whales (Black et al. 1997; Dahlheim and Heyning 1999). The abundance of killer whales in the ETP was estimated at 8500 (Wade and Gerrodette 1993), and the minimum global abundance is 50,000 (Ford 2009).

Groups sizes of killer whales are 1–75, though offshore transient groups generally contain <10 (Dahlheim et al. 1982; Jefferson et al. 2008). Off Costa Rica, May-Collado et al. (2005) reported that the mean group size (3.5) was the smallest among the delphinids seen, based on sightings during 1979–2001. For the ETP, Ferguson et al. (2006b) reported a mean group size of 5.5, and Jackson et al. (2008) reported a mean group size of 8.1 (n = 15). The maximum depth to which seven tagged free-ranging killer whales dove off B.C. was 228 m, but only an average of 2.4 % of their time was spent below 30 m (Baird et al. 2003).

Killer whales are found throughout the ETP (Pitman and Ballance 1992; Wade and Gerrodette 1993), but are most densely distributed near the coast from 35°N to 5°S (Dahlheim et al. 1982). Dahlheim et al. (1982) reported the occurrence of a cluster of sightings at two offshore locations in the ETP. One location was bounded by 7–14°N and 127–139°W, and the other was within a band between the equator and 5°N and from the Galápagos Islands to 115°W; both are well to the west of the proposed survey area.

Killer whales are rare in the proposed survey area. May-Collado et al. (2005) reported seven sightings of 25 animals in Costa Rica waters in 1979–2001; two of the seven sightings occurred nearshore of the west coast of Osa Peninsula. Jackson et al. (2008) reported one sighting of killer whales in the proposed survey area during surveys in July–December 2006. None were reported near the proposed survey area during surveys in 2003 (Jackson et al. 2004). Rasmussen et al. (2004) reported three sightings in annual surveys (1996–2003) off Costa Rica.

No killer whales were detected during L-DEO seismic surveys off Costa Rica or Nicaragua in November–December 2004 or February–March 2008 (Holst et al. 2005a; Holst and Smultea 2008).

Short-finned Pilot Whale (*Globicephala macrorhynchus*)

The short-finned pilot whale typically inhabits pelagic tropical and warm temperate waters of ~1000-m depth near the continental shelf edge but also slope waters (Davis et al. 1998; Jefferson et al. 2008). It is generally nomadic, but resident populations have been reported in certain locations, including Hawaii and California (Olson and Reilly 2002). The abundance of pilot whales in the ETP for 1998–2000 was estimated at 589,315 (Gerrodette and Forcada 2002).

Pilot whales have a wide distribution throughout the ETP, but are most abundant in cold waters where upwelling occurs (Wade and Gerrodette 1993). Polacheck (1987) reported that encounter rates for pilot whales in the ETP were highest inshore; offshore concentrations may also occur, but at lower densities. Pilot whales are usually seen in groups of 20–90, although groups of several hundred are also

seen (Olson and Reilly 2002; Jefferson et al. 2008). May-Collado et al. (2005) reported a mean group size of 14.2 in Costa Rica based on sightings during 1979–2001. For the ETP, Wade and Gerrodette (1993) and Ferguson et al. (2006b) reported a mean group size of 18, and Jackson et al. (2008) reported a mean group size of 18.0 (n = 57). Pilot whales outfitted with time-depth recorders dove to depths of up to 828 m, although most of their time was spent above depths of 7 m (Heide-Jørgensen et al. 2002). The species' maximum recorded dive depth is 971 m (Baird pers. comm. in DoN 2005).

Short-finned pilot whales are common in the proposed survey area. May-Collado et al. (2005) reported 68 sightings of 967 animals off Costa Rica in 1979–2001. Numerous sightings were made within ~200 km and least 2 sightings were within ~50 km of the proposed survey area (May-Collado et al. 2005). Jackson et al. (2004, 2008) reported one and three sightings of short-finned pilot whales within ~200 km of the proposed survey area during July–December surveys in 2003 and 2006, respectively.

During L-DEO seismic surveys off Costa Rica and Nicaragua, one group of short-finned pilot whales was identified near proposed survey area in waters ~1000 m deep, and one group was identified near the project area in waters <2000 m deep in November–December 2004 and February–March 2008, respectively (Holst et al. 2005a; Holst and Smultea 2008).

(3) Pinnipeds

Six species of pinnipeds are known to occur in the ETP: the California sea lion (*Zalophus californianus*), South American sea lion (*Otaria flavescens*), Galápagos sea lion (*Zalophus wolfebaeki*), Galápagos fur seal (*Arctocephalus galapagoensis*), Guadalupe fur seal (*A. townsendi*), and South American fur seal (*A. australis*). Of the six species, two have the potential to occur within the survey area, although any occurrence would be rare as they are vagrants to the area.

The California sea lion is listed as **Least Concern** on the 2010 IUCN Red List of Threatened Species (IUCN 2010) and listed in CITES Appendix II (UNEP-WCMC 2010). Its normal southernmost range is considerably north of the proposed survey area. However, the California sea lion has been documented off western Costa Rica on at least seven occasions including, from north to south, on the Nicoya and Osa peninsulas, in Golfo Dulce, and at Isla del Cocos (Acevedo-Gutiérrez 1994, 1996; Cubero-Pardo and Rodríguez 1999; Rodríguez-Herrera et al. 2002; May-Collado 2009).

The California sea lion is normally distributed from southern Mexico north to southwestern Canada and is considered as the subspecies *Z. c. californianus* (other subspecies are found on the Galápagos Islands and in Japan, although the latter is likely extinct). The breeding areas of the California sea lion are on islands located in southern California, western Baja California, and the Gulf of California. Although encounters with the species are possible in the proposed survey area, it is unlikely that it would be seen there. No pinnipeds were observed off Costa Rica during L-DEO seismic surveys in the ETP in November–December 2004 or February–March 2008 (Holst et al. 2005a; Holst and Smultea 2008). Similarly, Jackson et al. (2004, 2008) did not encounter any pinnipeds in the proposed survey area during surveys in the ETP.

The Galápagos sea lion, listed as **Endangered** on the 2010 IUCN Red List of Threatened Species (IUCN 2010) and listed in CITES Appendix II (UNEP-WCMC 2010), generally occurs around the Galápagos Islands. Galápagos sea lions are seen occasionally at Isla del Coco, an island 500 km southwest of Costa Rica (Acevedo-Gutiérrez 1994; Capella et al. 2002; Palacios 1996b; Palacios et al. 1997). Based on available data, it is unlikely that this species would occur in the proposed survey area.

No encounters with pinnipeds are expected during the proposed survey and no takes are requested.

Seabirds

Two seabird species of conservation concern, the California least tern (*Sternula antillarum browni*) and the Galápagos petrel (*Pterodroma phaeopygia*), are known to occur in or near the proposed study area off Costa Rica. However, only the California least tern is listed under the ESA.

(1) California Least Tern

The California least tern has a limited breeding range extending from southern California to northern Mexico. It nests in colonies on sandy beaches with little vegetation. The California least tern is suspected to winter in South America; fall migrations generally start at the end of July or beginning of August (USFWS 2006). In Costa Rica, least terns are common during fall and spring migration (Stiles and Skutch 1989).

The California least tern is currently listed as **Endangered** under the U.S. ESA, because of a loss of habitat (Craig 1971 in Marschalek 2009). However, in 2006, the USFWS recommended a downlisting to **threatened** because of an increase in the population from 2800 to 7100 pairs between 1995 and 2005 (USFWS 2006). In 2008, there were an estimated 6998–7698 breeding pairs (Marschalek 2009). But although the population has been increasing, chick mortality is still a concern (Marschalek 2006).

(2) Galápagos Petrel

The Galápagos petrel is considered **Critically Endangered** by the IUCN; it is not listed under the U.S. ESA, as its range does not extend into the U.S. This species is endemic to the Galápagos Islands. Although these birds only breed in burrows and other cavities in the highlands of the Galápagos, they forage around the islands, and may travel to nearshore areas along the coast of Mexico, Central America, and South America (BirdLife International 2010). The population declined drastically up until the 1980s because of introduced predators and agricultural activities (Cruz and Cruz 1987). Population estimates for 2008 are 10,000–19,999 mature individuals, but this population still appears to be declining (BirdLife International 2010).

Sea Turtles

Of the world's seven species of sea turtles, five could be found in the proposed study area: the leatherback, loggerhead, green, hawksbill, and olive ridley turtles. Some nesting beaches occur near the proposed survey area, but the biggest nesting beaches (e.g., Playa Grande and Playa Langosta) are located on the Nicoya Peninsula >150 km to the north. Most leatherbacks nest on the Nicoya Peninsula, most green turtles nest in Mexico, and the largest nesting concentrations of olive ridley turtles occur in southern Mexico and northern Costa Rica. No major nesting sites for hawksbill turtles occur on the Pacific coast of Central America, and loggerheads do not nest in the eastern Pacific. Near the proposed survey area, olive ridley and hawksbill turtles nesting sites are found in the Parque Nacional Marino Ballena (Costa Rica 2010), green, olive ridley, hawksbill, and leatherback turtles nest on the beaches of the Parque Nacional Corcovado (CRTTB 2010b), and olive ridley turtles also nest at the Playa Hermosa Wildlife Refuge (CCSA 2005).

Mostly foraging or migrating individuals would be encountered during the proposed survey. The survey is scheduled after the peak nesting periods for leatherbacks (October–March), green turtles (October–November), and olive ridleys (September–December). Given incubation periods of ~2 months, it is likely that only leatherback hatchlings could be encountered, and numbers would be small because of the distance from the beaches where most nesting takes place.

(1) Leatherback Turtle (*Dermochelys coriacea*)

The leatherback turtle is listed as *Endangered* under the U.S. ESA and *Critically Endangered* on the 2010 IUCN Red List of Threatened Species (IUCN 2010), and is listed in CITES Appendix I (UNEP-WCMC 2010). The world leatherback turtle population is estimated at 35,860 females (Spotila 2004).

The leatherback is the largest and most widely distributed sea turtle, ranging far from its tropical and subtropical breeding grounds (Plotkin 2003). Frair et al. (1972) and Greer et al. (1973) noted that leatherback turtles have evolved physiological and anatomical adaptations to cold water, allowing them to venture into higher latitudes than other species of sea turtle. After nesting, female turtles typically migrate from tropical waters to temperate areas, where higher densities of jellyfish occur in the summer (NMFS 2010a). Leatherbacks tend to feed in areas of high productivity, such as current fronts and upwelling areas, along continental margins, and in archipelagic waters (Morreale et al. 1994; Lutcavage 1996). Leatherbacks feed mainly on jellyfish, tunicates, and other epipelagic soft-bodied invertebrates (Davenport and Balazs 1991). Predation on squid is inferred by incidental, long-line catches with squid used as bait (Skillman and Balazs 1992).

Leatherbacks are highly pelagic and are known to swim more than 11,000 km each year (Eckert 1998). This species is one of the deepest divers in the ocean, with dives deeper than 4000 m (Spotila 2004). The leatherback dives continually and spends short periods of time on the surface between dives (Eckert et al. 1986; Southwood et al. 1998). Off St. Croix, six inter-nesting females dove to a mean depth of 61.6 m for an average of 9.9 min/dive, and post-dive surfacing intervals averaged 4.9 min (Eckert et al. 1989). During shallow-water diving in the South China Sea, typical dive durations averaged 6.9–14.5 min, with a maximum of 42 min (Eckert et al. 1996). Off central California, leatherbacks dove to 20–30 m with a maximum of 92 m, corresponding to the vertical distribution of their prey, and mean dive and surface durations were 2.9 and 2.2 min, respectively (Harvey et al. 2006). During migrations or long distance movements, leatherbacks maximize swimming efficiency by traveling within 5 m of the surface (Eckert 2002).

In the Pacific Ocean, leatherbacks nest along the west coast of Mexico and in Central America, particularly in Costa Rica, from October to March (Spotila 2004). Until recently, Mexico had the highest concentration of nesting turtles (NMFS and USFWS 1998a). However, a significant decline in the numbers of nesting leatherbacks in the Pacific has been reported, with possible extirpation of some nesting groups in the eastern Pacific (Spotila et al. 2000). Females may lay up to nine clutches in a season (although six is more common), and the incubation period is 58–65 days. At Playa Grande, Costa Rica, and in French Guiana, the mean internesting period is 9 days (Lux et al. 2003). Hatchling leatherbacks are pelagic, but nothing is known about their distribution for the first four years (Musick and Limpus 1997).

On the Pacific coast of Costa Rica, the largest number of leatherbacks nest at Playa Grande in Las Baulas National Park (Spotila 2004), followed by Playa Naranjo in Santa Rosa National Park (Yañez et al. 2010). Smaller numbers of leatherbacks also nest at Playa Langosta in Las Baulas National Park and at Rio Oro on the Osa Peninsula. The number of leatherback turtles nesting in Las Baulas National Park declined steadily during the 1990s, from ~1500 females during the 1988–89 nesting season, to ~800 in 1990–91 and 1991–92, 193 in 1993–94 (Williams et al. 1996) and 117 in 1998–99 (Spotila 2000 *in* NMFS 2002). Spotila (2004) reported that between 59 and 435 leatherbacks nest at Las Baulas each year depending on the El Niño–La Niña cycle.

Post-nesting adult leatherbacks appear to migrate along bathymetric contours from 200 to 3500 m (Morreale et al. 1994). Telemetry studies suggest that post-nesting females from eastern Pacific populations in Mexico and Central America migrated southward to equatorial and Southern Hemisphere

waters (Dutton et al. 2006). Female leatherbacks tagged at Playa Grande migrated southward along a well-defined corridor from Costa Rica past the Galápagos, and then dispersed south of 10°S (Shillinger et al. 2010).

During L-DEO marine seismic surveys in the ETP off Honduras, Nicaragua, and Costa Rica in November–December 2004 and off Nicaragua and Costa Rica in March–April 2008, only one of ~179 turtle sightings and none of 341 turtle sightings, respectively, was identified as a leatherback turtle (Holst et al. 2005a; Holst and Smultea 2008).

(2) Loggerhead Turtle (*Caretta caretta*)

The loggerhead turtle is listed as *Threatened* under the U.S. ESA throughout its range and *Endangered* on the 2010 IUCN Red List of Threatened Species (IUCN 2010), and is listed in CITES Appendix I (UNEP-WCMC 2010). The global population of loggerhead turtles is estimated at 43,320–44,560 nesting females (Spotila 2004). Numbers are declining primarily because of incidental capture in various fisheries (NMFS and USFWS 1998b; NMFS 2010b).

The loggerhead is a widely distributed species, occurring in coastal tropical and subtropical waters around the world. On average, loggerhead turtles spend over 90% of their time underwater (Byles 1988; Renaud and Carpenter 1994). In the North Pacific Ocean, two loggerheads tagged with satellite-linked depth recorders spent about 40% of their time in the top meter and virtually all their time shallower than 100 m; 70% of the dives were no deeper than 5 m (Polovina et al. 2003). Routine dives for adult female loggerheads are typically to depths <50 m, but maximum dive depths of 211–233 m have been reported (Sakamoto et al. 1990; 1993). Mean dive duration can range from 4 to 172 min and appears to be longer during the winter (Byles 1988; Sakamoto et al. 1990; Renaud and Carpenter 1994). Juveniles spend more time on the surface in deep, offshore areas than in shallow, nearshore waters (Lutcavage and Lutz 1997). Ten juvenile pelagic-stage loggerheads tagged off Madeira Island generally made shallow dives, spending most of the time near the surface, and ~20% of their time was spent at 10–25 m (Dellinger and Freitas 2000). Occasionally, dives were deep for long periods; maximum depths for the 10 turtles were 86–196 m, and maximum times were 90–240 min (Dellinger and Freitas 2000).

Nesting in the Pacific Ocean basin is restricted to the western region. The two main nesting stocks in Japan and Australia/New Caledonia have been identified as genetically distinct (Bowen et al. 1995). Hatchling loggerheads in the Pacific Ocean are thought to have a pelagic stage similar to that in the Atlantic (NMFS and USFWS 1998b). Telemetry studies, mark-recapture data, demographics, diet analysis, and oceanographic patterns suggest that North Pacific loggerhead turtles, mostly hatched in southern Japan, are transported as hatchlings and juveniles to the North Pacific by the Kuroshio Current (Kamezaki, pers. comm. in Nichols et al. 2000). Between the ages of 7 and 12, juvenile loggerheads move to nearshore foraging areas (NMFS 2010b). For example, some loggerheads seen feeding along Baja California have been tracked genetically and by satellite telemetry; these have been shown to come from Japanese breeding sites (Bowen et al. 1995; Resendiz et al. 1998; Nichols et al. 2000). Apparently, loggerheads gather along the Baja coast to capitalize on an abundance of nutrient-rich prey, like pelagic red crabs, that accumulate in local zones of upwelling (Bowen et al. 1995). Once sexually mature, loggerheads depart feeding grounds near California and begin their long, slow journey back to natal beaches in Japan (Bowen et al. 1995; Nichols et al. 2000). Recently, adult loggerheads and mating behavior have been reported in the waters of the Pacific coast of Baha California Sur (Rossi et al. 2010).

Traveling <2 km/h, loggerheads appear to migrate along nutrient-rich, oceanic fronts in the North Pacific (Nichols et al. 2000; Polovina et al. 2000; Kobayashi et al. 2008). This preferred route, counter the North Pacific Current and past the Hawaiian Islands, returns loggerheads to pelagic waters where they

are susceptible as bycatch to local longliners seeking tuna, swordfish, and sharks (Lewison et al. 2004; Yokota et al. 2006). After returning to Japan to breed, adult loggerheads tend to remain in the western Pacific, migrating annually between nesting beaches in Japan and feeding grounds in the South and East China Seas (Sato et al. 1997; Nichols 2005; Parker et al. 2005). All loggerheads in the North Pacific originate at Japanese nesting beaches (Hatase et al. 2002).

In the eastern Pacific, the loggerhead's distribution ranges from Alaska to Chile (NMFS and USFWS 1998b). Sightings are typically confined to the summer months in the eastern Pacific, peaking in July–September off southern California and southwestern Baja California (Stinson 1984; NMFS and USFWS 1998b). During L-DEO seismic surveys in the ETP off Honduras, Nicaragua, and Costa Rica in November–December 2004 and off Nicaragua and Costa Rica in March–April 2008, none of the ~179 and 341 turtle sightings, respectively, was identified as a loggerhead turtle (Holst et al. 2005a; Holst and Smultea 2008).

(3) Green Turtle (*Chelonia mydas*)

The green turtle is listed as *Threatened* under the U.S. ESA throughout its Pacific range, except for the *Endangered* population nesting on the Pacific coast of Mexico. It is listed as *Endangered* on the 2010 IUCN Red List of Threatened Species (IUCN 2010) and is listed in CITES Appendix I (UNEP-WCMC 2010). The worldwide green turtle population is estimated at ~110,000–150,000 nesting females per year (NMFS and USFWS 2007a). The worldwide population has declined 50–70% since 1900 (Spotila 2004).

Green turtles may undertake long migrations from foraging areas to nesting sites (NMFS 2010c). Mature females typically show nest-site fidelity and return to their natal beaches to nest repeatedly (NMFS 2010c). Hatchlings swim to offshore areas where they are epipelagic (surface dwelling in the open sea) for several years (NMFS 2010c). Subsequently, most green turtles travel to nearshore areas where they live in bays and along protected shorelines, and feed during the day on seagrass and algae (Bjorndal 1982). While in oceanic habitats near Hawaii, green turtles feed on jellyfish and other pelagic prey (Parker and Balazs 2008). Juvenile and sub-adult green turtles may travel thousands of kilometers before they return to breeding and nesting grounds (Carr et al. 1978). Juveniles have been observed by research vessels operating thousands of miles from land in the southeastern Pacific Ocean (NMFS and USFWS 1998c).

Green turtles typically make dives shallower than 30 m (Hochscheid et al. 1999; Hays et al. 2000), although they have been observed to dive to depths of 73–110 m in the eastern Pacific Ocean (Berkson 1967 *in* Lutcavage and Lutz 1997) to 164.5 m off Japan (Matsuzawa pers. comm. *in* DoN 2005). Green turtles spend most of their time feeding or resting underwater (Rice et al. 2000). Three subadult green turtles tagged in Hawaii spent averages of 9, 14, and 19 h/day foraging at depths <2 m, and 12, 10, and 5 h/day in resting dives at mean depths of 7–13 m (maximum depths were 16–40 m). Foraging dive durations were <10 min, and resting dive durations were 59, 44, and 24 min (Davis et al. 2000; Rice et al. 2000). The maximum dive time recorded for a juvenile green turtle off Hawaii was 66 min, and routine dive times were 9–23 min (Brill et al. 1995). Six green turtles tagged in the Gulf of California spent 6% of their time within 2 m of the surface, 39% of their time in resting dives to a mean of 10 m, and the remainder diving to depths up to ~50 m (Seminoff et al. 2005). During a breeding migration in the Hawaiian Islands, three adult green turtles made shallow (1–4 m) and short (1–18 min) dives during the day and deeper (mean maximum of 35–55 m) and longer (35–44 min) dives at night (Rice and Balazs 2010).

In the eastern Pacific, green turtles nest at several locations on the Mexican mainland, Central America, and off the coast of Colombia and Ecuador. The primary nesting grounds are located in Michoacán, Mexico, with an estimated 1395 nesting females per year, and the Galápagos Islands, Ecuador, with an estimated 1650 nesting females per year (NMFS and USFWS 2007a). Nesting occurs in Michoacán between August and January, with a peak in October–November, and on the Galápagos Islands between December and May with a peak in February–March (Alvarado and Figueroa 1995; Green and Ortiz-Crespo 1995). In Central America, small numbers of green turtles nest at major nesting sites of other species, primarily olive ridleys, in Nicaragua (Ocean Resources Foundation 1998) and in Costa Rica (NMFS and USFWS 1998c). Green turtles also nest in very small numbers in El Salvador (Hasbún and Vásquez 1999).

In the eastern Pacific, this species has been documented as far north as southern Alaska and as far south as Desolation Island, Chile (NMFS and USFWS 1998c). Based on tag-recovery information, the feeding grounds of the Mexican breeding population are restricted to Mexico and Central America, whereas the Galápagos breeding population forages from Costa Rica south to Peru (NMFS and USFWS 1998c).

During L-DEO seismic surveys in the ETP off Honduras, Nicaragua, and Costa Rica in November–December 2004 and off Nicaragua and Costa Rica in March–April 2008, 2 of the ~179 turtle sightings and 5 of 341 turtle sightings, respectively, were identified as green turtles (Holst et al. 2005a; Holst and Smultea 2008).

(4) Hawksbill Turtle (*Eretmochelys imbricata*)

The hawksbill turtle is listed as *Endangered* under the U.S. ESA and *Critically Endangered* on the 2010 IUCN Red List of Threatened Species (IUCN 2010), and is listed in CITES Appendix I (UNEP-WCMC 2010). The hawksbill is a solitary nester, and population trends or estimates are difficult to determine. Nonetheless, a minimum of 20,000–26,000 (<10% of the number that nested a century ago) females are thought to nest annually (Spotila 2004). As females nest once every three years, the total adult female population is estimated at 60,000–78,000 (Spotila 2004). NMFS and USFWS (2007b) provided an estimate of 21,212–28,138 nesting females.

Hawksbill turtles are typically associated with clear, coastal waters of mainland and island shelves, seagrass pastures, and coral reefs (Márquez 1990). Hawksbills have very long routine dive times. For inter-nesting females in St. Croix, Starbird et al. (1999) reported dive times averaging 56 min, a maximum dive time of 73.5 min, and an average surface interval of ~2 min. Average day and night dive times were 34–65 and 42–74 min, respectively. Based on time-depth recorder studies in Puerto Rico, foraging dives of immature hawksbills were 8.6–14 min to a mean depth of 4.7 m (van Dam and Diez 1996).

Hawksbill turtles most commonly perform short-distance movements between nesting beaches and offshore feeding banks, although long-distance movements are also known (NMFS and USFWS 1998d; 2007b). Post-hatchlings are believed to be pelagic for several years, taking shelter in weed lines around convergence zones; they re-enter coastal waters once they attain a length of ~20–25 cm (NMFS and USFWS 1998d). In the Pacific, the pelagic habitat of hawksbill juveniles is still unknown (NMFS 2010d).

Hawksbill turtles nest on low and high-energy beaches, often sharing high-energy locations with green turtles. No major nesting sites for hawksbill turtles occur on the Pacific coast of Central America, although a few hawksbills are known to nest at the La Flor National Wildlife Refuge in Nicaragua (Ocean Resource Foundation 1998) and at Punta Banco, Caña Blanca, and Playa Caletas in Costa Rica (Gaos et

al. 2006). In a regional review of sea turtle bycatch in the eastern Pacific (Kelez et al. 2010), hawksbill turtles are only mentioned as a secondary species in shrimp trawls off Costa Rica.

During L-DEO seismic surveys in the ETP off Honduras, Nicaragua, and Costa Rica in November–December 2004 and off Nicaragua and Costa Rica in March–April 2008, none of the ~179 and 341 turtle sightings, respectively, was identified as a hawksbill turtle (Holst et al. 2005a; Holst and Smultea 2008).

(5) Olive Ridley Turtle (*Lepidochelys olivacea*)

The olive ridley is the most abundant sea turtle in the world, although its population is in serious decline worldwide (Spotila 2004). Olive ridley populations on the Pacific coast of Mexico are listed as **Endangered** under the U.S. ESA; all other populations are listed as **Threatened**. The olive ridley is categorized as **Vulnerable** on the 2010 IUCN Red List of Threatened Species (IUCN 2010) and is listed in CITES Appendix I (UNEP-WCMC 2010). The worldwide population of olive ridley turtles is estimated at ~2 million nesting females (Spotila 2004).

The olive ridley has a large range in tropical and subtropical regions in the Pacific, Indian, and South Atlantic oceans, and is generally found between 40°N and 40°S. The olive ridley turtle is primarily a pelagic species (NMFS 2010e), capable of feeding at considerable depths (80–300 m), although ~90% of their time is spent at depths <100 m (Eckert et al. 1986; Polovina et al. 2003). In the ETP, at least 25% of their total dive time is spent in the permanent thermocline, located at 20–100 m (Parker et al. 2003). Olive ridleys spend considerable time at the surface basking, presumably in an effort to speed their metabolism and digestion after a deep dive (Spotila 2004). In the North Pacific Ocean, two olive ridleys tagged with satellite-linked depth recorders spent about 20% of their time in the top meter and about 10% of their time deeper than 100 m; 70% of the dives were no deeper than 5 m (Polovina et al. 2003).

Olive ridleys are primarily carnivorous, feeding on crabs, jellyfish, and fish eggs, resorting to algae when prey is scarce. They are often associated with flotsam in high seas, possibly feeding on associated fish and invertebrates (Pitman 1992). They are generally thought to be surface feeders, but have also been caught in trawls at depths of 80–110 m (NMFS and USFWS 1998e, 2007c).

In the eastern Pacific, the largest nesting concentrations occur in southern Mexico and northern Costa Rica, with stragglers nesting as far north as southern Baja California (Fritts et al. 1982) and as far south as Peru (Brown and Brown 1982; Kelez et al. 2009). Most olive ridleys nest synchronously in huge colonies called “arribadas”, with several thousand females nesting at the same time; others nest alone, out of sequence with the arribada (Kalb and Owens 1994). The arribadas usually last from three to seven nights (Aprill 1994). Most females lay two clutches of eggs with an inter-nesting period of 1–2 months (Plotkin et al. 1994b). Incubation usually takes from 50 to 60 days (NMFS and USFWS 1998e). Radio-tracking studies showed that females that nested in arribadas remain within 5 km of the beach most of the time during the inter-nesting period (Kalb and Owens 1994). Olive ridleys nest throughout the year in the eastern Pacific with peak months, including major arribadas, occurring from September through December (NMFS and USFWS 1998e).

Females and males begin to aggregate near their nesting beaches two months before the nesting season (Arenas and Hall 1992), and most mating likely occurs near the nesting beaches (Márquez et al. 1976 in NMFS and USFWS 1998e). However, Pitman (1990) observed olive ridleys mating at sea, as far as 1850 km from the nearest mainland, during every month of the year except March and December. There was a sharp peak in offshore mating activity during August and September, corresponding with peak breeding activity in mainland populations. Of 324 olive ridleys that were captured during surveys in the ETP (including offshore waters to 155°W), 50 were involved in mating (Kopitsky et al. 2002).

Outside of the breeding season, the turtles disperse, but little is known of their behavior. The post-nesting migration routes of olive ridleys tracked via satellite from Costa Rica traversed thousands of kilometers of deep oceanic waters ranging from Mexico to Peru, and more than 3000 km out into the central Pacific Ocean (Plotkin et al. 1994a). Aggregations of turtles¹, sometimes >100 individuals, have been observed as far offshore as 120°W, ~3000 km from shore (Arenas and Hall 1991). However, movements of turtles tagged in Central America were highly dissociated from each other, indicating that olive ridleys are “nomadic epipelagic foragers that prey on patchily distributed food” (Morreale et al. 2007:220). Neither males nor females migrate to one specific foraging area, but exhibit a nomadic movement pattern and occupy a series of feeding areas in oceanic waters (Plotkin et al. 1994a,b). The olive ridley is the most abundant sea turtle in the open ocean waters of the ETP (Pitman 1990), where it can be seen mating or foraging in groups exceeding 1000 individuals called flotillas (Pitman 1990, 1991; Arenas and Hall 1992; Kopitsky et al. 2000).

In the ETP, olive ridleys range from the U.S. to central Chile, but are most common off Mexico and Central America. Among longline fisheries in the ETP, olive ridleys were the most frequent bycatch off northern Peru, Ecuador, and Central America; bycatch rates there were higher than those further south, but lower than those off Mexico. Among gillnet fisheries, olive ridleys were the species most frequently captured during shrimp trawling off Costa Rica (Kelez et al. 2010).

The olive ridley turtle was the most common species encountered during L-DEO seismic surveys in the ETP off Honduras, Nicaragua, and Costa Rica in November–December 2004 and off Nicaragua and Costa Rica in March–April 2008; 84 of the ~179 turtle sightings and 204 of 341 turtle sightings, respectively, were identified as olive ridleys (Holst et al. 2005a; Holst and Smultea 2008).

IV. ENVIRONMENTAL CONSEQUENCES

Proposed Action

(1) Direct Effects and Their Significance

The material in this section includes a summary of the anticipated effects (or lack thereof) on marine mammals and sea turtles of the airgun system to be used by L-DEO. A more detailed review of airgun effects on marine mammals appears in Appendix B. That Appendix is similar to corresponding parts of previous EAs and associated IHA applications concerning other L-DEO seismic surveys since 2003, but was updated in 2008. Appendix C contains a general review of the effects of seismic pulses on sea turtles. This section (along with Appendix B) also includes a discussion of the potential impacts of operations by L-DEO’s MBES and SBP.

Finally, this section includes estimates of the numbers of marine mammals that could be affected by the proposed activity during the seismic survey scheduled to occur during April–May 2011. A description of the rationale for L-DEO’s estimates of the numbers of exposures to various received sound levels that could occur during the planned seismic program is also provided.

(a) Summary of Potential Effects of Airgun Sounds

The effects of sounds from airguns could include one or more of the following: tolerance, masking of natural sounds, behavioral disturbance, and at least in theory, temporary or permanent hearing impairment, or non-auditory physical or physiological effects (Richardson et al. 1995; Gordon et al. 2004;

¹ Of sea turtles observed at sea, 75% were olive ridleys.

Nowacek et al. 2007; Southall et al. 2007). Permanent hearing impairment, in the unlikely event that it occurred, would constitute injury, but temporary threshold shift (TTS) is not an injury (Southall et al. 2007). Although the possibility cannot be entirely excluded, it is unlikely that the project would result in any cases of temporary or especially permanent hearing impairment, or any significant non-auditory physical or physiological effects. Some behavioral disturbance is expected, but this would be localized and short-term.

Tolerance.—Numerous studies have shown that pulsed sounds from airguns are often readily detectable in the water at distances of many kilometers. For a summary of the characteristics of airgun pulses, see Appendix B (3). Several studies have shown that marine mammals at distances more than a few kilometers from operating seismic vessels often show no apparent response—see Appendix B (5). That is often true even in cases when the pulsed sounds must be readily audible to the animals based on measured received levels and the hearing sensitivity of that mammal group. Although various baleen whales and toothed whales, and (less frequently) pinnipeds have been shown to react behaviorally to airgun pulses under some conditions, at other times mammals of all three types have shown no overt reactions. The relative responsiveness of baleen and toothed whales are quite variable. During active seismic surveys, sea turtles typically do not show overt reactions to airgun pulses.

Masking.—Masking effects of pulsed sounds (even from large arrays of airguns) on marine mammal calls and other natural sounds are expected to be limited, although there are very few specific data on this. Because of the intermittent nature and low duty cycle of seismic pulses, animals can emit and receive sounds in the relatively quiet intervals between pulses. However, in exceptional situations, reverberation occurs for much or all of the interval between pulses (e.g., Simard et al. 2005; Clark and Gagnon 2006) which could mask calls. Some baleen and toothed whales are known to continue calling in the presence of seismic pulses, and their calls usually can be heard between the seismic pulses (e.g., Richardson et al. 1986; McDonald et al. 1995; Greene et al. 1999; Nieu Kirk et al. 2004; Smultea et al. 2004; Holst et al. 2005a,b, 2006; Dunn and Hernandez 2009). However, Clark and Gagnon (2006) reported that fin whales in the northeast Pacific Ocean went silent for an extended period starting soon after the onset of a seismic survey in the area. Similarly, there has been one report that sperm whales ceased calling when exposed to pulses from a very distant seismic ship (Bowles et al. 1994). However, more recent studies found that they continued calling in the presence of seismic pulses (Madsen et al. 2002; Tyack et al. 2003; Smultea et al. 2004; Holst et al. 2006; Jochens et al. 2008). Dolphins and porpoises commonly are heard calling while airguns are operating (e.g., Gordon et al. 2004; Smultea et al. 2004; Holst et al. 2005a,b; Potter et al. 2007). The sounds important to small odontocetes are predominantly at much higher frequencies than are the dominant components of airgun sounds, thus limiting the potential for masking. In general, masking effects of seismic pulses are expected to be minor, given the normally intermittent nature of seismic pulses. Masking effects on marine mammals are discussed further in Appendix B (4). We are not aware of any information concerning masking of hearing in sea turtles.

Disturbance Reactions.—Disturbance includes a variety of effects, including subtle to conspicuous changes in behavior, movement, and displacement. Based on NMFS (2001, p. 9293), NRC (2005), and Southall et al. (2007), we assume that simple exposure to sound, or brief reactions that do not disrupt behavioral patterns in a potentially significant manner, do not constitute harassment or “taking”. By potentially significant, we mean “in a manner that might have deleterious effects to the well-being of individual marine mammals or their populations”.

Reactions to sound, if any, depend on species, state of maturity, experience, current activity, reproductive state, time of day, and many other factors (Richardson et al. 1995; Wartzok et al. 2004; Southall et al. 2007; Weilgart 2007). If a marine mammal does react briefly to an underwater sound by changing

its behavior or moving a small distance, the impacts of the change are unlikely to be significant to the individual, let alone the stock or population. However, if a sound source displaces marine mammals from an important feeding or breeding area for a prolonged period, impacts on individuals and populations could be significant (e.g., Lusseau and Bejder 2007; Weilgart 2007). Given the many uncertainties in predicting the quantity and types of impacts of noise on marine mammals, it is common practice to estimate how many mammals would be present within a particular distance of industrial activities and/or exposed to a particular level of industrial sound. In most cases, this approach likely overestimates the numbers of marine mammals that would be affected in some biologically-important manner.

The sound criteria used to estimate how many marine mammals might be disturbed to some biologically-important degree by a seismic program are based primarily on behavioral observations of a few species. Detailed studies have been done on humpback, gray, bowhead, and sperm whales. Less detailed data are available for some other species of baleen whales, small toothed whales, and sea otters, but for many species there are no data on responses to marine seismic surveys.

Baleen Whales

Baleen whales generally tend to avoid operating airguns, but avoidance radii are quite variable. Whales are often reported to show no overt reactions to pulses from large arrays of airguns at distances beyond a few kilometers, even though the airgun pulses remain well above ambient noise levels out to much longer distances. However, as reviewed in Appendix B (5), baleen whales exposed to strong noise pulses from airguns often react by deviating from their normal migration route and/or interrupting their feeding and moving away. In the cases of migrating gray and bowhead whales, the observed changes in behavior appeared to be of little or no biological consequence to the animals. They simply avoided the sound source by displacing their migration route to varying degrees, but within the natural boundaries of the migration corridors.

Studies of gray, bowhead, and humpback whales have shown that seismic pulses with received levels of 160–170 dB re 1 $\mu\text{Pa}_{\text{rms}}$ seem to cause obvious avoidance behavior in a substantial fraction of the animals exposed (Richardson et al. 1995). In many areas, seismic pulses from large arrays of airguns diminish to those levels at distances ranging from 4 to 15 km from the source. A substantial proportion of the baleen whales within those distances may show avoidance or other strong behavioral reactions to the airgun array. Subtle behavioral changes sometimes become evident at somewhat lower received levels, and studies summarized in Appendix B (5) have shown that some species of baleen whales, notably bowhead and humpback whales, at times show strong avoidance at received levels lower than 160–170 dB re 1 $\mu\text{Pa}_{\text{rms}}$.

Responses of *humpback whales* to seismic surveys have been studied during migration, on summer feeding grounds, and on Angolan winter breeding grounds; there has also been discussion of effects on the Brazilian wintering grounds. McCauley et al. (1998, 2000a) studied the responses of humpback whales off Western Australia to a full-scale seismic survey with a 16-airgun, 2678-in³ array, and to a single 20-in³ airgun with source level 227 dB re 1 $\mu\text{Pa}\cdot\text{m}_{\text{p-p}}$. McCauley et al. (1998) documented that avoidance reactions began at 5–8 km from the array, and that those reactions kept most pods ~3–4 km from the operating seismic boat. McCauley et al. (2000a) noted localized displacement during migration of 4–5 km by traveling pods and 7–12 km by more sensitive resting pods of cow-calf pairs. Avoidance distances with respect to the single airgun were smaller but consistent with the results from the full array in terms of the received sound levels. The mean received level for initial avoidance of an approaching airgun was 140 dB re 1 $\mu\text{Pa}_{\text{rms}}$ for humpback pods containing females, and at the mean closest point of approach (CPA) distance the received level was 143 dB re 1 $\mu\text{Pa}_{\text{rms}}$. The initial avoidance response generally occurred at distances of 5–8 km from the airgun array and 2 km from the single airgun.

However, some individual humpback whales, especially males, approached within distances of 100–400 m, where the maximum received level was 179 dB re 1 $\mu\text{Pa}_{\text{rms}}$.

Humpback whales on their summer feeding grounds in southeast Alaska did not exhibit persistent avoidance when exposed to seismic pulses from a 1.64-L (100-in³) airgun (Malme et al. 1985). Some humpbacks seemed “startled” at received levels of 150–169 dB re 1 μPa . Malme et al. (1985) concluded that there was no clear evidence of avoidance, despite the possibility of subtle effects, at received levels up to 172 re 1 μPa on an approximate rms basis.

It has been suggested that South Atlantic humpback whales wintering off Brazil may be displaced or even strand upon exposure to seismic surveys (Engel et al. 2004). The evidence for this was circumstantial and subject to alternative explanations (IAGC 2004). Also, the evidence was not consistent with subsequent results from the same area of Brazil (Parente et al. 2006), or with direct studies of humpbacks exposed to seismic surveys in other areas and seasons. After allowance for data from subsequent years, there was “no observable direct correlation” between strandings and seismic surveys (IWC 2007:236).

There are no data on reactions of *right whales* to seismic surveys, but results from the closely-related *bowhead whale* show that their responsiveness can be quite variable depending on their activity (migrating vs. feeding). Bowhead whales migrating west across the Alaskan Beaufort Sea in autumn, in particular, are unusually responsive, with substantial avoidance occurring out to distances of 20–30 km from a medium-sized airgun source at received sound levels of around 120–130 dB re 1 $\mu\text{Pa}_{\text{rms}}$ [Miller et al. 1999; Richardson et al. 1999; see Appendix B (5)]. However, more recent research on bowhead whales (Miller et al. 2005; Harris et al. 2007) corroborates earlier evidence that, during the summer feeding season, bowheads are not as sensitive to seismic sources. Nonetheless, subtle but statistically significant changes in surfacing–respiration–dive cycles were evident upon analysis (Richardson et al. 1986). In summer, bowheads typically begin to show avoidance reactions at received levels of about 152–178 dB re 1 $\mu\text{Pa}_{\text{rms}}$ (Richardson et al. 1986, 1995; Ljungblad et al. 1988; Miller et al. 2005).

Reactions of migrating and feeding (but not wintering) *gray whales* to seismic surveys have been studied. Malme et al. (1986, 1988) studied the responses of feeding eastern Pacific gray whales to pulses from a single 100-in³ airgun off St. Lawrence Island in the northern Bering Sea. They estimated, based on small sample sizes, that 50% of feeding gray whales stopped feeding at an average received pressure level of 173 dB re 1 μPa on an (approximate) rms basis, and that 10% of feeding whales interrupted feeding at received levels of 163 dB re 1 $\mu\text{Pa}_{\text{rms}}$. Those findings were generally consistent with the results of experiments conducted on larger numbers of gray whales that were migrating along the California coast (Malme et al. 1984; Malme and Miles 1985), and western Pacific gray whales feeding off Sakhalin Island, Russia (Würsig et al. 1999; Gailey et al. 2007; Johnson et al. 2007; Yazvenko et al. 2007a,b), along with data on gray whales off British Columbia (Bain and Williams 2006).

Various species of *Balaenoptera* (blue, sei, fin, and minke whales) have occasionally been reported in areas ensonified by airgun pulses (Stone 2003; MacLean and Haley 2004; Stone and Tasker 2006), and calls from blue and fin whales have been localized in areas with airgun operations (e.g., McDonald et al. 1995; Dunn and Hernandez 2009). Sightings by observers on seismic vessels off the United Kingdom from 1997 to 2000 suggest that, during times of good sightability, sighting rates for mysticetes (mainly fin and sei whales) were similar when large arrays of airguns were shooting vs. silent (Stone 2003; Stone and Tasker 2006). However, these whales tended to exhibit localized avoidance, remaining significantly further (on average) from the airgun array during seismic operations compared with non-seismic periods (Stone and Tasker 2006). In a study off Nova Scotia, Canada, Moulton and Miller (2005) found little difference in sighting rates (after accounting for water depth) and initial sighting distances of balaenopterid whales when airguns were operating vs. silent. However, there were indications that these

whales were more likely to be moving away when seen during airgun operations. Similarly, ship-based monitoring studies of blue, fin, sei and minke whales offshore of Newfoundland (Orphan Basin and Laurentian Sub-basin) found no more than small differences in sighting rates and swim directions during seismic vs. non-seismic periods (Moulton et al. 2005, 2006a,b).

Data on short-term reactions by cetaceans to impulsive noises are not necessarily indicative of long-term or biologically significant effects. It is not known whether impulsive sounds affect reproductive rate or distribution and habitat use in subsequent days or years. However, gray whales have continued to migrate annually along the west coast of North America with substantial increases in the population over recent years, despite intermittent seismic exploration (and much ship traffic) in that area for decades (Appendix A *in* Malme et al. 1984; Richardson et al. 1995; Allen and Angliss 2010). The western Pacific gray whale population did not seem affected by a seismic survey in its feeding ground during a previous year (Johnson et al. 2007). Similarly, bowhead whales have continued to travel to the eastern Beaufort Sea each summer, and their numbers have increased notably, despite seismic exploration in their summer and autumn range for many years (Richardson et al. 1987; Allen and Angliss 2010).

Toothed Whales

Little systematic information is available about reactions of toothed whales to noise pulses. Few studies similar to the more extensive baleen whale/seismic pulse work summarized above and (in more detail) in Appendix B have been reported for toothed whales. However, there are recent systematic studies on sperm whales (e.g., Gordon et al. 2006; Madsen et al. 2006; Winsor and Mate 2006; Jochens et al. 2008; Miller et al. 2009). There is also an increasing amount of information about responses of various odontocetes to seismic surveys based on monitoring studies (e.g., Stone 2003; Smultea et al. 2004; Moulton and Miller 2005; Bain and Williams 2006; Holst et al. 2006; Stone and Tasker 2006; Potter et al. 2007; Hauser et al. 2008; Holst and Smultea 2008; Weir 2008; Barkaszi et al. 2009; Richardson et al. 2009).

Seismic operators and marine mammal observers on seismic vessels regularly see dolphins and other small toothed whales near operating airgun arrays, but in general there is a tendency for most delphinids to show some avoidance of operating seismic vessels (e.g., Goold 1996a,b,c; Calambokidis and Osmek 1998; Stone 2003; Moulton and Miller 2005; Holst et al. 2006; Stone and Tasker 2006; Weir 2008; Richardson et al. 2009; see also Barkaszi et al. 2009). Some dolphins seem to be attracted to the seismic vessel and floats, and some ride the bow wave of the seismic vessel even when large arrays of airguns are firing (e.g., Moulton and Miller 2005). Nonetheless, small toothed whales more often tend to head away, or to maintain a somewhat greater distance from the vessel, when a large array of airguns is operating than when it is silent (e.g., Stone and Tasker 2006; Weir 2008). In most cases the avoidance radii for delphinids appear to be small, on the order of 1 km less, and some individuals show no apparent avoidance. The beluga is a species that (at least at times) shows long-distance avoidance of seismic vessels. Aerial surveys conducted in the southeastern Beaufort Sea during summer found that sighting rates of beluga whales were significantly lower at distances 10–20 km compared with 20–30 km from an operating airgun array, and observers on seismic boats in that area rarely see belugas (Miller et al. 2005; Harris et al. 2007).

Captive bottlenose dolphins and beluga whales exhibited changes in behavior when exposed to strong pulsed sounds similar in duration to those typically used in seismic surveys (Finneran et al. 2000, 2002, 2005). However, the animals tolerated high received levels of sound before exhibiting aversive behaviors.

Results for porpoises depend on species. The limited available data suggest that harbor porpoises show stronger avoidance of seismic operations than do Dall's porpoises (Stone 2003; MacLean and Koski

2005; Bain and Williams 2006; Stone and Tasker 2006). Dall's porpoises seem relatively tolerant of airgun operations (MacLean and Koski 2005; Bain and Williams 2006), although they too have been observed to avoid large arrays of operating airguns (Calambokidis and Osmeck 1998; Bain and Williams 2006). This apparent difference in responsiveness of these two porpoise species is consistent with their relative responsiveness to boat traffic and some other acoustic sources (Richardson et al. 1995; Southall et al. 2007).

Most studies of sperm whales exposed to airgun sounds indicate that the sperm whale shows considerable tolerance of airgun pulses (e.g., Stone 2003; Moulton et al. 2005, 2006a; Stone and Tasker 2006; Weir 2008). In most cases the whales do not show strong avoidance, and they continue to call (see Appendix B for review). However, controlled exposure experiments in the Gulf of Mexico indicate that foraging behavior was altered upon exposure to airgun sound (Jochens et al. 2008; Miller et al. 2009; Tyack 2009).

There are almost no specific data on the behavioral reactions of beaked whales to seismic surveys. However, some northern bottlenose whales remained in the general area and continued to produce high-frequency clicks when exposed to sound pulses from distant seismic surveys (Gosselin and Lawson 2004; Laurinolli and Cochrane 2005; Simard et al. 2005). Most beaked whales tend to avoid approaching vessels of other types (e.g., Würsig et al. 1998). They may also dive for an extended period when approached by a vessel (e.g., Kasuya 1986), although it is uncertain how much longer such dives may be as compared to dives by undisturbed beaked whales, which also are often quite long (Baird et al. 2006; Tyack et al. 2006). Based on a single observation, Aguilar-Soto et al. (2006) suggested that foraging efficiency of Cuvier's beaked whales may be reduced by close approach of vessels. In any event, it is likely that beaked whales would also show strong avoidance of an approaching seismic vessel, although this has not been documented explicitly.

There are increasing indications that some beaked whales tend to strand when naval exercises involving mid-frequency sonar operation are ongoing nearby (e.g., Simmonds and Lopez-Jurado 1991; Frantzis 1998; NOAA and USN 2001; Jepson et al. 2003; Hildebrand 2005; Barlow and Gisiner 2006; see also the "Strandings and Mortality" subsection, later). These strandings are apparently at least in part a disturbance response, although auditory or other injuries or other physiological effects may also be involved. Whether beaked whales would ever react similarly to seismic surveys is unknown (see "Strandings and Mortality", below). Seismic survey sounds are quite different from those of the sonars in operation during the above-cited incidents.

Odontocete reactions to large arrays of airguns are variable and, at least for delphinids and Dall's porpoises, seem to be confined to a smaller radius than has been observed for the more responsive of the mysticetes, belugas, and harbor porpoises (Appendix B). A ≥ 170 dB re 1 μ Pa disturbance criterion (rather than ≥ 160 dB) is considered appropriate for delphinids (and pinnipeds), which tend to be less responsive than the more responsive cetaceans.

Pinnipeds

Pinnipeds are not likely to show a strong avoidance reaction to the airgun array. Visual monitoring from seismic vessels has shown only slight (if any) avoidance of airguns by pinnipeds, and only slight (if any) changes in behavior—see Appendix B (5). In the Beaufort Sea, some ringed seals avoided an area of 100 m to (at most) a few hundred meters around seismic vessels, but many seals remained within 100–200 m of the trackline as the operating airgun array passed by (e.g., Harris et al. 2001; Moulton and Lawson 2002; Miller et al. 2005). Ringed seal sightings averaged somewhat farther away from the seismic vessel when the airguns were operating than when they were not, but the difference was small (Moulton and Lawson 2002). Similarly, in Puget Sound, sighting distances for harbor seals and

California sea lions tended to be larger when airguns were operating (Calambokidis and Osmek 1998). Previous telemetry work suggests that avoidance and other behavioral reactions may be stronger than evident to date from visual studies (Thompson et al. 1998).

Sea Turtles

The limited available data indicate that sea turtles will hear airgun sounds and sometimes exhibit localized avoidance (see Appendix C). Based on available data, it is likely that sea turtles will exhibit behavioral changes and/or avoidance within an area of unknown size near a seismic vessel (e.g., Holst et al. 2005a, 2006; Holst and Smultea 2008). Observed responses of sea turtles to airguns are reviewed in Appendix C. To the extent that there are any impacts on sea turtles, seismic operations in or near areas where turtles concentrate are likely to have the greatest impact. There are no specific data that demonstrate the consequences to sea turtles if seismic operations with large or small arrays of airguns occur in important areas at biologically important times of year.

Additional details on the behavioral reactions (or the lack thereof) by all types of marine mammals to seismic vessels can be found in Appendix B (5). Corresponding details for sea turtles can be found in Appendix C.

Hearing Impairment and Other Physical Effects.—Temporary or permanent hearing impairment is a possibility when marine mammals are exposed to very strong sounds, and TTS has been demonstrated and studied in certain captive odontocetes and pinnipeds exposed to strong sounds (reviewed in Southall et al. 2007). However, there has been no specific documentation of TTS let alone permanent hearing damage, i.e., permanent threshold shift (PTS), in free-ranging marine mammals exposed to sequences of airgun pulses during realistic field conditions. Current NMFS policy regarding exposure of marine mammals to high-level sounds is that cetaceans and pinnipeds should not be exposed to impulsive sounds with received levels ≥ 180 dB and 190 dB re $1 \mu\text{Pa}_{\text{rms}}$, respectively (NMFS 2000). These criteria have been used in establishing the exclusion (=shut-down) zones planned for the proposed seismic survey. However, those criteria were established before there was any information about minimum received levels of sounds necessary to cause auditory impairment in marine mammals. As discussed in Appendix B (6) and summarized here,

- the 180-dB criterion for cetaceans is probably quite precautionary, i.e., lower than necessary to avoid temporary auditory impairment let alone permanent auditory injury, at least for delphinids.
- TTS is not injury and does not constitute “Level A harassment” in U.S. MMPA terminology.
- the minimum sound level necessary to cause permanent hearing impairment (“Level A harassment”) is higher, by a variable and generally unknown amount, than the level that induces barely-detectable TTS.
- the level associated with the onset of TTS is often considered to be a level below which there is no danger of permanent damage. The actual PTS threshold is likely to be well above the level causing onset of TTS (Southall et al. 2007).

Recommendations for new science-based noise exposure criteria for marine mammals, frequency-weighting procedures, and related matters were published recently (Southall et al. 2007). Those recommendations have not, as of late 2010, been formally adopted by NMFS for use in regulatory processes and during mitigation programs associated with seismic surveys. However, some aspects of the recommendations have been taken into account in certain environmental impact statements and small-take authorizations. NMFS has indicated that it may issue new noise exposure criteria for marine mammals that account for the now-available scientific data on TTS, the expected offset between the TTS and PTS thresholds, differences in the acoustic frequencies to which different marine mammal groups are sensitive

(e.g., M-weighting or generalized frequency weightings for various groups of marine mammals, allowing for their functional bandwidths), and other relevant factors. Preliminary information about possible changes in the regulatory and mitigation requirements, and about the possible structure of the new criteria, was given by Wieting (2004) and NMFS (2005).

Several aspects of the planned monitoring and mitigation measures for this project are designed to detect marine mammals occurring near the airgun array, and to avoid exposing them to sound pulses that might, at least in theory, cause hearing impairment (see § II, “Monitoring and Mitigation Measures”). In addition, many marine mammals and (to a limited degree) sea turtles show some avoidance of the area where received levels of airgun sound are high enough such that hearing impairment could potentially occur. In those cases, the avoidance responses of the animals themselves will reduce or (most likely) avoid any possibility of hearing impairment.

Non-auditory physical effects may also occur in marine mammals exposed to strong underwater pulsed sound. Possible types of non-auditory physiological effects or injuries that might (in theory) occur in mammals close to a strong sound source include stress, neurological effects, bubble formation, and other types of organ or tissue damage. It is possible that some marine mammal species (i.e., beaked whales) may be especially susceptible to injury and/or stranding when exposed to strong transient sounds. However, as discussed below, there is no definitive evidence that any of these effects occur even for marine mammals in close proximity to large arrays of airguns. It is unlikely that any effects of these types would occur during the present project given the brief duration of exposure of any given mammal, and the planned monitoring and mitigation measures (see below). The following subsections discuss in somewhat more detail the possibilities of TTS, PTS, and non-auditory physical effects.

Temporary Threshold Shift

TTS is the mildest form of hearing impairment that can occur during exposure to a strong sound (Kryter 1985). While experiencing TTS, the hearing threshold rises and a sound must be stronger in order to be heard. At least in terrestrial mammals, TTS can last from minutes or hours to (in cases of strong TTS) days. For sound exposures at or somewhat above the TTS threshold, hearing sensitivity in both terrestrial and marine mammals recovers rapidly after exposure to the noise ends. Few data on sound levels and durations necessary to elicit mild TTS have been obtained for marine mammals, and none of the published data concern TTS elicited by exposure to multiple pulses of sound. Available data on TTS in marine mammals are summarized in Southall et al. (2007).

For toothed whales exposed to single short pulses, the TTS threshold appears to be, to a first approximation, a function of the energy content of the pulse (Finneran et al. 2002, 2005). Given the available data, the received energy level of a single seismic pulse (with no frequency weighting) might need to be ~ 186 dB re $1 \mu\text{Pa}^2 \cdot \text{s}$ (i.e., 186 dB SEL or ~ 196 – 201 dB re $1 \mu\text{Pa}_{\text{rms}}$) in order to produce brief, mild TTS². Exposure to several strong seismic pulses that each have received levels near 190 dB re $1 \mu\text{Pa}_{\text{rms}}$ might result in cumulative exposure of ~ 186 dB SEL and thus slight TTS in a small odontocete, assuming the TTS threshold is (to a first approximation) a function of the total received pulse energy; however, this ‘equal-energy’ concept is an oversimplification. The distances from the *Langseth*’s airguns at which the received energy level (per pulse, flat-weighted) would be expected to be ≥ 190 dB re $1 \mu\text{Pa}_{\text{rms}}$ are estimated in Table 1. Levels ≥ 190 dB re $1 \mu\text{Pa}_{\text{rms}}$ are expected to be restricted to radii no more than

² If the low frequency components of the watergun sound used in the experiments of Finneran et al. (2002) are downweighted as recommended by Southall et al. (2007) using their M_{mf} -weighting curve, the effective exposure level for onset of mild TTS was 183 dB re $1 \mu\text{Pa}^2 \cdot \text{s}$ (Southall et al. 2007).

1020 m (Table 1). For an odontocete closer to the surface, the maximum radius with ≥ 190 dB re $1 \mu\text{Pa}_{\text{rms}}$ would be smaller.

The above TTS information for odontocetes is derived from studies on the bottlenose dolphin and beluga. For the one harbor porpoise tested, the received level of airgun sound that elicited onset of TTS was lower (Lucke et al. 2009). If these results from a single animal are representative, it is inappropriate to assume that onset of TTS occurs at similar received levels in all odontocetes (*cf.* Southall et al. 2007). Some cetaceans apparently can incur TTS at considerably lower sound exposures than are necessary to elicit TTS in the beluga or bottlenose dolphin.

For baleen whales, there are no data, direct or indirect, on levels or properties of sound that are required to induce TTS. The frequencies to which baleen whales are most sensitive are assumed to be lower than those to which odontocetes are most sensitive, and natural background noise levels at those low frequencies tend to be higher. As a result, auditory thresholds of baleen whales within their frequency band of best hearing are believed to be higher (less sensitive) than are those of odontocetes at their best frequencies (Clark and Ellison 2004). From this, it is suspected that received levels causing TTS onset may also be higher in baleen whales (Southall et al. 2007). In any event, no cases of TTS are expected given three considerations: (1) the low abundance of baleen whales in the planned study area at the time of the survey; (2) the strong likelihood that baleen whales would avoid the approaching airguns (or vessel) before being exposed to levels high enough for TTS to occur; and (3) the mitigation measures that are planned.

In pinnipeds, TTS thresholds associated with exposure to brief pulses (single or multiple) of underwater sound have not been measured. Initial evidence from more prolonged (non-pulse) exposures suggested that some pinnipeds (harbor seals in particular) incur TTS at somewhat lower received levels than do small odontocetes exposed for similar durations (Kastak et al. 1999, 2005; Ketten et al. 2001). The TTS threshold for pulsed sounds has been indirectly estimated as being an SEL of ~ 171 dB re $1 \mu\text{Pa}^2 \cdot \text{s}$ (Southall et al. 2007), which would be equivalent to a single pulse with received level ~ 181 – 186 dB re $1 \mu\text{Pa}_{\text{rms}}$, or a series of pulses for which the highest rms values are a few dB lower. Corresponding values for California sea lions and northern elephant seals are likely to be higher (Kastak et al. 2005).

NMFS (1995, 2000) concluded that cetaceans and pinnipeds should not be exposed to pulsed underwater noise at received levels exceeding, respectively, 180 and 190 dB re $1 \mu\text{Pa}_{\text{rms}}$. Those sound levels are *not* considered to be the levels above which TTS might occur. Rather, they were the received levels above which, in the view of a panel of bioacoustics specialists convened by NMFS before TTS measurements for marine mammals started to become available, one could not be certain that there would be no injurious effects, auditory or otherwise, to marine mammals. As summarized above and in Southall et al. (2007), data that are now available imply that TTS is unlikely to occur in most odontocetes (and probably mysticetes as well) unless they are exposed to a sequence of several airgun pulses stronger than 190 dB re $1 \mu\text{Pa}_{\text{rms}}$. For the harbor seal and any species with similarly low TTS thresholds, TTS may occur upon exposure to one or more airgun pulses whose received level equals the NMFS “do not exceed” value of 190 dB re $1 \mu\text{Pa}_{\text{rms}}$. That criterion corresponds to a single-pulse SEL of 175–180 dB re $1 \mu\text{Pa}^2 \cdot \text{s}$ in typical conditions, whereas TTS is suspected to be possible (in harbor seals) with a cumulative SEL of ~ 171 dB re $1 \mu\text{Pa}^2 \cdot \text{s}$.

Permanent Threshold Shift

When PTS occurs, there is physical damage to the sound receptors in the ear. In severe cases, there can be total or partial deafness, while in other cases, the animal has an impaired ability to hear sounds in specific frequency ranges (Kryter 1985).

There is no specific evidence that exposure to pulses of airgun sound can cause PTS in any marine mammal, even with large arrays of airguns. However, given the possibility that mammals close to an airgun array might incur at least mild TTS, there has been further speculation about the possibility that some individuals occurring very close to airguns might incur PTS (Richardson et al. 1995, p. 372ff; Gedamke et al. 2008). Single or occasional occurrences of mild TTS are not indicative of permanent auditory damage, but repeated or (in some cases) single exposures to a level well above that causing TTS onset might elicit PTS.

Relationships between TTS and PTS thresholds have not been studied in marine mammals, but are assumed to be similar to those in humans and other terrestrial mammals. PTS might occur at a received sound level at least several decibels above that inducing mild TTS if the animal were exposed to strong sound pulses with rapid rise time—see Appendix B (6). Based on data from terrestrial mammals, a precautionary assumption is that the PTS threshold for impulse sounds (such as airgun pulses as received close to the source) is *at least* 6 dB higher than the TTS threshold on a peak-pressure basis, and probably >6 dB (Southall et al. 2007). On an SEL basis, Southall et al. (2007:441-4) estimated that received levels would need to exceed the TTS threshold by at least 15 dB for there to be risk of PTS. Thus, for cetaceans they estimate that the PTS threshold might be an M-weighted SEL (for the sequence of received pulses) of ~198 dB re $1 \mu\text{Pa}^2 \cdot \text{s}$ (15 dB higher than the M_{mf} -weighted TTS threshold, in a beluga, for a watargun impulse), where the SEL value is cumulated over the sequence of pulses. Additional assumptions had to be made to derive a corresponding estimate for pinnipeds, as the only available data on TTS-thresholds in pinnipeds pertain to non-impulse sound. Southall et al. (2007) estimate that the PTS threshold could be a cumulative M_{pw} -weighted SEL of ~186 dB re $1 \mu\text{Pa}^2 \cdot \text{s}$ in the harbor seal exposed to impulse sound. The PTS threshold for the California sea lion and northern elephant seal would probably be higher, given the higher TTS thresholds in those species.

Southall et al. (2007) also note that, regardless of the SEL, there is concern about the possibility of PTS if a cetacean received one or more pulses with peak pressure exceeding 230 or 218 dB re $1 \mu\text{Pa}$ (peak), respectively. Thus, PTS might be expected upon exposure of cetaceans to either SEL ≥ 198 dB re $1 \mu\text{Pa}^2 \cdot \text{s}$ or peak pressure ≥ 230 dB re $1 \mu\text{Pa}$. Corresponding proposed dual criteria for pinnipeds (at least harbor seals) are ≥ 186 dB SEL and ≥ 218 dB peak pressure (Southall et al. 2007). These estimates are all first approximations, given the limited underlying data, assumptions, species differences, and evidence that the “equal energy” model is not entirely correct. A peak pressure of ≥ 230 dB re $1 \mu\text{Pa}$ (3.2 bar \cdot m, 0-pk) would only be found within a few meters of the largest (360-in³) airguns in the planned airgun array (Caldwell and Dragoset 2000). A peak pressure of 218 dB re $1 \mu\text{Pa}$ could be received somewhat farther away; to estimate that specific distance, one would need to apply a model that accurately calculates peak pressures in the near-field around an array of airguns.

Given the higher level of sound necessary to cause PTS as compared with TTS, it is considerably less likely that PTS would occur. Baleen whales generally avoid the immediate area around operating seismic vessels, as do some other marine mammals and sea turtles. The planned monitoring and mitigation measures, including visual monitoring, PAM, power downs, and shut downs of the airguns when mammals are seen within or approaching the “exclusion zones”, will further reduce the probability of exposure of marine mammals to sounds strong enough to induce PTS.

Strandings and Mortality

Marine mammals close to underwater detonations of high explosives can be killed or severely injured, and the auditory organs are especially susceptible to injury (Ketten et al. 1993; Ketten 1995). However, explosives are no longer used for marine waters for commercial seismic surveys or (with rare exceptions) for seismic research; they have been replaced entirely by airguns or related non-explosive

pulse generators. Airgun pulses are less energetic and have slower rise times, and there is no specific evidence that they can cause serious injury, death, or stranding even in the case of large airgun arrays. However, the association of mass strandings of beaked whales with naval exercises and, in one case, an L-DEO seismic survey (Malakoff 2002; Cox et al. 2006), has raised the possibility that beaked whales exposed to strong “pulsed” sounds may be especially susceptible to injury and/or behavioral reactions that can lead to stranding (e.g., Hildebrand 2005; Southall et al. 2007). Appendix B (6) provides additional details.

Specific sound-related processes that lead to strandings and mortality are not well documented, but may include (1) swimming in avoidance of a sound into shallow water; (2) a change in behavior (such as a change in diving behavior) that might contribute to tissue damage, gas bubble formation, hypoxia, cardiac arrhythmia, hypertensive hemorrhage or other forms of trauma; (3) a physiological change such as a vestibular response leading to a behavioral change or stress-induced hemorrhagic diathesis, leading in turn to tissue damage; and (4) tissue damage directly from sound exposure, such as through acoustically mediated bubble formation and growth or acoustic resonance of tissues. Some of these mechanisms are unlikely to apply in the case of impulse sounds. However, there are increasing indications that gas-bubble disease (analogous to “the bends”), induced in supersaturated tissue by a behavioral response to acoustic exposure, could be a pathologic mechanism for the strandings and mortality of some deep-diving cetaceans exposed to sonar. However, the evidence for this remains circumstantial and associated with exposure to naval mid-frequency sonar, not seismic surveys (Cox et al. 2006; Southall et al. 2007).

Seismic pulses and mid-frequency sonar signals are quite different, and some mechanisms by which sonar sounds have been hypothesized to affect beaked whales are unlikely to apply to airgun pulses. Sounds produced by airgun arrays are broadband impulses with most of the energy below 1 kHz. Typical military mid-frequency sonars emit non-impulse sounds at frequencies of 2–10 kHz, generally with a relatively narrow bandwidth at any one time. A further difference between seismic surveys and naval exercises is that naval exercises can involve sound sources on more than one vessel. Thus, it is not appropriate to assume that there is a direct connection between the effects of military sonar and seismic surveys on marine mammals. However, evidence that sonar signals can, in special circumstances, lead (at least indirectly) to physical damage and mortality (e.g., Balcomb and Claridge 2001; NOAA and USN 2001; Jepson et al. 2003; Fernández et al. 2004, 2005; Hildebrand 2005; Cox et al. 2006) suggests that caution is warranted when dealing with exposure of marine mammals to any high-intensity pulsed sound.

There is no conclusive evidence of cetacean strandings or deaths at sea as a result of exposure to seismic surveys, but a few cases of strandings in the general area where a seismic survey was ongoing have led to speculation concerning a possible link between seismic surveys and strandings. Suggestions that there was a link between seismic surveys and strandings of humpback whales in Brazil (Engel et al. 2004) were not well founded (IAGC 2004; IWC 2007). In September 2002, there was a stranding of two Cuvier’s beaked whales in the Gulf of California, Mexico, when the L-DEO vessel R/V *Maurice Ewing* was operating a 20-airgun, 8490-in³ airgun array in the general area. The link between the stranding and the seismic surveys was inconclusive and not based on any physical evidence (Hogarth 2002; Yoder 2002). Nonetheless, the Gulf of California incident plus the beaked whale strandings near naval exercises involving use of mid-frequency sonar suggests a need for caution in conducting seismic surveys in areas occupied by beaked whales until more is known about effects of seismic surveys on those species (Hildebrand 2005). No injuries of beaked whales are anticipated during the proposed study because of (1) the high likelihood that any beaked whales nearby would avoid the approaching vessel before being exposed to high sound levels, (2) the proposed monitoring and mitigation measures, and (3) differences between the sound sources operated by L-DEO and those involved in the naval exercises associated with strandings.

Non-auditory Physiological Effects

Non-auditory physiological effects or injuries that theoretically might occur in marine mammals exposed to strong underwater sound include stress, neurological effects, bubble formation, resonance, and other types of organ or tissue damage (Cox et al. 2006; Southall et al. 2007). Studies examining such effects are limited. However, resonance effects (Gentry 2002) and direct noise-induced bubble formation (Crum et al. 2005) are implausible in the case of exposure to an impulsive broadband source like an airgun array. If seismic surveys disrupt diving patterns of deep-diving species, this might perhaps result in bubble formation and a form of “the bends”, as speculated to occur in beaked whales exposed to sonar. However, there is no specific evidence of this upon exposure to airgun pulses.

In general, very little is known about the potential for seismic survey sounds (or other types of strong underwater sounds) to cause non-auditory physical effects in marine mammals. Such effects, if they occur at all, would presumably be limited to short distances and to activities that extend over a prolonged period. The available data do not allow identification of a specific exposure level above which non-auditory effects can be expected (Southall et al. 2007), or any meaningful quantitative predictions of the numbers (if any) of marine mammals that might be affected in those ways. Marine mammals that show behavioral avoidance of seismic vessels, including most baleen whales, some odontocetes, and some pinnipeds, are especially unlikely to incur non-auditory physical effects. Also, the planned mitigation measures [§ II (3)], including shut downs of the airguns, will reduce any such effects that might otherwise occur.

Sea Turtles

The limited available data indicate that the frequency range of best hearing sensitivity by sea turtles extends from roughly 250–300 Hz to 500–700 Hz. Sensitivity deteriorates as one moves away from that range to either lower or higher frequencies. However, there is some sensitivity to frequencies as low as 60 Hz, and probably as low as 30 Hz. Thus, there is substantial overlap in the frequencies that sea turtles detect vs. the frequencies in airgun pulses. We are not aware of measurements of the absolute hearing thresholds of any sea turtle to waterborne sounds similar to airgun pulses. In the absence of relevant absolute threshold data, we cannot estimate how far away an airgun array might be audible. Moein et al. (1994) and Lenhardt (2002) reported TTS for loggerhead turtles exposed to many airgun pulses (Appendix C). This suggests that sounds from an airgun array might cause temporary hearing impairment in sea turtles if they do not avoid the (unknown) radius where TTS occurs. However, exposure duration during the planned surveys would be much less than during the aforementioned studies. Also, recent monitoring studies show that some sea turtles do show localized movement away from approaching airguns (Holst et al. 2005a, 2006; Holst and Smultea 2008). At short distances from the source, received sound level diminishes rapidly with increasing distance. In that situation, even a small-scale avoidance response could result in a significant reduction in sound exposure.

As noted above, the PSOs stationed on the *Langseth* will also watch for sea turtles, and airgun operations will be shut down if a turtle enters the designated exclusion zone.

(b) Possible Effects of Multibeam Echosounder Signals

The Kongsberg EM 122 MBES will be operated from the source vessel during the planned study. Information about this equipment was provided in § II. Sounds from the MBES are very short pings, occurring for 2–15 ms once every 5–20 s, depending on water depth. Most of the energy in the sound emitted by this MBES is at frequencies near 12 kHz, and the maximum source level is 242 dB re 1 $\mu\text{Pa}_{\text{rms}} \cdot \text{m}$. The beam is narrow (1°) in fore-aft extent and wide (150°) in the cross-track extent. Each ping consists of eight (in water >1000 m deep) or four (<1000 m deep) successive fan-shaped transmissions (segments) at different cross-track angles. Any given mammal at depth near the trackline

would be in the main beam for only one or two of the segments. Also, marine mammals that encounter the Kongsberg EM 122 are unlikely to be subjected to repeated pulses because of the narrow fore-aft width of the beam and will receive only limited amounts of energy because of the short pulses. Animals close to the ship (where the beam is narrowest) are especially unlikely to be ensounded for more than one 2–15 ms pulse (or two pulses if in the overlap area). Similarly, Kremser et al. (2005) noted that the probability of a cetacean swimming through the area of exposure when an MBES emits a pulse is small. The animal would have to pass the transducer at close range and be swimming at speeds similar to the vessel in order to receive the multiple pulses that might result in sufficient exposure to cause TTS.

Navy sonars that have been linked to avoidance reactions and stranding of cetaceans (1) generally have a longer signal duration than the Kongsberg EM 122, and (2) are often directed close to horizontally vs. more downward for the MBES. The area of possible influence of the MBES is much smaller—a narrow band below the source vessel. The duration of exposure for a given marine mammal can be much longer for a naval sonar. During L-DEO's operations, the individual pulses will be very short, and a given mammal would not receive many of the downward-directed pulses as the vessel passes by. Possible effects of an MBES on marine mammals are outlined below.

Masking.—Marine mammal communications will not be masked appreciably by the MBES signals given the low duty cycle of the echosounder and the brief period when an individual mammal is likely to be within its beam. Furthermore, in the case of baleen whales, the MBES signals (12 kHz) do not overlap with the predominant frequencies in the calls, which would avoid any significant masking.

Behavioral Responses.—Behavioral reactions of free-ranging marine mammals to sonars, echosounders, and other sound sources appear to vary by species and circumstance. Observed reactions have included silencing and dispersal by sperm whales (Watkins et al. 1985), increased vocalizations and no dispersal by pilot whales (Rendell and Gordon 1999), and the previously-mentioned beachings by beaked whales. During exposure to a 21–25 kHz “whale-finding” sonar with a source level of 215 dB re 1 $\mu\text{Pa}\cdot\text{m}$, gray whales reacted by orienting slightly away from the source and being deflected from their course by ~200 m (Frankel 2005). When a 38-kHz echosounder and a 150-kHz acoustic Doppler current profiler were transmitting during studies in the ETP, baleen whales showed no significant responses, whereas spotted and spinner dolphins were detected slightly more often and beaked whales less often during visual surveys (Gerrodette and Pettis 2005).

Captive bottlenose dolphins and a white whale exhibited changes in behavior when exposed to 1-s tonal signals at frequencies similar to those that will be emitted by the MBES used by L-DEO, and to shorter broadband pulsed signals. Behavioral changes typically involved what appeared to be deliberate attempts to avoid the sound exposure (Schlundt et al. 2000; Finneran et al. 2002; Finneran and Schlundt 2004). The relevance of those data to free-ranging odontocetes is uncertain, and in any case, the test sounds were quite different in duration as compared with those from an MBES.

Very few data are available on the reactions of pinnipeds to echosounder sounds at frequencies similar to those used during seismic operations. Hastie and Janik (2007) conducted a series of behavioral response tests on two captive gray seals to determine their reactions to underwater operation of a 375-kHz multibeam imaging echosounder that included significant signal components down to 6 kHz. Results indicated that the two seals reacted to the signal by significantly increasing their dive durations. Because of the likely brevity of exposure to the MBES sounds, pinniped reactions are expected to be limited to startle or otherwise brief responses of no lasting consequence to the animals.

Hearing Impairment and Other Physical Effects.—Given recent stranding events that have been associated with the operation of naval sonar, there is concern that mid-frequency sonar sounds can cause serious impacts to marine mammals (see above). However, the MBES proposed for use by L-DEO is

quite different than sonars used for navy operations. Ping duration of the MBES is very short relative to the naval sonars. Also, at any given location, an individual marine mammal would be in the beam of the MBES for much less time given the generally downward orientation of the beam and its narrow fore-aft beamwidth; navy sonars often use near-horizontally-directed sound. Those factors would all reduce the sound energy received from the MBES rather drastically relative to that from the sonars used by the navy.

Given the maximum source level of 242 dB re 1 $\mu\text{Pa} \cdot \text{m}_{\text{rms}}$ (see § II), the received level for an animal within the MBES beam 100 m below the ship would be ~ 202 dB re 1 $\mu\text{Pa}_{\text{rms}}$, assuming 40 dB of spreading loss over 100 m (circular spreading). Given the narrow beam, only one ping is likely to be received by a given animal as the ship passes overhead. The received energy level from a single ping of duration 15 ms would be about 184 dB re 1 $\mu\text{Pa}^2 \cdot \text{s}$, i.e., 202 dB + 10 log (0.015 s). That is below the TTS threshold for a cetacean receiving a single non-impulse sound (195 dB re 1 $\mu\text{Pa}^2 \cdot \text{s}$) and even further below the anticipated PTS threshold (215 dB re 1 $\mu\text{Pa}^2 \cdot \text{s}$) (Southall et al. 2007). In contrast, an animal that was only 10 m below the MBES when a ping is emitted would be expected to receive a level ~ 20 dB higher, i.e., 204 dB re 1 $\mu\text{Pa}^2 \cdot \text{s}$ in the case of the EM 122. That animal might incur some TTS (which would be fully recoverable), but the exposure would still be below the anticipated PTS threshold for cetaceans. As noted by Burkhardt et al. (2008), cetaceans are very unlikely to incur PTS from operation of scientific sonars on a ship that is underway.

In the harbor seal, the TTS threshold for non-impulse sounds is about 183 dB re 1 $\mu\text{Pa}^2 \cdot \text{s}$, as compared with ~ 195 dB re 1 $\mu\text{Pa}^2 \cdot \text{s}$ in odontocetes (Kastak et al. 2005; Southall et al. 2007). TTS onset occurs at higher received energy levels in the California sea lion and northern elephant seal than in the harbor seal. A harbor seal as much as 100 m below the *Langseth* could receive a single MBES ping with received energy level of ≥ 184 dB re 1 $\mu\text{Pa}^2 \cdot \text{s}$ (as calculated in the toothed whale subsection above) and thus could incur slight TTS. Species of pinnipeds with higher TTS thresholds would not incur TTS unless they were closer to the transducers when a ping was emitted. However, the SEL criterion for PTS in pinnipeds (203 dB re 1 $\mu\text{Pa}^2 \cdot \text{s}$) might be exceeded for a ping received within a few meters of the transducers, although the risk of PTS is higher for certain species (e.g., harbor seal). Given the intermittent nature of the signals and the narrow MBES beam, only a small fraction of the pinnipeds below (and close to) the ship would receive a ping as the ship passed overhead.

Sea Turtles.—It is unlikely that MBES operations during the planned seismic survey would significantly affect sea turtles through masking, disturbance, or hearing impairment. Any effects would likely be negligible given the brief exposure and the fact that the MBES frequency is far above the range of optimal hearing by sea turtles (see Appendix C).

(c) Possible Effects of the Sub-bottom Profiler Signals

An SBP will also be operated from the source vessel during the planned study. Details about this equipment were provided in § II. Sounds from the SBP are very short pings, occurring for 1–4 ms once every second. Most of the energy in the sound emitted by the SBP is at 3.5 kHz, and the beam is directed downward. The sub-bottom profiler on the *Langseth* has a maximum source level of 204 dB re 1 $\mu\text{Pa} \cdot \text{m}$ (see § II). Kremser et al. (2005) noted that the probability of a cetacean swimming through the area of exposure when a bottom profiler emits a ping is small—even for an SBP more powerful than that on the *Langseth*—if the animal was in the area, it would have to pass the transducer at close range in order to be subjected to sound levels that could cause TTS.

Masking.—Marine mammal communications will not be masked appreciably by the SBP signals given the directionality of the signal and the brief period when an individual mammal is likely to be

within its beam. Furthermore, in the case of most baleen whales, the SBP signals do not overlap with the predominant frequencies in the calls, which would avoid significant masking.

Behavioral Responses.—Marine mammal behavioral reactions to other sound sources are discussed above, and responses to the SBP are likely to be similar to those for other non-impulse sources if received at the same levels. However, the signals from the SBP are considerably weaker than those from the MBES. Therefore, behavioral responses are not expected unless marine mammals are very close to the source.

Hearing Impairment and Other Physical Effects.—It is unlikely that the SBP produces sound levels strong enough to cause hearing impairment or other physical injuries even in an animal that is (briefly) in a position near the source. The SBP is operated simultaneously with other higher-power acoustic sources, including airguns. Many marine mammals will move away in response to the approaching higher-power sources or the vessel itself before the mammals would be close enough for there to be any possibility of effects from the less intense sounds from the SBP. In the case of mammals that do not avoid the approaching vessel and its various sound sources, mitigation measures that would be applied to minimize effects of other sources [see § II(3)] would further reduce or eliminate any minor effects of the SBP.

Sea Turtles.—It is very unlikely that SBP operations during the planned seismic survey would significantly affect sea turtles through masking, disturbance, or hearing impairment. Any effects likely would be negligible given the brief exposure and relatively low source level. Also, the frequency of the SBP sounds is higher than the frequency range of best hearing by sea turtles.

(2) Mitigation Measures

Several mitigation measures are built into the proposed seismic survey as an integral part of the planned activities. These measures include the following: ramp ups, minimum of one dedicated observer maintaining a visual watch during all daytime airgun operations, two observers for 30 min before and during ramp-ups during the day and at night (and when possible at other times), PAM during the day and night to complement visual monitoring, power downs (or if necessary shut downs) when mammals or turtles are detected in or about to enter designated exclusion zones. These mitigation measures are described earlier in this document, in § II(3). The fact that the 18-airgun subarray, as a result of its design, directs the majority of the energy downward, and less energy laterally, is also an inherent mitigation measure.

Previous and subsequent analysis of the potential impacts take account of these planned mitigation measures. It would not be meaningful to analyze the effects of the planned activities without mitigation, as the mitigation (and associated monitoring) measures are a basic part of the activities.

(3) Numbers of Marine Mammals that could be Exposed to Various Received Sound Levels

All anticipated takes would be “takes by harassment”, involving temporary changes in behavior. The mitigation measures to be applied will minimize the possibility of injurious takes. (However, as noted earlier, there is no specific information demonstrating that injurious “takes” would occur even in the absence of the planned mitigation measures.) In the sections below, we describe methods to estimate the number of potential exposures to various received sound levels and present estimates of the numbers of marine mammals that could be affected during the proposed seismic program. The estimates are based on a consideration of the number of marine mammals that could be disturbed appreciably by operations with the 18-airgun subarray to be used during ~3200 km of seismic surveys in the ETP off Costa Rica. The sources of distributional and numerical data used in deriving the estimates are described in the next subsection.

It is assumed that, during simultaneous operations of the airgun array and the other sources, any marine mammals close enough to be affected by the MBES and SBP would already be affected by the

airguns. However, whether or not the airguns are operating simultaneously with the other sources, marine mammals are expected to exhibit no more than short-term and inconsequential responses to the MBES and SBP given their characteristics (e.g., narrow downward-directed beam) and other considerations described in § II and IV(1)(b and c), above. Such reactions are not considered to constitute “taking” (NMFS 2001). Therefore, no additional allowance is included for animals that could be affected by sound sources other than airguns.

(a) Basis for Estimating “Take by Harassment”

Extensive systematic ship-based surveys have been conducted by NMFS SWFSC for marine mammals in the ETP. We used densities from two sources: (1) SWFSC has recently developed habitat modeling as a method to estimate cetacean densities on a finer spatial scale than traditional line-transect analyses by using a continuous function of habitat variables, e.g., sea surface temperature, depth, distance from shore, and prey density (Barlow et al. 2009). For the ETP, the models are based on data from 12 SWFSC ship-based cetacean and ecosystem assessment surveys conducted during July–December from 1986 to 2006. The models have been incorporated into a web-based Geographic Information System (GIS) developed by Duke University’s Department of Defense Strategic Environmental Research and Development Program (SERDP) team in close collaboration with the SWFSC SERDP team (Read et al. 2009). We used the GIS to obtain mean and maximum densities for the 11 cetacean species in the model in the proposed survey area. (2) For species sighted in SWFSC surveys whose sample sizes were too small to model density, we used densities from the surveys conducted during summer and fall 1986–1996, as summarized by Ferguson and Barlow (2001, 2003). Densities were calculated from Ferguson and Barlow (2003) for 5° x 5° blocks that include the proposed survey area (Block 138) and blocks adjacent to 138 that include coastal waters: Blocks 119, 137, 138, 139, 158, and 159. Those blocks included 18,385 km of survey effort in Beaufort sea states 0–5, and 3899 km³ of survey effort in Beaufort sea states 0–2. Densities were obtained for an additional seven species that were sighted in one or more of those blocks.

For two endangered species for which there are only unconfirmed sightings in the region, the sei and fin whales, arbitrary low densities (equal to the density of the species with the lowest calculated density) were assigned. The false killer whale has been sighted near the survey area but not in the 7 blocks of Ferguson and Barlow (2003), so it was also assigned the same arbitrary low density.

Oceanographic conditions, including occasional El Niño and La Niña events, influence the distribution and numbers of marine mammals present in the ETP, resulting in considerable year-to-year variation in the distribution and abundance of many marine mammal species (e.g., Escorza-Treviño 2009). Thus, for some species the densities derived from recent surveys may not be representative of the densities that will be encountered during the proposed seismic survey.

Table 3 gives the estimated densities for each cetacean species likely to occur in the study area, i.e., species for which we obtained or assigned densities. The densities have been corrected for both detectability and availability bias by the authors. Detectability bias is associated with diminishing sightability with increasing lateral distance from the trackline [$f(0)$]. Availability bias refers to the fact that there is less-than-100% probability of sighting an animal that is present along the survey trackline, and it is measured by $g(0)$.

There is some uncertainty about the representativeness of the data and the assumptions used in the calculations below. However, the approach used here is believed to be the best available approach. Also, to provide some allowance for these uncertainties, “maximum estimates” as well as “best estimates” of the densities present and numbers potentially affected have been derived. For the modeled species, best

³ Includes other blocks pooled with the blocks of interest to provide sufficient effort to allow a density estimate.

TABLE 3. Densities of marine mammals in the ETP near the proposed survey area. Cetacean densities are based on NMFS SWFSC ship transect surveys conducted in 1986–2006 from predictive modeling (Barlow et al. 2009; Read et al. 2009) or in 1986–1996 from Ferguson and Barlow (2003). See text for details. Densities are corrected for $f(0)$ and $g(0)$. Species listed as "Endangered" under the ESA are in italics.

Species ¹	Density (#/1000 km ²)		Source
	Best (mean)	Maximum	
Mysticetes			
<i>Humpback whale</i>	0.25	4.40	Ferguson and Barlow (2003)
Bryde's whale	0.96	2.52	Read et al. (2009)
<i>Sei whale</i>	0.01	0.01	Arbitrary low
<i>Fin whale</i>	0.01	0.01	Arbitrary low
<i>Blue whale</i>	0.13	1.86	Read et al. (2009)
Odontocetes			
<i>Sperm whale</i>	4.19	9.80	Ferguson and Barlow (2003)
Pygmy and dwarf sperm whales	0.03	0.05	Read et al. (2009)
Cuvier's beaked whale	2.47	3.70	Ferguson and Barlow (2003)
<i>Mesoplodon</i> spp. □	0.36	1.00	Read et al. (2009)
Rough-toothed dolphin	4.19	11.19	Read et al. (2009)
Bottlenose dolphin	17.06	90.91	Read et al. (2009)
Pantropical spotted dolphin	76.96	236.66	Read et al. (2009)
Spinner dolphin	58.43	364.26	Read et al. (2009)
Striped dolphin	67.75	154.21	Read et al. (2009)
Short-beaked common dolphin	110.89	763.50	Read et al. (2009)
Risso's dolphin	12.76	22.60	Ferguson and Barlow (2003)
Melon-headed Whale	11.06	57.70	Ferguson and Barlow (2003)
Pygmy killer whale	1.25	2.30	Ferguson and Barlow (2003)
False killer whale	0.01	0.01	Arbitrary low
Killer whale	0.19	0.40	Ferguson and Barlow (2003)
Short-finned pilot whale	11.88	28.22	Read et al. (2009)

¹ With the exception of sei, fin, and false killer whales, includes only species for which density estimates are available. Densities of other species included in Table 2 (minke whale, Fraser's dolphin, and the sea lions) presumably would be lower than the lowest density in this table.

□ Includes pygmy, ginkgo-toothed, and Blaineville's beaked whales.

estimates and maximum estimates of density in the survey area are the mean and maximum densities given in Read et al. (2009). For the other species, best estimates of density are the effort-weighted mean densities in the seven 5° x 5° blocks from Ferguson and Barlow (2001, 2003), and maximum estimates of density are the highest densities in any of the blocks.

There is some uncertainty about the representativeness of the data and the assumptions used in the calculations below. However, the approach used here is believed to be the best available approach. Also, to provide some allowance for these uncertainties, "maximum estimates" as well as "best estimates" of the densities present and numbers potentially affected have been derived. For the modeled species, best estimates and maximum estimates of density in the survey area are the mean and maximum densities given in Read et al. (2009). For the other species, best estimates of density are the effort-weighted mean densities in the seven 5° x 5° blocks from Ferguson and Barlow (2001, 2003), and maximum estimates of density are the highest densities in any of the blocks.

The estimated numbers of individuals potentially exposed are based on the 160-dB re 1 $\mu\text{Pa}_{\text{rms}}$ criterion for all cetaceans and the 170-dB re 1 $\mu\text{Pa}_{\text{rms}}$ criterion for delphinids. It is assumed that marine mammals exposed to airgun sounds that strong might change their behavior sufficiently to be considered “taken by harassment”.

It should be noted that the following estimates of exposures to various sound levels assume that the surveys will be fully completed; in fact, the ensonified areas calculated using the planned number of line-kilometers *have been increased by 25%* to accommodate lines that may need to be repeated, equipment testing, etc. As is typical during ship surveys, inclement weather and equipment malfunctions are likely to cause delays and may limit the number of useful line-kilometers of seismic operations that can be undertaken. Furthermore, any marine mammal sightings within or near the designated exclusion zone will result in the shut down of seismic operations as a mitigation measure. Thus, the following estimates of the numbers of marine mammals potentially exposed to 160- or 170-dB re 1 $\mu\text{Pa}_{\text{rms}}$ sounds are precautionary, and probably overestimate the actual numbers of marine mammals that might be involved. These estimates assume that there will be no weather, equipment, or mitigation delays, which is highly unlikely. Furthermore, the radii and therefore exposures may be overestimated, possibly considerably (see § I).

(b) Potential Number of Marine Mammals Exposed to Airgun Sounds

Number of Cetaceans that could be Exposed to ≥ 160 dB.—The number of different individuals that could be exposed to airgun sounds with received levels ≥ 160 dB re 1 $\mu\text{Pa}_{\text{rms}}$ on one or more occasions can be estimated by considering the expected density of animals in the area along with the total marine area that would be within the 160-dB radius around the operating airgun array on at least one occasion. The number of possible exposures (including repeated exposures of the same individuals) can be estimated by considering the total marine area that would be within the 160-dB radius around the operating airguns, including areas of overlap. In the proposed survey, the seismic lines are parallel and in close proximity, so individuals could be exposed on two or more occasions. The area including overlap is 31.9 x the area excluding overlap (13.7 x the area excluding overlap for the 170-dB radius), so a marine mammal that stayed in the survey area during the entire survey could be exposed 32 times (14 times), on average. Given the pattern of the seismic lines, the interval between exposures of a stationary animal would be ~18 h. However, it is unlikely that a particular animal would stay in the area during the entire survey. The numbers of different individuals potentially exposed to ≥ 160 dB re 1 $\mu\text{Pa}_{\text{rms}}$ were calculated by multiplying

- the expected species density, either “mean” (i.e., best estimate) or “maximum”, times
- the anticipated area to be ensonified to that level during airgun operations including overlap (exposures), or
- the anticipated area to be ensonified to that level during airgun operations excluding overlap (individuals).

The area expected to be ensonified was determined by entering the planned survey lines into a MapInfo GIS, using the GIS to identify the relevant areas by “drawing” the applicable 160-dB (or, in the next subsection, 170-dB) buffer (see Table 1) around each seismic line, and then calculating the total area within the buffers. Areas of overlap were included only once when estimating the number of individuals exposed. Before calculating numbers of individuals exposed, the areas were increased by 25% as a precautionary measure.

Table 4 shows the best and maximum estimates of the number of different individual marine mammals that potentially could be exposed to ≥ 160 dB re 1 $\mu\text{Pa}_{\text{rms}}$ during the seismic survey if no animals moved away from the survey vessel. The **Requested Take Authorization**, given in the far right column of

TABLE 4. Estimates of the possible numbers of different individuals that might be exposed, during L-DEO's proposed seismic survey in ETP in April–May 2011. The proposed sound source consists of an 18-airgun subarray with a total discharge volume of 3300 in³. Received levels of seismic sounds are expressed in dB re 1 µPa (rms, averaged over pulse duration), consistent with NMFS' practice. Not all marine mammals will change their behavior when exposed to these sound levels, but some may alter their behavior when levels are lower (see text). Delphinids are unlikely to react to levels below 170 dB. Species in italics are listed under the ESA as endangered or threatened. The column of numbers in boldface shows the numbers of "takes" for which authorization is requested.

Species	Number of Individuals Exposed to Sound Levels >160 dB (>170 dB, Delphinids)				
	Best Estimate ¹		Maximum Estimate ¹	Requested Take Authorization	
	Number	% of Regional Pop'n ²			
Balaenopteridae					
<i>Humpback whale</i>	1	0.07	18	18	
Bryde's whale	4	0.03	10	10	
<i>Sei whale</i>	0	NA	0	1³	
<i>Fin whale</i>	0	<0.01	0	1³	
<i>Blue whale</i>	1	0.04	8	8	
Physeteridae					
<i>Sperm whale</i>	17	0.05	40	40	
Pygmy/dwarf sperm whales	0	<0.01	0	0	
Ziphiidae					
Cuvier's beaked whale	10	0.05	15	15	
<i>Mesoplodon</i> sp. (unidentified)	1	0.01	4	4	
Delphinidae					
Rough-toothed dolphin	17	(7)	0.02	45 (18)	21
Bottlenose dolphin	69	(27)	0.02	366 (146)	173
Pantropical spotted dolphin	310	(124)	0.02	954 (380)	450
Spinner dolphin	236	(94)	0.01	1468 (585)	693
Striped dolphin	273	(109)	0.03	622 (248)	293
Short-beaked common dolphin	447	(178)	0.01	3077 (1226)	1452
Risso's dolphin	51	(20)	0.05	91 (36)	43
Melon-headed whale	45	(18)	0.10	233 (93)	258³
Pygmy killer whale	5	(2)	0.01	9 (4)	30³
False killer whale	0	(0)	<0.01	0 (0)	0
Killer whale	1	(0)	0.01	2 (1)	5
Short-finned pilot whale	48	(19)	0.01	114 (45)	54

¹ Best and maximum estimates are based on densities from Table 3 and ensonified areas (including 25% contingency) of 4030.63 for 160 dB and 1605.71 km² for 170 dB (identified in parentheses). Takes are not anticipated for the minke whale and Fraser's dolphin.

² Regional population size estimates are from Table 2; NA means not available.

³ Requested Take Authorization increased to mean group size in the ETP for baleen whales (Jackson et al. 2008) and delphinids (Ferguson et al. 2006).

Table 4, is based on the maximum estimates rather than the best estimates of the numbers exposed, because the density estimates they are based on SWFSC marine mammal surveys conducted during July–November, whereas the proposed seismic survey is scheduled during April–May. For *endangered* species, the **Requested Take Authorization** has been increased to the mean group size in the ETP (Jackson et al. 2008) for the particular species in cases where the calculated number of individuals exposed was between 0.05 and

the mean group size (i.e., for sei and fin whales). For non-listed species, the **Requested Take Authorization** has been increased to the mean group size in the ETP (Ferguson et al. 2006) for the particular species in cases where the calculated number of individuals exposed was between 1 and the mean group size.

Applying the approach described above, $\sim 3225 \text{ km}^2$ ($\sim 4030 \text{ km}^2$ including the 25% contingency) would be within the 160-dB isopleth during the survey assuming that all contingency lines are completed. Because this approach does not allow for turnover in the mammal populations in the study area during the course of the survey, the actual number of individuals exposed could be underestimated. However, the approach assumes that no cetaceans will move away from or toward the trackline as the *Langseth* approaches in response to increasing sound levels prior to the time the levels reach 160 dB, which will result in overestimates for those species known to avoid seismic vessels (see § IV a).

The ‘best estimate’ of the number of individual cetaceans that could be exposed to seismic sounds with received levels $\geq 160 \text{ dB re } 1 \mu\text{Pa}_{\text{rms}}$ during the proposed survey is 1536 (Table 4). That total includes 17 sperm whales (listed as **endangered under** the ESA) or 0.06% of the regional population.

In addition, 11 beaked whales (10 Cuvier’s and 1 Mesoplodont beaked whales) could be exposed during the survey (Table 4). Most (97.8%) of the cetaceans potentially exposed are delphinids; short-beaked common, pantropical spotted, striped, and spinner dolphins are estimated to be the most common species in the area, with best estimates of 447, 310, 273, and 236 (each representing 0.01%–0.03% of the regional population) exposed to $\geq 160 \text{ dB re } 1 \mu\text{Pa}_{\text{rms}}$, respectively. However, a more meaningful estimate is the one for sound levels $\geq 170 \text{ dB}$ (see below). The ‘Maximum Estimate’ column in Table 4 shows an estimated total of 7076 cetaceans. Again, most of these consist of dolphins.

Number of Delphinids that could be Exposed to $\geq 170 \text{ dB}$.—The 160-dB criterion, on which the preceding estimates are based, was derived from studies of baleen whales. Odontocete hearing at low frequencies is relatively insensitive, and delphinids generally appear to be more tolerant of strong low-frequency sounds than are many baleen whales. As summarized in Appendix B (5), delphinids commonly occur within distances where received levels would be expected to exceed 160 dB re $1 \mu\text{Pa}_{\text{rms}}$. There is no generally accepted alternative “take” criterion for delphinids exposed to airgun sounds. However, the estimates in this subsection assume that only those delphinids exposed to $\geq 170 \text{ dB re } 1 \mu\text{Pa}_{\text{rms}}$, on average, would be affected sufficiently to be considered “taken by harassment”. (“On average” means that some individuals might react significantly upon exposure to levels somewhat $< 170 \text{ dB}$, but others would not do so even upon exposure to levels somewhat $> 170 \text{ dB}$.)

The area ensonified by levels $\geq 170 \text{ dB}$ was estimated to be $\sim 1285 \text{ km}^2$ ($\sim 1605 \text{ km}^2$ including the 25% contingency). The best and maximum estimates of the numbers of individual delphinids that could be exposed to $\geq 170 \text{ dB}$ during the survey are 598 and 2782, respectively (Table 4). These values are based on the predicted 170-dB radius around the airgun array to be used during the study, and are considered to be more realistic estimates of the number of individual delphinids that could be affected.

(4) Conclusions for Marine Mammals and Sea Turtles

The proposed seismic survey will involve towing an airgun array that introduces pulsed sounds into the ocean, along with simultaneous operation of an MBES and SBP. The survey will employ an 18-airgun subarray similar to the airgun arrays used for typical high-energy seismic surveys. The total airgun discharge volume is $\sim 3300 \text{ in}^3$. Routine vessel operations, other than the proposed airgun operations, are conventionally assumed not to affect marine mammals sufficiently to constitute “taking”. No “taking” of marine mammals is expected in association with echosounder operations given the considerations discussed in §IV(1)(b and c), i.e., sounds are beamed downward, the beam is narrow, and the pulses are extremely short.

(a) Cetaceans

Several species of mysticetes show strong avoidance reactions to seismic vessels at ranges up to 6–8 km and occasionally as far as 20–30 km from the source vessel when medium-large airgun arrays have been used. However, reactions at the longer distances appear to be atypical of most species and situations. If mysticetes are encountered, the numbers estimated to occur within the 160-dB isopleth in the survey area are expected to be low.

Odontocete reactions to seismic pulses, or at least the reactions of delphinids, are expected to extend to lesser distances than are those of mysticetes. Odontocete low-frequency hearing is less sensitive than that of mysticetes, and dolphins are often seen from seismic vessels. In fact, there are documented instances of dolphins approaching active seismic vessels. However, delphinids (along with other cetaceans) sometimes show avoidance responses and/or other changes in behavior when near operating seismic vessels.

Taking into account the mitigation measures that are planned (see § II), effects on cetaceans are generally expected to be limited to avoidance of the area around the seismic operation and short-term changes in behavior, falling within the MMPA definition of “Level B harassment”.

Varying estimates of the numbers of marine mammals that might be exposed to strong airgun sounds during the proposed program have been presented, depending on the specific exposure criteria (≥ 160 or ≥ 170 dB) and density criterion used (best or maximum). The requested “take authorization” for each species is based on the best estimates of the number of individuals that could be exposed to ≥ 160 dB re $1 \mu\text{Pa}_{\text{rms}}$. Those figures likely overestimate the actual number of animals that will be exposed to and will react to the seismic sounds. The reasons for that conclusion are outlined above. The relatively short-term exposures are unlikely to result in any long-term negative consequences for the individuals or their populations.

The many cases of apparent tolerance by cetaceans of seismic exploration, vessel traffic, and some other human activities show that co-existence is possible. Mitigation measures such as look outs, ramp ups, and power downs or shut downs when marine mammals are seen within defined ranges should further reduce short-term reactions, and avoid or minimize any effects on hearing sensitivity. In all cases, the effects are expected to be short-term, with no lasting biological consequence.

(b) Pinnipeds

No pinnipeds are expected to occur in the survey area.

(c) Sea Turtles

Some leatherback, green, and olive ridley nesting beaches occur near the proposed survey area, but the biggest and most-used beaches are located >150 km to the north, on the Nicoya Peninsula. The survey is scheduled after the peak nesting periods for leatherbacks (October–March), green turtles (October–November), and olive ridleys (September–December), so it is likely that only a few hatchlings of any species would be encountered. Foraging or migrating individuals of those species and hawksbill and loggerhead turtles could be encountered at any time of year. With the implementation of mitigation measures, it is anticipated that the proposed seismic survey will have, at most, a short-term effect on behavior and no long-term impacts on individual sea turtles or their populations.

(5) Direct Effects on Fish and Their Significance

One reason for the adoption of airguns as the standard energy source for marine seismic surveys is that, unlike explosives, they have not been associated with large-scale fish kills. However, existing information on the impacts of seismic surveys on marine fish populations is very limited (see Appendix D).

There are three types of potential effects of exposure to seismic surveys: (1) pathological, (2) physiological, and (3) behavioral. Pathological effects involve lethal and temporary or permanent sub-lethal injury. Physiological effects involve temporary and permanent primary and secondary stress responses, such as changes in levels of enzymes and proteins. Behavioral effects refer to temporary and (if they occur) permanent changes in exhibited behavior (e.g., startle and avoidance behavior). The three categories are interrelated in complex ways. For example, it is possible that certain physiological and behavioral changes could potentially lead to an ultimate pathological effect on individuals (i.e., mortality).

The specific received sound levels at which permanent adverse effects to fish potentially could occur are little studied and largely unknown. Furthermore, the available information on the impacts of seismic surveys on marine fish is from studies of individuals or portions of a population; there have been no studies at the population scale. The studies of individual fish have often been on caged fish that were exposed to airgun pulses in situations not representative of an actual seismic survey. Thus, available information provides limited insight on possible real-world effects at the ocean or population scale. This makes drawing conclusions about impacts on fish problematic because, ultimately, the most important issues concern effects on marine fish populations, their viability, and their availability to fisheries.

Hastings and Popper (2005), Popper (2009), and Popper and Hastings (2009a,b) provided recent critical reviews of the known effects of sound on fish. The following sections provide a general synopsis of the available information on the effects of exposure to seismic and other anthropogenic sound as relevant to fish. The information comprises results from scientific studies of varying degrees of rigor plus some anecdotal information. Some of the data sources may have serious shortcomings in methods, analysis, interpretation, and reproducibility that must be considered when interpreting their results (see Hastings and Popper 2005). Potential adverse effects of the program's sound sources on marine fish are then noted.

(a) Pathological Effects

The potential for pathological damage to hearing structures in fish depends on the energy level of the received sound and the physiology and hearing capability of the species in question (see Appendix D). For a given sound to result in hearing loss, the sound must exceed, by some substantial amount, the hearing threshold of the fish for that sound (Popper 2005). The consequences of temporary or permanent hearing loss in individual fish or a fish population are unknown; however, they likely depend on the number of individuals affected and whether critical behaviors involving sound (e.g. predator avoidance, prey capture, orientation and navigation, reproduction, etc.) are adversely affected.

Little is known about the mechanisms and characteristics of damage to fish that may be inflicted by exposure to seismic survey sounds. Few data have been presented in the peer-reviewed scientific literature. As far as we know, there are only two papers with proper experimental methods, controls, and careful pathological investigation implicating sounds produced by actual seismic survey airguns in causing adverse anatomical effects. One such study indicated anatomical damage, and the second indicated TTS in fish hearing. The anatomical case is McCauley et al. (2003), who found that exposure to airgun sound caused observable anatomical damage to the auditory maculae of "pink snapper" (*Pagrus auratus*). This damage in the ears had not been repaired in fish sacrificed and examined almost two months after exposure. On the other hand, Popper et al. (2005) documented only TTS (as determined by auditory brainstem response) in two of three fish species from the Mackenzie River Delta. This study found that broad whitefish (*Coregonus nasus*) that received a sound exposure level of 177 dB re 1 $\mu\text{Pa}^2 \cdot \text{s}$ showed no hearing loss. During both studies, the repetitive exposure to sound was greater than would have occurred during a typical seismic survey. However, the substantial low-frequency energy produced by the airguns [less than ~400 Hz in the study by McCauley et al. (2003) and less than ~200 Hz in Popper et al. (2005)] likely did not propagate to the fish because the water in the study areas was very shallow (~9 m in the former case and <2

m in the latter). Water depth sets a lower limit on the lowest sound frequency that will propagate (the “cutoff frequency”) at about one-quarter wavelength (Urlick 1983; Rogers and Cox 1988).

Wardle et al. (2001) suggested that in water, acute injury and death of organisms exposed to seismic energy depends primarily on two features of the sound source: (1) the received peak pressure and (2) the time required for the pressure to rise and decay. Generally, as received pressure increases, the period for the pressure to rise and decay decreases, and the chance of acute pathological effects increases. According to Buchanan et al. (2004), for the types of seismic airguns and arrays involved with the proposed program, the pathological (mortality) zone for fish would be expected to be within a few meters of the seismic source. Numerous other studies provide examples of no fish mortality upon exposure to seismic sources (Falk and Lawrence 1973; Holliday et al. 1987; La Bella et al. 1996; Santulli et al. 1999; McCauley et al. 2000a,b, 2003; Bjarti 2002; Thomsen 2002; Hassel et al. 2003; Popper et al. 2005; Boeger et al. 2006).

Some studies have reported, some equivocally, that mortality of fish, fish eggs, or larvae can occur close to seismic sources (Kostyuchenko 1973; Dalen and Knutsen 1986; Booman et al. 1996; Dalen et al. 1996). Some of the reports claimed seismic effects from treatments quite different from actual seismic survey sounds or even reasonable surrogates. However, Payne et al. (2009) reported no statistical differences in mortality/morbidity between control and exposed groups of capelin eggs or monkfish larvae. Saetre and Ona (1996) applied a ‘worst-case scenario’ mathematical model to investigate the effects of seismic energy on fish eggs and larvae. They concluded that mortality rates caused by exposure to seismic surveys are so low, as compared to natural mortality rates, that the impact of seismic surveying on recruitment to a fish stock must be regarded as insignificant.

(b) Physiological Effects

Physiological effects refer to cellular and/or biochemical responses of fish to acoustic stress. Such stress potentially could affect fish populations by increasing mortality or reducing reproductive success. Primary and secondary stress responses of fish after exposure to seismic survey sound appear to be temporary in all studies done to date (Sverdrup et al. 1994; Santulli et al. 1999; McCauley et al. 2000a,b). The periods necessary for the biochemical changes to return to normal are variable and depend on numerous aspects of the biology of the species and of the sound stimulus (see Appendix D).

(c) Behavioral Effects

Behavioral effects include changes in the distribution, migration, mating, and catchability of fish populations. Studies investigating the possible effects of sound (including seismic survey sound) on fish behavior have been conducted on both uncaged and caged individuals (Chapman and Hawkins 1969; Pearson et al. 1992; Santulli et al. 1999; Wardle et al. 2001; Hassel et al. 2003). Typically, in these studies fish exhibited a sharp “startle” response at the onset of a sound followed by habituation and a return to normal behavior after the sound ceased.

There is general concern about potential adverse effects of seismic operations on fisheries, namely a potential reduction in the “catchability” of fish involved in fisheries. Although reduced catch rates have been observed in some marine fisheries during seismic testing, in a number of cases the findings are confounded by other sources of disturbance (Dalen and Raknes 1985; Dalen and Knutsen 1986; Løkkeborg 1991; Skalski et al. 1992; Engås et al. 1996). In other airgun experiments, there was no change in catch per unit effort (CPUE) of fish when airgun pulses were emitted, particularly in the immediate vicinity of the seismic survey (Pickett et al. 1994; La Bella et al. 1996). For some species, reductions in catch may have resulted from a change in behavior of the fish, e.g., a change in vertical or horizontal distribution, as reported in Slotte et al. (2004).

In general, any adverse effects on fish behavior or fisheries attributable to seismic testing may depend on the species in question and the nature of the fishery (season, duration, fishing method). They may also depend on the age of the fish, its motivational state, its size, and numerous other factors that are difficult, if not impossible, to quantify at this point, given such limited data on effects of airguns on fish, particularly under realistic at-sea conditions.

(6) Direct Effects on Invertebrates and Their Significance

(a) Seismic operations

The existing body of information on the impacts of seismic survey sound on marine invertebrates is very limited. However, there is some unpublished and very limited evidence of the potential for adverse effects on invertebrates, thereby justifying further discussion and analysis of this issue. The three types of potential effects of exposure to seismic surveys on marine invertebrates are pathological, physiological, and behavioral. Based on the physical structure of their sensory organs, marine invertebrates appear to be specialized to respond to particle displacement components of an impinging sound field and not to the pressure component (Popper et al. 2001; see also Appendix E).

The only information available on the impacts of seismic surveys on marine invertebrates involves studies of individuals; there have been no studies at the population scale. Thus, available information provides limited insight on possible real-world effects at the regional or ocean scale. The most important aspect of potential impacts concerns how exposure to seismic survey sound ultimately affects invertebrate populations and their viability, including availability to fisheries.

Literature reviews of the effects of seismic and other underwater sound on invertebrates were provided by Moriyasu et al. (2004) and Payne et al. (2008). The following sections provide a synopsis of available information on the effects of exposure to seismic survey sound on species of decapod crustaceans and cephalopods, the two taxonomic groups of invertebrates on which most such studies have been conducted. The available information is from studies with variable degrees of scientific soundness and from anecdotal information. A more detailed review of the literature on the effects of seismic survey sound on invertebrates is provided in Appendix E.

Pathological Effects.—In water, lethal and sub-lethal injury to organisms exposed to seismic survey sound could depend on at least two features of the sound source: (1) the received peak pressure, and (2) the time required for the pressure to rise and decay. Generally, as received pressure increases, the period for the pressure to rise and decay decreases, and the chance of acute pathological effects increases. For the type of airgun array planned for the proposed program, the pathological (mortality) zone for crustaceans and cephalopods is expected to be within a few meters of the seismic source; however, very few specific data are available on levels of seismic signals that might damage these animals. This premise is based on the peak pressure and rise/decay time characteristics of seismic airgun arrays currently in use around the world.

Some studies have suggested that seismic survey sound has a limited pathological impact on early developmental stages of crustaceans (Pearson et al. 1994; Christian et al. 2003; DFO 2004). However, the impacts appear to be either temporary or insignificant compared to what occurs under natural conditions. Controlled field experiments on adult crustaceans (Christian et al. 2003, 2004; DFO 2004) and adult cephalopods (McCauley et al. 2000a,b) exposed to seismic survey sound have not resulted in any significant pathological impacts on the animals. It has been suggested that exposure to commercial seismic survey activities has injured giant squid (Guerra et al. 2004), but there is no evidence to support such claims.

Physiological Effects.—Physiological effects refer mainly to biochemical responses by marine invertebrates to acoustic stress. Such stress potentially could affect invertebrate populations by increasing

mortality or reducing reproductive success. Primary and secondary stress responses (i.e., changes in haemolymph levels of enzymes, proteins, etc.) of crustaceans have been noted several days or months after exposure to seismic survey sounds (Payne et al. 2007). The periods necessary for these biochemical changes to return to normal are variable and depend on numerous aspects of the biology of the species and of the sound stimulus.

Behavioral Effects.—There is increasing interest in assessing the possible direct and indirect effects of seismic and other sounds on invertebrate behavior, particularly in relation to the consequences for fisheries. Changes in behavior could potentially affect such aspects as reproductive success, distribution, susceptibility to predation, and catchability by fisheries. Studies investigating the possible behavioral effects of exposure to seismic survey sound on crustaceans and cephalopods have been conducted on both uncaged and caged animals. In some cases, invertebrates exhibited startle responses (e.g., squid in McCauley et al. 2000a,b). In other cases, no behavioral impacts were noted (e.g., crustaceans in Christian et al. 2003, 2004; DFO 2004). There have been anecdotal reports of reduced catch rates of shrimp shortly after exposure to seismic surveys; however, other studies have not observed any significant changes in shrimp catch rate (Andriguetto-Filho et al. 2005). Any adverse effects on crustacean and cephalopod behavior or fisheries attributable to seismic survey sound depend on the species in question and the nature of the fishery (season, duration, fishing method).

(7) Direct Effects on Seabirds and Their Significance

Investigations into the effects of airguns on seabirds are extremely limited. Stemp (1985) conducted opportunistic observations on the effects of seismic exploration on seabirds, and Lacroix et al. (2003) investigated the effect of seismic surveys on molting long-tailed ducks in the Beaufort Sea, Alaska. Stemp (1985) did not observe any effects of seismic testing, although he warned that his observations should not be extrapolated to areas with large concentrations of feeding or molting birds. In a more intensive and directed study, Lacroix et al. (2003) did not detect any effects of nearshore seismic exploration on molting long-tailed ducks in the inshore lagoon systems of Alaska's North Slope. Both aerial surveys and radio-tracking indicated that the proportion of ducks that stayed near their marking location from before to after seismic exploration was unaffected by proximity to seismic survey activities. Seismic activity also did not appear to change the diving intensity of long-tailed ducks significantly.

Birds might be affected slightly by seismic sounds from the proposed study, but the impacts are not expected to be significant to individual birds or their populations. The types of impacts that are possible are summarized below.

Localized, temporary displacement and disruption of feeding.—Such displacements would be similar to those caused by other large vessels that passed through the area. Agness et al. (2008) reported changes in behavior of Kittlitz's murrelets in the presence of large, fast-moving vessels, and suggested the possibility of biological effects due to increased energy expenditure by the birds. However, the *Langseth* travels at a relatively slow speed (8.5 km/h) during seismic acquisition.

Modified prey abundance.—It is unlikely that prey species for birds will be affected by seismic activities to a degree that affects the foraging success of birds. If prey species exhibit avoidance of the ship, the avoidance is expected to be transitory and limited to a very small portion of a bird's foraging range.

Disturbance to breeding birds.—A vessel (seismic or otherwise) that approaches too close to a breeding colony could disturb adult birds from nests in response to sonic or visual stimuli. There is little potential for disturbance of breeding birds during the proposed survey, as the *Langseth* will work at least 30 km from shore.

Egg and nestling mortality.—Disturbance of adult birds from nests can lead to egg or nestling mortality *via* temperature stress or predation. There is little potential for this during the proposed survey, as the *Langseth* will work at least 30 km from shore.

Chance injury or mortality.—Many species of marine birds feed by diving to depths of several meters or more. Flocks of feeding birds may consist of hundreds or even thousands of individuals. Also, some species of seabirds escape from boats by diving when the boat gets too close. It is possible that, during the course of normal feeding or escape behavior, some birds could be near enough to an airgun to be injured by a pulse. Although no specific information is available about the circumstances (if any) where this might occur, the negligible aversive reactions of birds to airguns (see above) suggest that a bird would have to be very close to any airgun to receive a pulse with sufficient energy to cause injury, if that is possible at all.

Induced injury or mortality.—If it disorients, injures, or kills prey species, or otherwise increases the availability of prey species to marine birds, a seismic survey could attract birds. Birds drawn too close to an airgun may be at risk of injury. However, available evidence from other seismic surveys utilizing airguns has not shown a pattern of fish (or other prey) kills from airguns [see § IV(5), above]. Thus, the potential that birds would be attracted and subsequently injured by the proposed seismic survey appears very low.

(8) Indirect Effects on Marine Mammals, Sea Turtles, and Their Significance

The proposed airgun operations will not result in any permanent impact on habitats used by marine mammals or sea turtles, or to the food sources they use. The main impact issue associated with the proposed activities will be temporarily elevated noise levels and the associated direct effects on marine mammals and sea turtles, as discussed above.

During the seismic study, only a small fraction of the available habitat would be ensonified at any given time. Disturbance to fish species and invertebrates would be short-term, and fish would return to their pre-disturbance behavior once the seismic activity ceased [see § IV(5) and § IV(6), above]. Thus, the proposed survey would have little impact on the abilities of marine mammals or sea turtles to feed in the area where seismic work is planned.

Some mysticetes feed on concentrations of zooplankton. A reaction by zooplankton to a seismic impulse would only be relevant to whales if it caused a concentration of zooplankton to scatter. Pressure changes of sufficient magnitude to cause that type of reaction would probably occur only very close to the source. Impacts on zooplankton behavior are predicted to be negligible, and that would translate into negligible impacts on those mysticetes that feed on zooplankton.

(9) Cumulative Effects

Cumulative effects refer to the impacts on the environment that result from a combination of past, existing, and reasonably foreseeable projects and human activities. Causal agents of cumulative effects can include multiple causes, multiple effects, effects of activities in more than one locale, and recurring events. Human activities in the region of the proposed seismic survey in and near the proposed survey areas include commercial and recreational vessel traffic and fishing.

(a) Vessel Traffic

Vessel traffic in the proposed study area will consist of fishing vessels, as well as other commercial (cargo), and pleasure vessels.

Large Vessel Traffic.—Port container traffic is high along the coastline due west of the study area. At least 10 important ports occur between 10°N and 10°S, with overall port container traffic of more than

5.3 million twenty-foot equivalent units (TEUs) recorded in 2008 (AAPA 2010). The main port of the Pacific coast of Costa Rica is Puerto Caldera; it recorded container traffic of 169,827 and 127,658 TEUs in 2008 and 2009, respectively (AAPA 2010).

The port activity reflects the importance of the area for international trade. Several major international marine trade routes pass near the study area, leading to and from the Panama Canal, which connects the Pacific with the Atlantic Ocean. The Panama Canal is one of the world's major shipping routes and is a significant focus for marine shipping to Central America (Rodrigue et al. 2009).

Vessel traffic in the proposed study area will include bulk vessels, oil tankers, and container vessels. The most important vessel traffic will consist of bulk carrier vessels, which comprise 40% of the world's merchant fleets and range in size from single-hold mini-bulkers to ships able to carry 365,000 metric tons of deadweight. The Amver (from its original name Atlantic Merchant Vessel Emergency Reporting) system, a computer-based and voluntary global ship reporting system used worldwide by search and rescue authorities used by some 12,000 participating ships from over 140 nations (USCG 2010), gives an indication of the merchant ship traffic (over 100 gross tons) near the study area during the period of interest. Based on Amver monthly plots, ship density in the area during April and May would consist of a maximum of 4 vessels per month in the study area and 15–49 vessels per month west of the study area.

Vessel traffic in the area may also include military vessels. On 1 July 2010, Costa Rica's National Assembly authorized as many as 46 U.S. warships to operate in its territorial waters as part of anti-narcotics operations (Latin America Press 2010). To date, only one U.S. vessel has called, docking at the Costa Rican port of Limon for a 10-day visit. The agreement extends through the end of the year. It is unknown if it will be renewed for 2011 (Johnson 2010)

Recreational Vessel Traffic.—Cocos Island, a National Park located 530 km off Costa Rica, is visited by ~1100 people annually, mainly between March and May. The island can be reached by commercial launch or small boat from the port of Puntarenas (UNEP-WCMC 2008). New facilities at the port of Puntarenas will likely attract more cruises to the area. The new facilities have replaced aging Puerto Caldera as the Pacific stopover point (CRTTB 2010a).

Cocos Island is a frequented dive site. Four different live-aboard dive vessels are involved, operating every month of the year; one operator with three vessels 28–39 m long capable of carrying 14–18 passengers has averaged 42 trips annually during 2004–2009 (Undersea Hunter Group 2010), and the other operator's 33-m vessel has 35 trips to Cocos scheduled for 2010 (Aggressor Fleet 2010). Isla del Caño Biological Reserve, located ~20 km off the Osa Peninsula close to the proposed survey area, is also a popular dive site. Five dive sites are open to the public, and only 10 divers are allowed at each site at a time. Dive trips to the island occur daily (CRTTB 2010b).

Costa Rica is one of the top whale-watching destinations in Latin America, and its popularity is growing rapidly. Between 1998 and 2006, the number of whale-watchers in the country increased from 1227 to 105,617, representing a 74.5% average annual increase in the total number of whale-watchers. Growth was so rapid that concerns have been expressed about the number of boats operating near whales (Hoyt and Iñiguez 2008). Most boats used for whale-watching are adapted fishing boats or inflatables adapted from research use, and most boats are owned by single operators (Hoyt and Iñiguez 2008). Several tour operators offer whale-watching trips in Drake Bay, around the Osa Peninsula, and off Isla del Caño. The main whale-watching species are the humpback whale, dolphins (bottlenose, pantropical, spinner), false killer whale and blue whales (offshore only).

Vessel Noise.—Vessel noise could affect marine animals in the proposed study area. Shipping noise generally dominates ambient noise at frequencies from 20 to 300 Hz (Richardson et al. 1995). Baleen whales are thought to be more sensitive to sound at these low frequencies than are toothed whales,

possibly causing localized avoidance by marine mammals of commercial ships, and the seismic vessel, operating in and near the proposed seismic survey area.

Reactions of gray and humpback whales to vessels have been studied, and there is limited information available about the reactions of right whales and orquals (fin, blue, and minke whales). Reactions of humpback whales to boats are variable, ranging from approach to avoidance (Payne 1978; Salden 1993). Baker et al. (1982, 1983) and Baker and Herman (1989) found humpbacks often move away when vessels are within several kilometers. Humpbacks seem less likely to react overtly when actively feeding than when resting or engaged in other activities (Krieger and Wing 1984, 1986).

Many odontocetes show considerable tolerance of vessel traffic, although they sometimes react at long distances if confined by ice or shallow water, if previously harassed by vessels, or have had little or no recent exposure to ships (Richardson et al. 1995). Dolphins of many species tolerate and sometimes approach vessels. Some dolphin species approach moving vessels to ride the bow or stern waves (Williams et al. 1992). Killer whales rarely show avoidance to boats within 400 m (Duffus and Dearden 1993), but when more than one boat is nearby, they sometimes swim faster towards less confined waters (Kruse 1991; Williams et al. 2002a,b). Sperm whales can often be approached with small motorized or sailing vessels (Papastavrou et al. 1989), but sometimes avoid outboard-powered whale watching vessels up to 2 km away (J. McGibbon *in* Cawthorn 1992). Resident sperm whales that are repeatedly exposed to small vessels show subtle changes in various measures of behavior, and transient individuals (which presumably have less exposure to vessels) react more strongly (Richter et al. 2003, 2006). There are few data on the behavioral reactions of beaked whales to vessel noise, though they seem to avoid approaching vessels (e.g., Würsig et al. 1998) or dive for an extended period when approached by a vessel (e.g., Kasuya 1986). Based on a single observation, Aguilar-Soto et al. (2006) suggest foraging efficiency of Cuvier's beaked whales may be reduced by close approach of vessels.

Vessel Collisions.—Another concern with vessel traffic is the potential for striking marine mammals. Jensen and Silber (2004) assembled a database of whale strikes reported throughout the world. Of the 292 records of confirmed or possible ship strikes to large whales, most were reported in North America, but this may be an artifact of data collection procedures and/or decreased reporting in other global jurisdictions. The probability of a ship strike resulting in a lethal injury (mortality or severe injury) of a large cetacean increases with ship speed (Laist et al. 2001; Vanderlaan and Taggart 2007). Most lethal and severe injuries to large whales occur when vessels travel 14 kt or faster, and the probability of severe or lethal injury to a whale approaches 100% in the event of a direct strike when a ship is traveling faster than 15 kt (Laist et al. 2001; Vanderlaan and Taggart 2007). The probability of a ship strike is a function of vessel density, animal density, and vessel speed. Given the slow speed of the seismic vessel (~8.5 km/h or 4.6 kt), the probability of injurious or fatal strikes with mammals during the proposed operations is considered to be low. Vessels traveling at speeds >4 km/h are more likely to collide with turtles at sea, which can result in turtle injury or death (Hazel et al. 2007). Large species like leatherbacks that spend extended periods near the surface are particularly susceptible to ship strikes.

The total transit distance by L-DEO's vessel (a maximum of ~2505 km) will be minimal relative to total transit length for vessels operating in the study area during April–May 2011. Thus, the combination of L-DEO's operations with the existing shipping and fishing operations is expected to produce only a negligible increase in overall ship disturbance effects on marine mammals.

(b) Fisheries

The primary contributions of fishing to potential cumulative impacts on marine mammals and sea turtles involve direct removal of prey items, vessel noise, potential entanglement, and bycatch. There may be some localized avoidance by marine mammals of fishing vessels near the seismic area. Also,

bycatch and entanglement in fishing gear can lead to mortality of marine mammals and sea turtles (see below). Commercial fishing in the ETP takes place in two Food and Agriculture Organization (FAO) areas: the eastern central Pacific and the southeast Pacific.

Commercial Fisheries.—The most important fisheries in Pacific EEZ waters in terms of catch volume is the tuna fishery, with purse seiners of the international fleet operating in EEZ waters under a license system (Sea Around Us Project 2010b). Reported landings in Costa Rica waters are relatively small (Table 5). The largest catch is the tuna fishery with ~24 purse-seiners from the international fleet operating in Costa Rica’s EEZ. The total catch from purse seine fisheries represents a third of the landings from commercial fisheries for the Pacific EEZ of Costa Rica (Table 5).

TABLE 5. Commercial fisheries landings (tons) in 2006 by gear type for the Pacific EEZ of Costa Rica. Source: Sea Around Us Project (20010b).

EEZ	Total	Purse seines	Shrimp trawls	Hooks, gorges ¹	Bottom trawls	Gillnets	Mid-water trawls	Seine nets	Other
Costa Rica	10274	3857	1229	2189	847	364	152	267	1369

¹ Includes squid hooks but not longlines

The second largest-volume fisheries in Costa Rica involve 588 registered longline vessels of various sizes fishing beyond the 12-n.mi. territorial water limit, with larger vessels up to 24 m in length usually fishing beyond Costa Rica’s EEZ. There are 2421 officially registered vessels involved in the small-scale coastal demersal and pelagic fishery, but more boats probably operate illegally (FAO 2004). About 65 vessels are involved in the shrimp fishery using bottom trawlers, although the decline in catches caused by over-fishing, and increased fuel prices, have forced a number of them to remain in port. Only two purse seiners fish for sardine in the coastal zone.

Recreational Fisheries.—Costa Rica has some of the largest fleets of sport fishing boats. Recreational fishing for demersal and pelagic species is of growing importance. Sport fishing’s target species include sailfish, marlin, tuna, snook, tarpon, wahoo, dolphinfish, snapper, and barracuda. Approximately 100 vessels, mainly fiberglass, measuring up to 15 m in length and fitted with inboard motors, operate in this fishery (FAO 2004). There are about a half a dozen sport fishing operators scattered between Drake Bay, Golfo Dulce, Golfito, Puerto Jimenez, and Zancudo Beach (CRFR 2010).

It is not expected that L-DEO’s operations will have a significant impact on commercial or recreational fisheries at the survey site. L-DEO will minimize potential negative impacts on the fisheries by avoiding areas where fishing is actively underway or coordinating with fishers encountered. Two or three small fishing vessels and crews will be contracted locally to accompany the *Langseth* and avoid conflict with other small fishing vessels. Seismic operations in the study area are expected to have a negligible contribution to cumulative impacts when compared to that of commercial and recreational fisheries activities.

(c) Oil and Gas Activities and Seismic Surveys

In most Latin American countries, hydrocarbons are an asset of the state, and state-owned oil and gas companies are responsible for conducting extraction and development activities. In recent years, however, several countries have introduced regulatory reforms to allow for increased participation of the private sector in oil and gas production activities. Costa Rica, despite establishing oil and gas licensing blocks in 1994 and opening them to bid to foreign companies in 1997, effectively produces no oil. In 2002, the then-newly-elected President Abel Pacheco de la Espriella essentially declared Costa Rica free of oil exploration and development. The election of President Oscar Arias Sanchez in 2006 has not changed this de facto policy.

There were two L-DEO seismic surveys off Costa Rica in recent years, one using the 36-airgun array that extended from Drake Bay north to Nicaragua in January 2008, and one using a small source (three GI guns) that extended from the Nicoya Peninsula north to Honduras in November–December 2004. Also, Scripps Institution of Oceanography conducted a low-energy (two GI-gun) survey during October–November 2010 in deep water, beginning ~200 km offshore from Costa Rica and moving south from there. Those surveys and the proposed seismic survey in Drake Bay in April–May 2011 are expected to have a negligible cumulative impact because each occurred for a short time (~1 month), and they were separated by relatively long times.

(d) Incidental Mortality

The fishing industry has adverse effects on marine mammals and sea turtles. For example, the average annual mortality of dolphins as bycatch in the eastern Pacific Ocean (EPO) during 2000–2005 was 1550 (IATTC 2010). This estimate decreased to an average bycatch of 862 dolphins in 2006–2007, but increased slightly to 1169 dolphins in 2008 (IATTC 2010). At its peak in 1986, the annual estimate of dolphin mortality through bycatch in the EPO was 132,169 (IATTC 2010). Initial systematic studies of cetaceans in the ETP were prompted by the incidental killing of dolphins in the purse-seine fishery for yellowfin tuna, *Thunnus albacares*, in the area (Smith 1983). The main cetacean species that have been affected by the fishery are pantropical spotted dolphins and spinner dolphins (Smith 1983). Short-beaked common dolphins, striped dolphins, bottlenose dolphins, Fraser's dolphins, rough-toothed dolphins, and short-finned pilot whales have also been killed in the fishery (e.g., Hall and Boyer 1989). Despite a reduction in bycatch in recent years (IATTC 2008), populations of offshore spotted dolphins and eastern spinner dolphins have not yet recovered (Gerrodette and Forcada 2005). Wade et al. (2007) proposed that the lack of recovery of the pantropical spotted and spinner dolphins was as likely caused by the fishery as it was by changes in the ecosystem, and warned that the purse-seine fishery could impact dolphin stocks beyond what can be observed through the analysis of fishery mortality.

Commercial fisheries may also accidentally entangle and drown or injure other cetacean species during fishing operations or by lost and discarded fishing gear (e.g., Northridge and Hofman 1999). Humpback whales, perhaps because of their abundance in coastal waters where nets are commonly used or because of the many barnacles they carry, seem to be extremely vulnerable to entanglement in fishing gear (Lien 2002). Trites et al. (1997) suggested that fisheries might indirectly compete with cetaceans by reducing the amount of primary production accessible to cetaceans, thereby negatively affecting their numbers.

Incidental catch in fisheries is also widely recognized as a major mortality factor for sea turtles. An estimated average of 37 sea turtles died as a result of their incidental capture by purse-seine fishing vessels in the EPO during 2001–2008 (IATTC 2008). Sea turtle bycatch in longline fishing operations was evaluated off the Pacific coast of Costa Rica from October 1991–February 1992 (Segura and Arauz 1995). A total of 31 sea turtles were caught during 13 of 27 longline deployments, 29 of which were olive ridleys and 2 of which were green turtles (Segura and Arauz 1995). The mortality rate of olive ridleys was 10.3% (Segura and Arauz 1995).

During an observer program on shrimp trawlers along the Pacific coast of Costa Rica, 281 turtles were caught in nets during 2557 h of observation (Arauz et al. 1998). Most of the captured turtles were olive ridleys (90%), followed by green turtles (9.6%), and hawksbills (0.4%). Arauz et al. (1998) estimated the mortality rates attributable to shrimp nets to be 37.6% for olive ridleys and 50% for green turtles. The annual incidental catch of turtles by the shrimp fleet along the Pacific coast of Costa Rica is estimated at 15,631 turtles. Arauz et al. (1998) noted that Costa Rica has the highest recorded average CPUE rate for sea turtles in the world, and suggested that countries in the ETP use Turtle Excluder Devices to reduce turtle bycatch.

(e) Summary of Cumulative Impacts to Marine Mammals

Impacts of the proposed seismic survey in Costa Rica EEZ waters are expected to be no more than a very minor (and short-term) increment when viewed in light of other human activities within the study area. Unlike some other ongoing and routine activities (e.g., fishing), the proposed seismic activities are not expected to result in injuries or deaths of marine mammals. Although the sounds from the seismic survey will have higher source levels than those of some other human activities in the area, airgun operations will take place only for a total of <30 days, in contrast to other noise-producing activities that occur continuously over extended periods.

As previously discussed, L-DEO's airgun operations are unlikely to cause any large-scale or prolonged effects. Thus, the combination of L-DEO's operations with the existing Navy exercises, shipping, marine tourism, and fishing operations is expected to produce only a negligible increase in overall disturbance effects on marine mammals.

(f) Cumulative Impacts to Sea Turtles

Major threats to sea turtles include hunting and poaching, the collection of eggs, coastal development, increased tourism including beaches obstructed with lights and chairs, beach sand mining, pedestrian traffic, oil spills, ship strikes, entanglement in fishing gear (see further, above), ingestion of plastic and marine garbage, and destruction of feeding habitat in coral reefs and seagrass beds (Horrocks 1992; Marcovaldi et al. 2003). Unlike those activities, the low-energy seismic operations will not result in sea turtle injury or mortality. Given the planned mitigation measures, any short-term disturbance caused by the seismic surveys will be a negligible contribution to cumulative impacts.

(10) Unavoidable Impacts

Unavoidable impacts to the species of marine mammals and turtles occurring in the proposed study area will be limited to short-term, localized changes in behavior of individuals and possibly a few occurrences of TTS in marine mammals that approach close to the operating airgun array. For marine mammals, some of the changes in behavior may be sufficient to fall within the MMPA definition of "Level B Harassment" (behavioral disturbance; no serious injury or mortality). TTS, if it occurs, will be limited to a few individuals, is a temporary phenomenon that does not involve injury, and is unlikely to have long term consequences for the few individuals involved. No long-term or significant impacts are expected on any of these individual marine mammals or turtles, or on the populations to which they belong. Effects on recruitment or survival are expected to be (at most) negligible.

(11) Coordination with Other Agencies and Processes

This EA has been prepared by LGL on behalf of NSF pursuant to EO 12114. Potential impacts to endangered species and critical habitat have also been assessed in the document; therefore, it will be used to support the ESA Section 7 consultation process with NMFS and USFWS. This document will also be used as supporting documentation for an IHA application submitted by L-DEO to NMFS, under the U.S. MMPA, for "taking by harassment" (disturbance) of small numbers of marine mammals, for this proposed seismic survey. As this project will occur in waters outside of the U.S., this document does not address Essential Fish Habitat (EFH), the Coastal Zone Management Act (CZMA), the National Historic Preservation Act, or the National Marine Sanctuary Act (NMSA).

Dr. Laura May-Collado of the University of Puerto Rico was contacted concerning abundance and distribution of cetaceans in Costa Rica, in particular information on monthly humpback whale occurrence off Costa Rica. Kristen Rasmussen of the Cascadia Research Collective was also contacted regarding monthly humpback whale occurrence. NSF and L-DEO will coordinate the planned marine mammal

monitoring program associated with the seismic survey off Costa Rica with other parties that may have interest in this area. L-DEO and NSF have coordinated, and will continue to coordinate, with applicable Federal agencies (e.g., NMFS), and will comply with their requirements.

Alternative Action: Another Time

An alternative to issuing the IHA for the period requested, and to conducting the project then, is to issue the IHA for another time, and to conduct the project at that alternative time. The proposed dates for the cruise (April–May 2011) are the dates when the personnel and equipment essential to meet the overall project objectives are available.

Marine mammals and sea turtles are expected to be found throughout the proposed study area. Many cetaceans are widespread in the survey area throughout the year. Others (some baleen whales) are present in winter and possibly migrate through during spring and fall. Humpback whales occupy Drake Bay throughout the winter, but most if not all will have migrated north before the proposed survey. Some leatherback, green, and olive ridley nesting beaches occur near the proposed survey area, but the biggest are located >150 km to the north. The survey is scheduled after the peak nesting periods for leatherbacks (October–March), green turtles (October–November), and olive ridleys (September–December). Foraging or migrating individuals could be encountered at any time of year.

No Action Alternative

An alternative to conducting the proposed activities is the “No Action” alternative, i.e., do not issue an IHA and do not conduct the operations. If the research were not conducted, the “No Action” alternative would result in no disturbance to marine mammals or sea turtles attributable to the proposed activities, but geological data of considerable scientific value and relevance in understanding earthquake potential and tsunamis (see § I) would not be acquired.

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APPENDIX A: L-DEO MODELING FOR MARINE SEISMIC SOURCE ARRAYS FOR SPECIES MITIGATION⁴

Summary

To ensure that U.S. academic marine seismic activity does not adversely affect marine wildlife stocks, federal regulations controlling the levels of sound to which those stocks may be exposed are closely followed. These regulations include the establishment of various exclusion zones, which are defined by a priori modeling of the propagation of sound from the proposed seismic source array. To provide realistic results, modeling must include free surface and array effects. This is best accomplished when the near field signature of each airgun array element is propagated separately to the far field and the results summed there. The far field signatures are analyzed to provide measurements that characterize the source's energy as a function of distance and direction. The measure currently required for marine wildlife mitigation is root-mean-square [RMS]. While RMS is an appropriate measure for lengthy signals, it may not accurately represent the energy and impact of a short, impulsive signal. When a comparison is made between RMS and several other metrics, it is apparent that RMS is the least consistent.

Introduction

Modern marine seismic profiling is typically carried out using arrays of airguns as the acoustic source. Unlike single airguns or explosive sources, the physical extent and distributed quality of these arrays produce an asymmetric pressure field, which cannot be described accurately by a simple, rule-of-thumb approach.

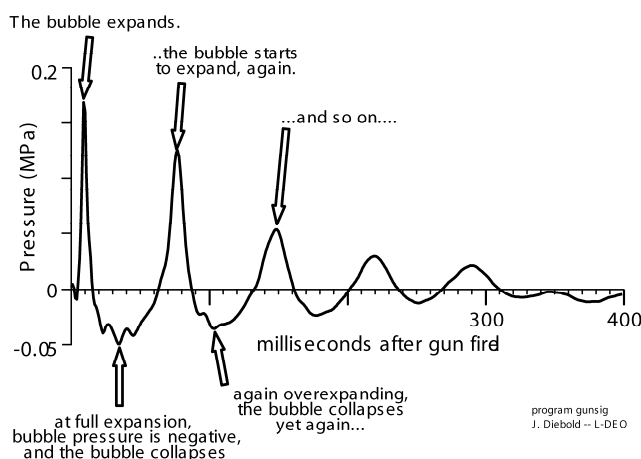


FIGURE A-1. Recording of a single airgun pulse made during R/V *EWING* tests, 1990.

⁴ By **John Diebold**, L-DEO, revised May 2006.

This wavetrain can be seen in its true form only very close to the airgun and it is called the “near field” signal. Airguns are usually towed at a shallow depth (3–9 m) beneath the sea surface, from which sound waves are negatively reflected, and at any significant distance from the airgun, both the direct and its negatively reflected “ghost” are seen, one right after the other. This ghosting imposes a strong and very predictable filter on the received arrivals.

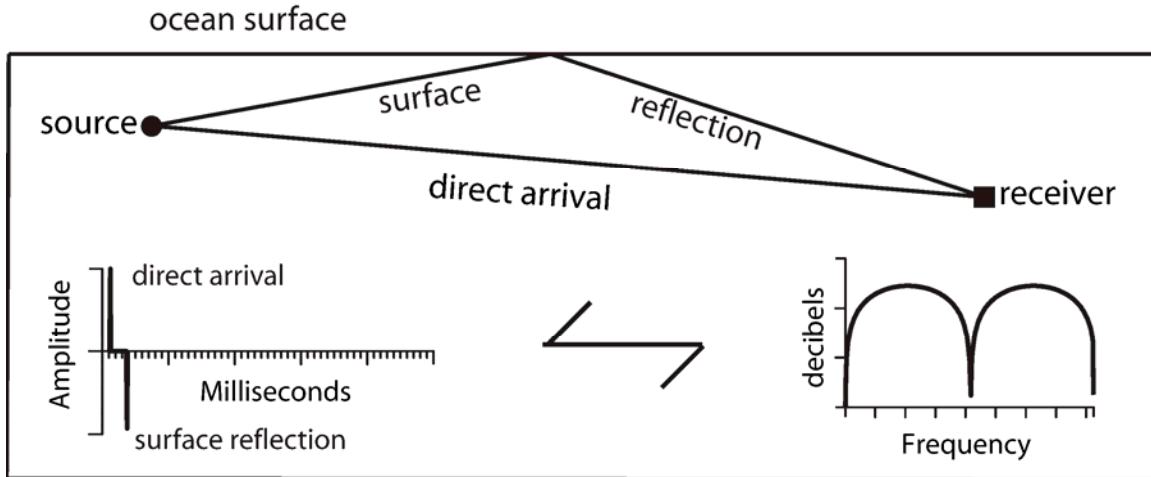


FIGURE A-2. Top: pathways for direct and surface-reflected arrivals used in modeling. Bottom: direct and ghosted arrival amplitudes in the time domain can be considered an operator whose spectrum is predictable, and which acts as a filter on the spectrum of the intrinsic near field source, whatever that may be.

The time interval between the arrivals of the direct and surface-reflected signals depends on the position of observation; it is greatest at any position directly beneath the source. Depending on the location of the point of observation relative to the source array, the appearance and strength of the signal can be extremely variable. In the comparison below, two observation points were chosen, equally distant from a 20-airgun array.

The differences here are caused by two effects. One is directionality resulting from the physical dimensions of the array. The other effect is that the surface ghosting imposes a strong filter on the near field source signatures, and the shape of this filter is controlled by the relative positions of sources and receivers.

Modeling

Since the sum of the direct and the surface-reflected signals varies according to position, modeling can only be carried out correctly when near-field source signatures are used, and propagation along all of the pathways between the source and the receiver is considered separately. In the simple half-space model illustrated above (Fig. 3), there are only two pathways. When an array of sources is used, travel time, spreading and reflection losses are calculated for each pathway and for each source element separately. According to the exact distance between the point of observation and the particular airgun, each element’s near-field signal is appropriately scaled in amplitude and shifted in time. Then the process is repeated to produce the free surface “ghost” signal of each airgun, and the results are summed.

For R/V *EWING* mitigation, the near-field signatures were calculated by extrapolation from a set of measured signals received from Teledyne in 1981. Results of this modeling have been compared to a great number of published signals, and the amplitudes of the library’s signals adjusted to provide a close match. Since peak values are highly dependent on an impulsive signal’s high frequency content, the comparisons are most accurately made in the spectral domain.

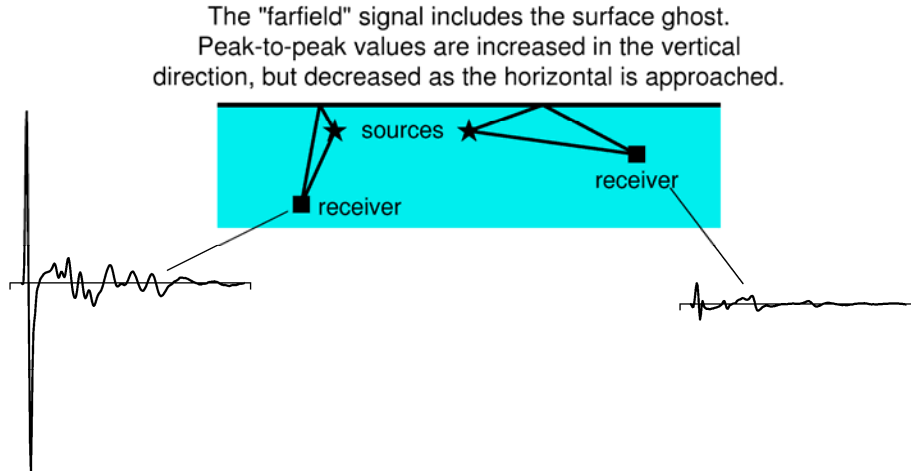


FIGURE 3. The far field signature of a 20-airgun array modeled at two receiver positions equidistant from the center of the array. Differences are due to array directivity and surface ghosting effects.

Few, if any, of the published examples include airguns with volumes as large as those often included in *EWING*'s source arrays. There are several very good reasons for this (and for the inclusion of such sizes in *EWING* arrays.) Principal among these was the observation by W. Dragoset of Western Geophysical [pers. comm., 1990] that the characteristics of the Bolt 1500C air exhaust ports are such that throttling occurs when air chambers above a certain size are used. The result of this is that peak amplitudes increase only slightly, so that the efficiency of these airguns diminishes with increasing volume. On the other hand, bubble pulse periods do increase according to theory, so that the benefit of larger sizes in array tuning is undiminished. The decrease in efficiency was borne out during testing of *EWING*'s airguns during the 1990 shakedown legs (Fig. 4).

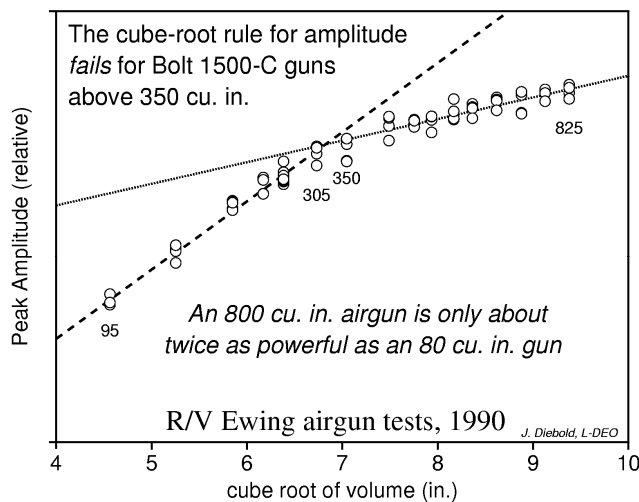


FIGURE 4. R/V *EWING* test results, 1990.

Near-field signatures can be created by a number of commercially available modeling packages, all based in part on the work of Ziolkowski (1978). Those packages were not used for *EWING* modeling for two reasons: cost and accuracy. As Figure 5 demonstrates, PGS' Nucleus/Masomo software does not accurately model the large Bolt airguns used in *EWING* arrays:

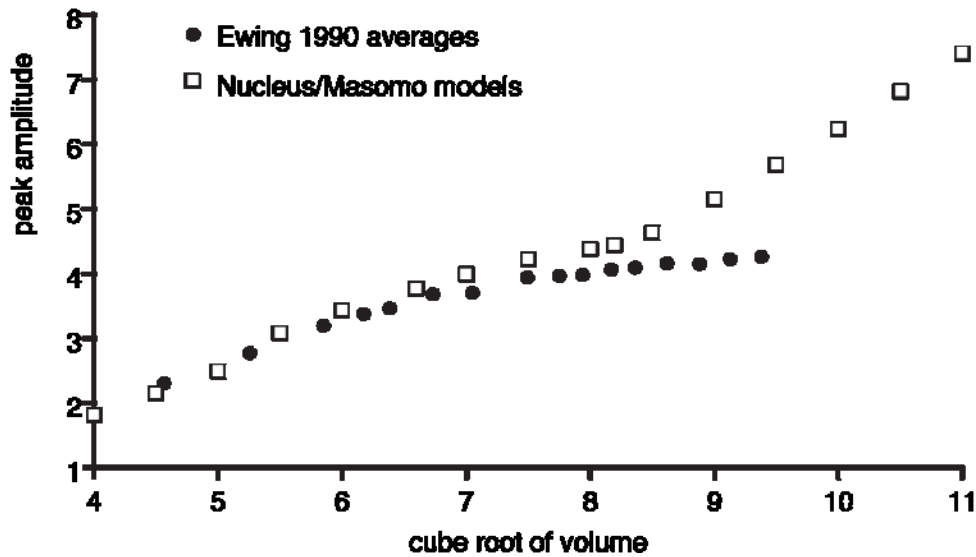


FIGURE 5. Nucleus/Masomo overestimates peak values for large Bolt airguns.

The R/V *LANGSETH* will have source arrays that are quite different than *EWING*'s: (1) maximum airgun volume will be much smaller, (2) two different kinds of airguns will be combined, (3) airguns will be towed closer together, and (4) two-element "clusters" will be included. The latter three of these features are unsupported by the homebrew modeling used for *EWING* arrays, and we are currently using PGS' Nucleus/Masomo software for this purpose [<http://www.pgs.com/business/products/nucleus/>]. Some of the examples below have been created using the simpler *EWING* models, however.

The modeling procedure can be summarized as follows:

- 1) Define the airgun array in terms of the size and relative location of each airgun [X, Y, Z].
- 2) Create near field ["notional"] signatures for each airgun.
- 3) Decide upon a 2D mesh of points, for example within a plane intersecting the center of the airgun array. A typical mesh is 100 x 50.
- 4) For each of the points in the mesh, create the signal that would be observed there when every airgun in the array was fired simultaneously.
- 5) For that signal, determine the desired statistic: Peak-to-peak dB, Peak dB, RMS dB, maximum psi, etc.
- 6) Contour the mesh.

Most of the work lies in step 4) which has steps of its own:

- a) For each of the airguns in the array, determine the distances, and thus the time-of-flight between the airgun and the mesh point, as well as the free surface ghost "image" of the airgun and the mesh point.

- b) Scale and shift this airgun’s near-field signal, dividing by the point-to-point distance and moving forward in time according to time-of-flight.
- c) Scale and shift the near-field signal’s ghost image, as above, in addition multiplying by the free surface reflection coefficient [typically between -.9 and -.95].
- d) Sum the results. For the *EWING* 20-airgun array, 40 scaled and shifted signals were created and summed for each mesh point.

Units

Exploration industry standard units for seismic source pressures are Bar-meters; an intuitively attractive measure in atmospheres [bars] at one meter from the center of the source array. In SI units, 10 Bar = 1 megaPascal = 10^{-12} μ Pascal. To convert Bar-m to decibels with respect to μ Pascal–m we use this formula:

$$\text{dB [wrt } \mu\text{Pascal –m]} = 220 + 20 \log^{10}(\text{B-m})$$

RMS dB and the exclusion zone

A variety of means are used to characterize the strength of seismic source signals. Peak, peak-to-peak, and total energy levels are easy to measure, but historically, all of the research on acoustic avoidance behavior of marine mammals has quantified the sound levels in terms of RMS, a measure which is entirely appropriate for many acoustic signals found in the marine environment (e.g., shipping noise, Navy sonar, etc.). Although it is less appropriate for impulsive airgun signals, the RMS measure has been used in most published studies anyway (cf. Malme et al. 1983a,b), so that meaningful comparisons could be made. The protocols used for the RMS calculation in most published research are diagrammed below (Fig. 6), applied to the signal predicted by our modeling for a point 4000 m aft of *EWING*’s 20 airgun array, at a depth of 1200 m.

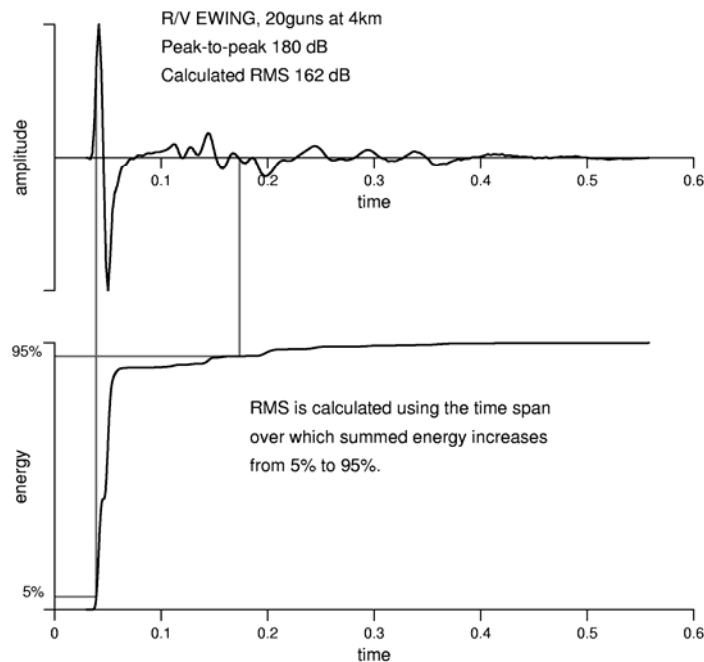


FIGURE 6. The “standard” 90% RMS calculation. Energy is summed as a function of time for the entire signal. From this result, the times at which 5% and 95% of the total energy are attained define the RMS integration window.

This difference between the peak-to-peak and RMS dB levels for the same signal falls within the 16-18 dB averages reported for impulsive airgun signals by Greene (1997) and McCauley (1998).

Calculating the exclusion zone

R/V *EWING* source arrays were intended and designed for 2D seismic reflection and refraction work, and were, consequentially, highly directional, focusing energy downwards and in line with the ship's track direction.

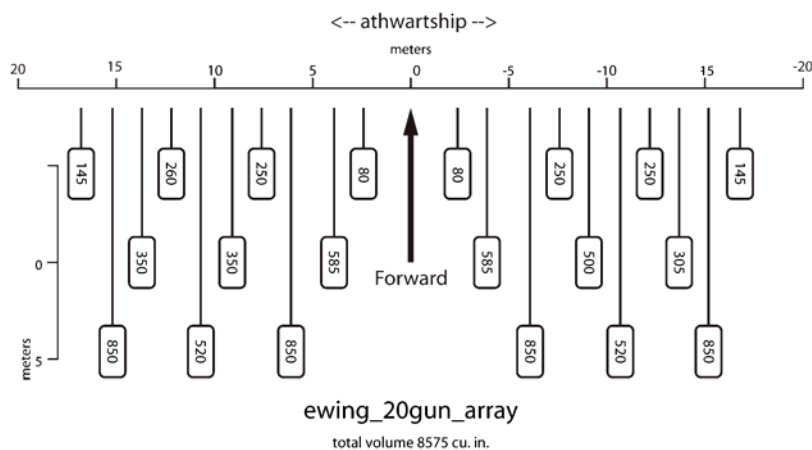


FIGURE 7. Plan view of the 20-airgun array used to calculate Fig. 3, 4, and 6. Tow depth is 7.5 m.

The RMS calculation is applied to the mesh point signatures resulting from the modeling process described above. When the 90% RMS levels are contoured, the directional nature of the standard R/V *EWING* source array is obvious (Fig. 8).

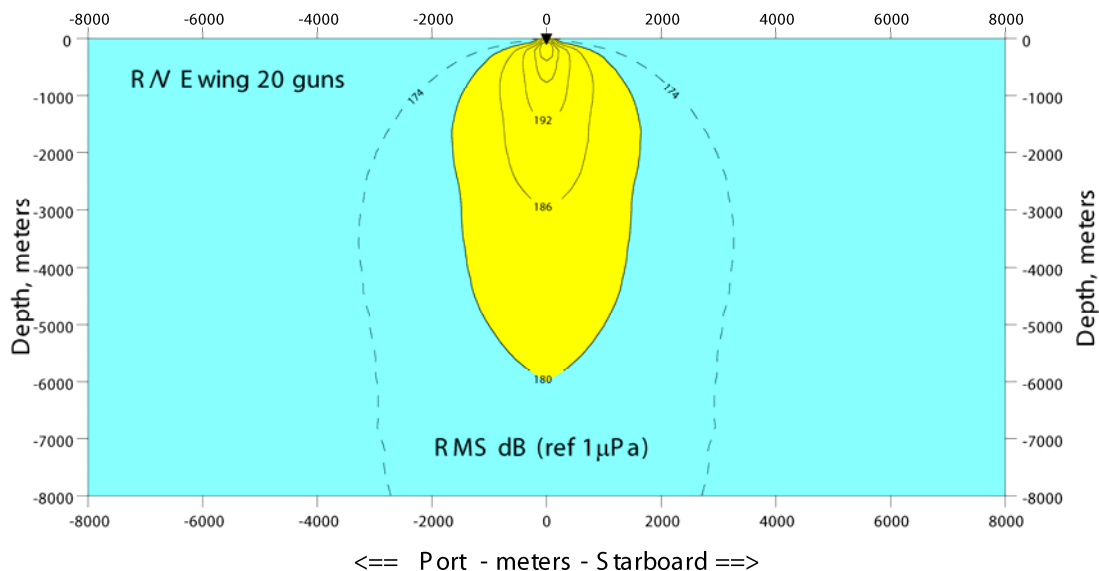


FIGURE 8a. 90% RMS isopleths calculated in the crosstrack direction for a 20-airgun array. Yellow denotes RMS values >180 dB.

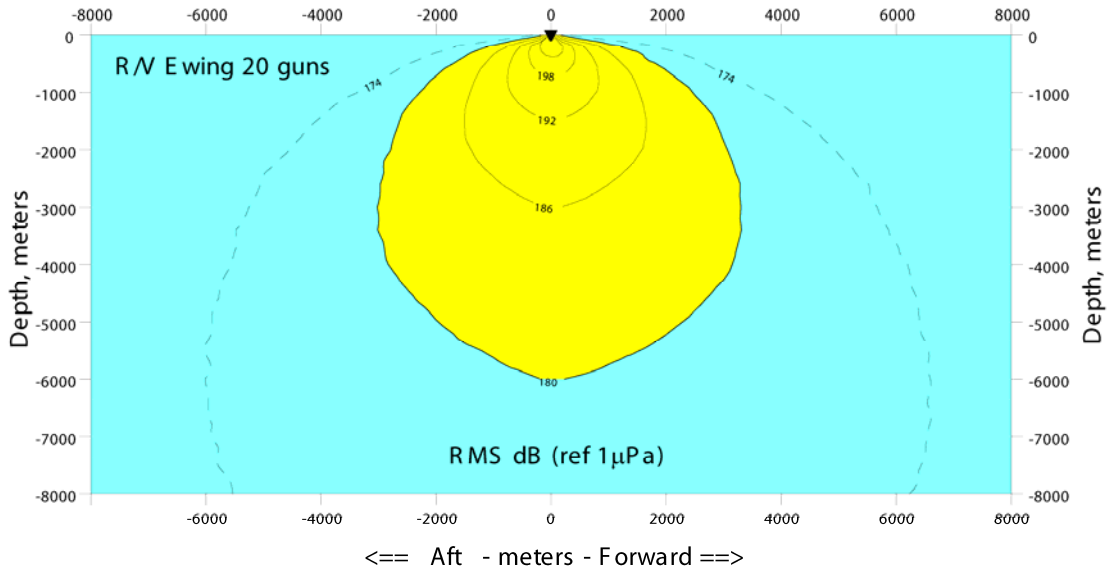


FIGURE 8b. 90% RMS isopleths calculated in the along track direction for a 20-airun array. Yellow denotes RMS values >180 dB.

Since the fore-and-aft extent of *EWING*'s array is smaller than the athwartship dimension, directionality is less marked in front of and behind the array. The distances therefore to the 180 dB contours, or isopleths, are greater in the fore-and-aft than athwartship directions, and we use these worst case distances to determine exclusion zones.

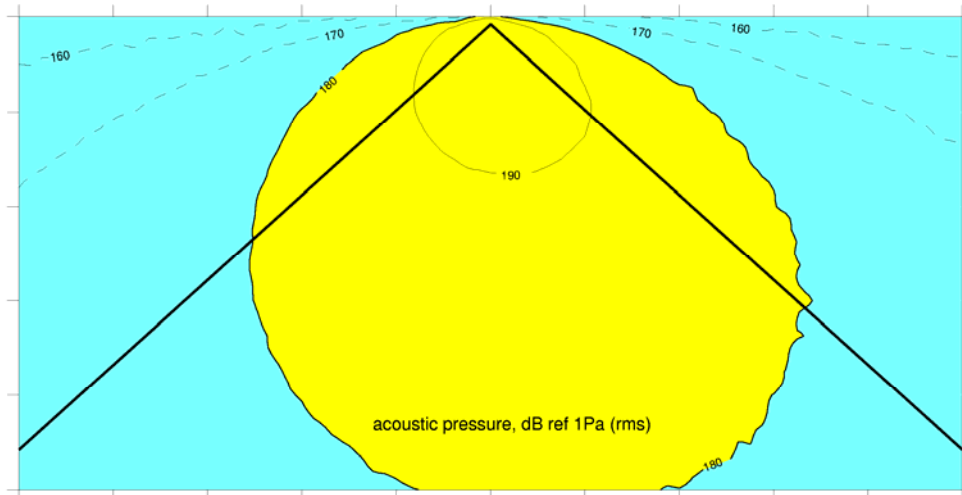


FIGURE 9. The pathways in offset and depth which intersect maximum-radius isopleths. These are used to calculate radii for various 90% RMS levels.

This modeling approach includes two important simplifications: (1) the assumption of a homogeneous water column (i.e., raypaths are linear), and (2) that interactions with the seafloor are not included. In deep water (i.e., 1000 m and greater) our predicted exclusion zones are conservatively greater than those determined by actual calibration (Tolstoy et al. 2004). In shallow water (100 m and

less) water column reverberations and constructive interference contribute to increase actual levels over those predicted by the modeling techniques described here.

Problems with 90% RMS

The biggest pitfall in the 90% RMS measure is that the RMS value can vary tremendously for signals having similar energy content. If the signal is only a little less “ringy” than the *EWING* 20 gun example shown above, the 90% energy time span will be much smaller, which greatly increases the RMS value. The better the “tuning” of a seismic source array, the more impulsive its signature and the shorter its 90% energy window. The resulting problems can be illustrated using a simple source – a two-gun “cluster” as modeled by Nucleus/Masomo. Signals are calculated at hundreds of mesh points, 90% RMS is calculated for each signal, and the resulting levels were contoured (Fig. 10).

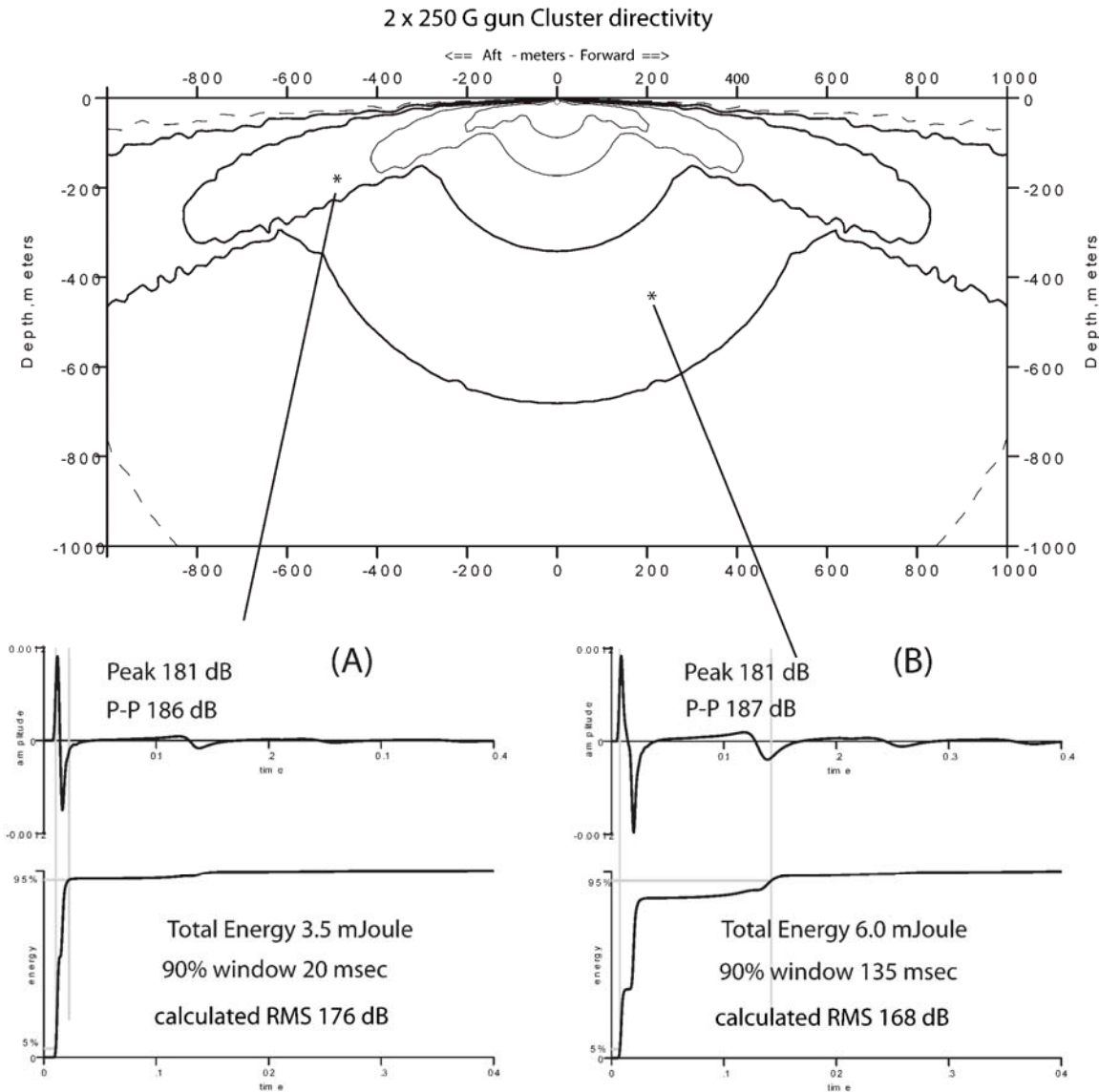


FIGURE 10. Modeled results from a simple 2-airgun cluster source.

Unlike the *EWING* example presented earlier, the RMS contours for this source are pathologically variable. To investigate the reason for this, two signatures, (A) and (B), were calculated at equal distances from the source array, but in high and low RMS zones, respectively. These signals have identical peak levels, but greatly different RMS values. The difference is almost entirely due to the varying length of the automatically determined 90% RMS integration window. This change in window length is in turn due to the effects of surface ghosting, which diminish the bubble pulse in the left-hand signal (A), thus reducing the 90% energy time span. Paradoxically, the right-hand signal (B), which has higher peak-to-peak and total energy levels, has a greatly lower RMS value. This is almost entirely due to large variations in the automatically calculated 90% RMS window length. A contour plot of 90% RMS window length shows that for this source, they vary between 5 and 137 milliseconds (Fig. 11).

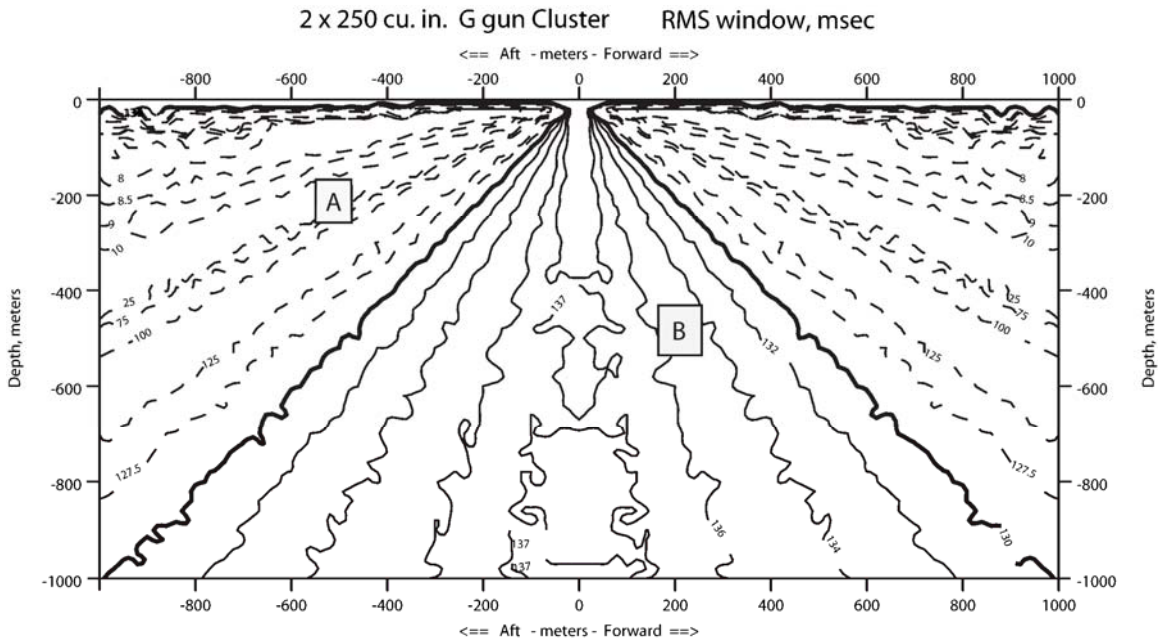


Figure 11. The locations from which signals (A) and (B) were extracted are shown for reference.

Other measures may be far more appropriate for quantifying airgun signal levels and predicting their effect on marine creatures.

Sound exposure level [SEL] is equal to RMS but with an added factor which is intended to minimize the time windowing effect, and to produce a measure more meaningful for the effects of noise on mammalian ears:

$$DB_{SEL} = dB_{RMS} + 10 * \text{Log}_{10}(\text{window}), \text{ where the window has units of seconds.}$$

For RMS window lengths less than one second, this additive factor varies between -30 dB for a RMS window length of 1 millisecond, to zero, for a window length of one second.

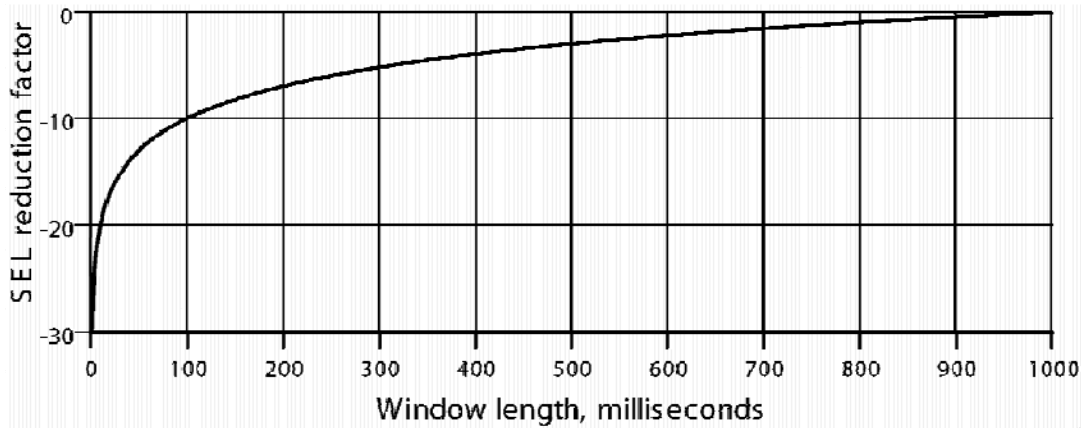


Figure 12.

Calculation of SEL for the two cluster signatures shown above shows the effect of the calculation's window length correction factor:

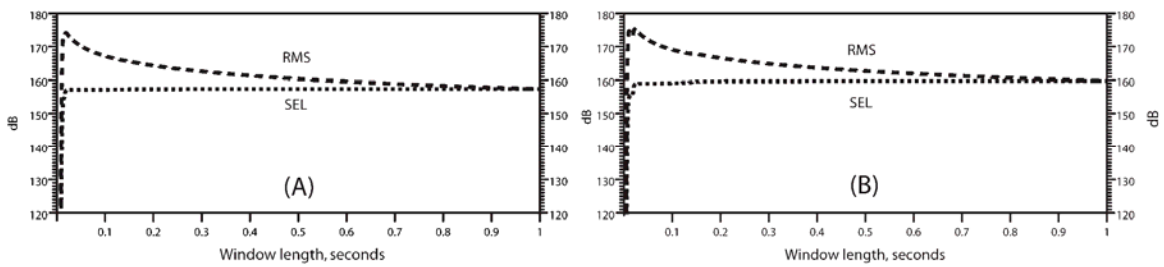


Figure 13.

While RMS varies continually with window length, SEL tends to approach a stationary level; in this case 157 dB for signal (A), and 160 dB for (B). The effect is to eliminate the dependence of the determined level upon window size; as long as the entire signal is captured, the calculated SEL will be pretty much the same. SEL is considered by many researchers (cf. Patterson 1991) to be a better predictor of hearing threshold shifts than is RMS or peak level.

Neither RMS nor SEL include frequency content, and there are many ways to look at this. Within the exploration seismic community, the cumulative energy flux is a standard measure (Johnston et al. 1988).

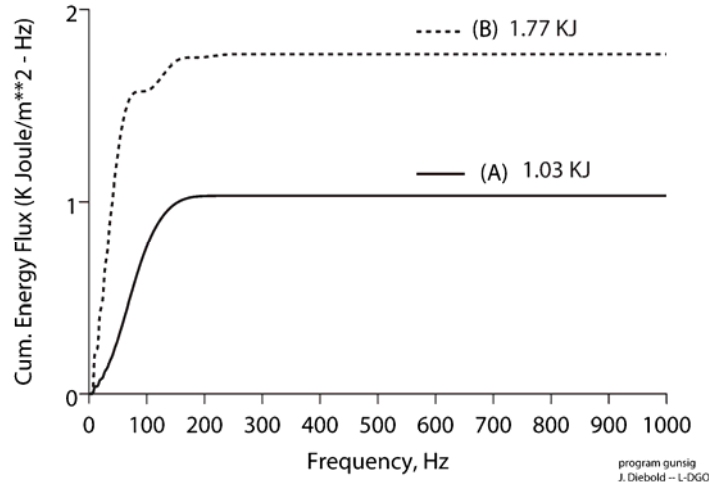


FIGURE 14.

Two features are immediately apparent from this plot: first, most of the energy in both signals is present at frequencies below several hundred Hz, and second, signal (B) whose 90% RMS level is less than half that of signal (A), actually contains appreciably more total energy. When the total energy of a short, impulsive signal, such as that created by an airgun array in deep water, is expressed in terms of dB, the result is usually equal to SEL.

The 90% RMS measure currently used to characterize possible impact on marine mammals may be severely flawed, especially when marine seismic source arrays are physically compact and/or well-tuned. An energy-based metric would produce more consistent results, and can be implemented in either time or frequency domains.

TABLE 1.

	A	B	%, A/B
RMS	176	168	166.67%
Peak	181	181	100.00%
P-P	186	187	91.67%
SEL	157	160	75.00%
Energy	3.5	6	58.33%
Energy	1.03	1.77	58.19%

The seismic sources planned and under construction for R/V *LANGSETH ARE* much more highly tuned than those deployed by R/V *EWING*. Although the total energy content in the signal produced by *LANGSETH*'s largest array is smaller than that of the "standard" *EWING* 20-airgun array, 90% RMS values of modeled signatures are much higher, due entirely to the RMS window length imposed by the improved tuning. Therefore, we propose to use SEL values, at least until new metrics are imposed. The question is: how to convert from SEL to equivalent RMS?

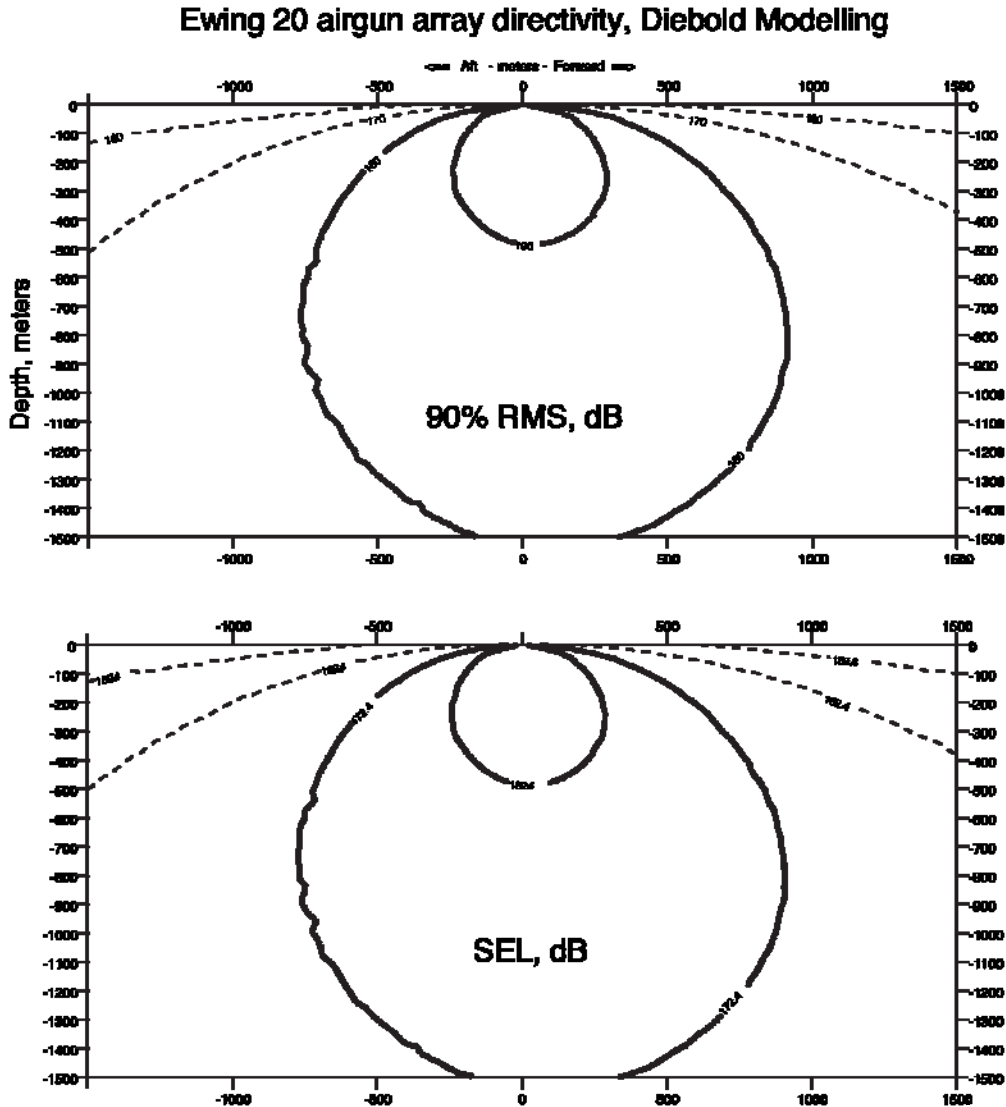


FIGURE 15. Here we have matched the RMS and SEL contours nearly perfectly by using an SEL value equal to $RMS - 7.6$ dB, an offset corresponding to the normal 90% energy window length of about 174 msec. Current IHA applications have used an SEL “discount” of 15 dB, which is equivalent to an RMS window of about 32 msec. It might be more appropriate to use a discount factor which corresponds to the natural mammal hearing integration time – it has been suggested, for example [Peter Tyack, pers. comm.] that this is about 200 msec for dolphins. This would be equivalent to an RMS – SEL discount of 7 dB.

Other metrics

When geophysicists investigate signal quality, they are likely to plot spectral energy on a linear frequency scale, as specified in Johnston et al. (1988):

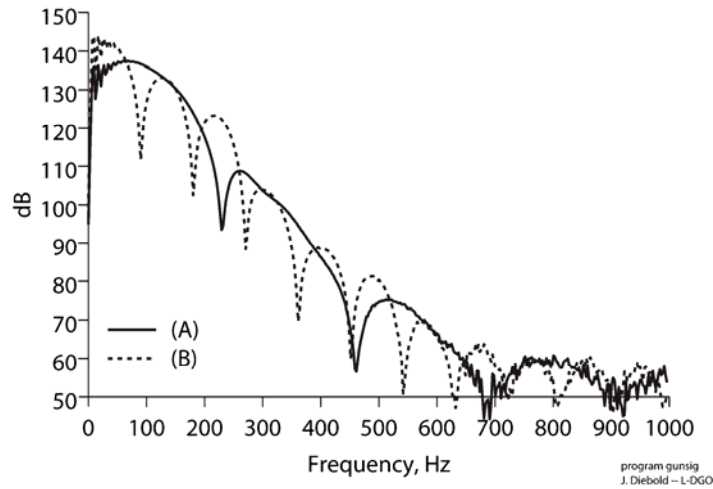


FIGURE 16.

In studies of noise and its effect on marine animals, a spectral display in terms of 1/3 octave energy levels is often preferred. To obtain such a display, spectral power is integrated within specified bands whose width increases logarithmically with frequency.

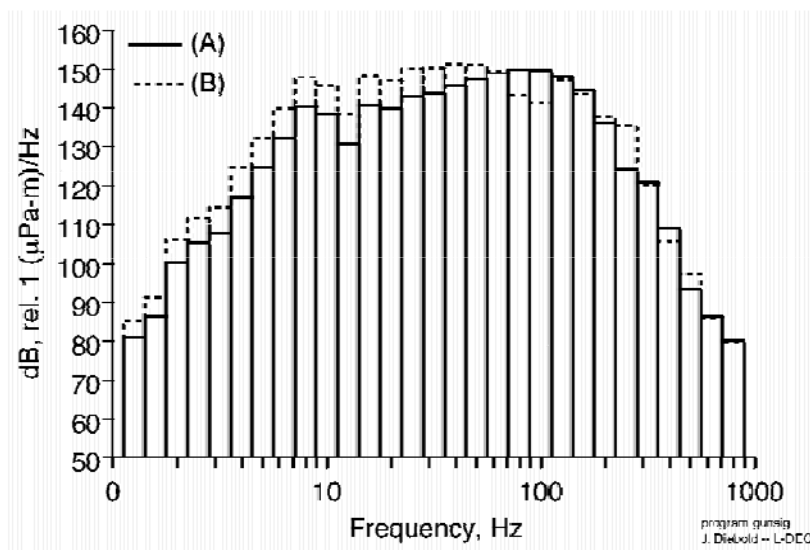


FIGURE 17.

It is clear from this display that despite its higher calculated 90% RMS level, signal (A) has lower energy than (B) at most frequencies, especially between zero and 100 Hz, where ghosting effects play a major role.

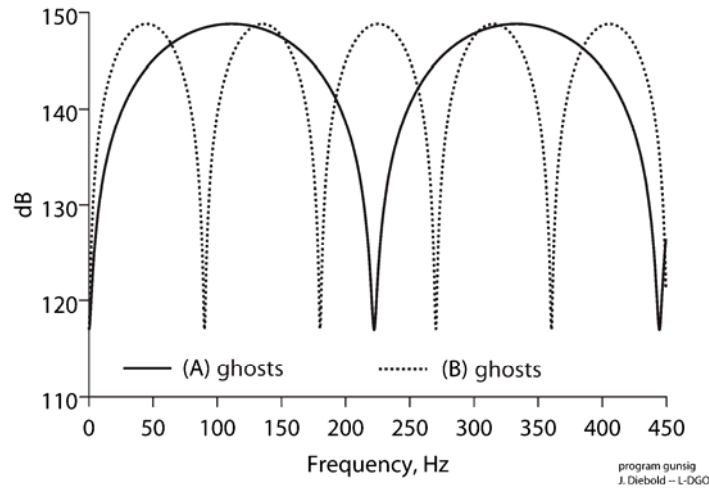


Figure 18.

The time lag between direct and surface-reflected paths for signal (A) is much smaller than that for signal (B). Therefore the ghost-induced shaping filter superimposed on signal (A) cuts out much of the low-frequency energy seen in signal (B).

If we plot the ghost shaping filters in the third-octave display described above, it is readily apparent that most of the differences between (A) and (B) in the previous third-octave plot are due to ghosting effects:

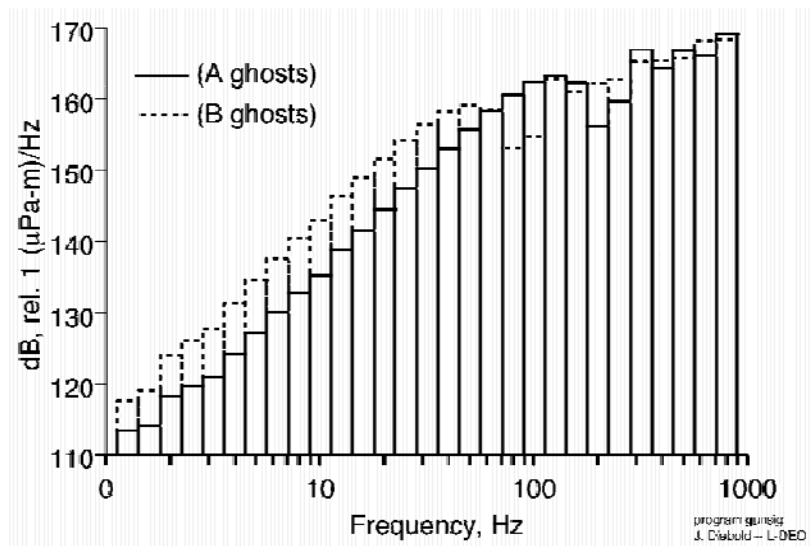


Figure 19.

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APPENDIX B: REVIEW OF THE EFFECTS OF AIRGUN SOUNDS ON MARINE MAMMALS⁵

The following subsections review relevant information concerning the potential effects of airguns on marine mammals. Because this review is intended to be of general usefulness, it includes references to types of marine mammals that will not be found in some specific regions.

1. Categories of Noise Effects

The effects of noise on marine mammals are highly variable, and can be categorized as follows (adapted from Richardson et al. 1995):

1. The noise may be too weak to be heard at the location of the animal, i.e., lower than the prevailing ambient noise level, the hearing threshold of the animal at relevant frequencies, or both;
2. The noise may be audible but not strong enough to elicit any overt behavioral response, i.e., the mammal may tolerate it, either without or with some deleterious effects (e.g., masking, stress);
3. The noise may elicit behavioral reactions of variable conspicuousness and variable relevance to the well being of the animal; these can range from subtle effects on respiration or other behaviors (detectable only by statistical analysis) to active avoidance reactions;
4. Upon repeated exposure, animals may exhibit diminishing responsiveness (habituation), or disturbance effects may persist; the latter is most likely with sounds that are highly variable in characteristics, unpredictable in occurrence, and associated with situations that the animal perceives as a threat;
5. Any man-made noise that is strong enough to be heard has the potential to reduce (mask) the ability of marine mammals to hear natural sounds at similar frequencies, including calls from conspecifics, echolocation sounds of odontocetes, and environmental sounds such as surf noise or (at high latitudes) ice noise. However, intermittent airgun or sonar pulses could cause strong masking for only a small proportion of the time, given the short duration of these pulses relative to the inter-pulse intervals;
6. Very strong sounds have the potential to cause temporary or permanent reduction in hearing sensitivity, or other physical or physiological effects. Received sound levels must far exceed the animal's hearing threshold for any temporary threshold shift to occur. Received levels must be even higher for a risk of permanent hearing impairment.

2. Hearing Abilities of Marine Mammals

The hearing abilities of marine mammals are functions of the following (Richardson et al. 1995; Au et al. 2000):

1. Absolute hearing threshold at the frequency in question (the level of sound barely audible in the absence of ambient noise). The "best frequency" is the frequency with the lowest absolute threshold.
2. Critical ratio (the signal-to-noise ratio required to detect a sound at a specific frequency in the presence of background noise around that frequency).
3. The ability to determine sound direction at the frequencies under consideration.

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4. The ability to discriminate among sounds of different frequencies and intensities.

Marine mammals rely heavily on the use of underwater sounds to communicate and to gain information about their surroundings. Experiments and monitoring studies also show that they hear and may react to many man-made sounds including sounds made during seismic exploration (Richardson et al. 1995; Gordon et al. 2004; Nowacek et al. 2007; Tyack 2008).

2.1 Toothed Whales (Odontocetes)

Hearing abilities of some toothed whales (odontocetes) have been studied in detail (reviewed in Chapter 8 of Richardson et al. [1995] and in Au et al. [2000]). Hearing sensitivity of several species has been determined as a function of frequency. The small to moderate-sized toothed whales whose hearing has been studied have relatively poor hearing sensitivity at frequencies below 1 kHz, but extremely good sensitivity at, and above, several kHz. There are very few data on the absolute hearing thresholds of most of the larger, deep-diving toothed whales, such as the sperm and beaked whales. However, Cook et al. (2006) found that a stranded juvenile Gervais' beaked whale showed evoked potentials from 5 kHz up to 80 kHz (the entire frequency range that was tested), with best sensitivity at 40–80 kHz. An adult Gervais' beaked whale had a similar upper cutoff frequency (80–90 kHz; Finneran et al. 2009).

Most of the odontocete species have been classified as belonging to the “mid-frequency” (MF) hearing group, and the MF odontocetes (collectively) have functional hearing from about 150 Hz to 160 kHz (Southall et al. 2007). However, individual species may not have quite so broad a functional frequency range. Very strong sounds at frequencies slightly outside the functional range may also be detectable. The remaining odontocetes—the porpoises, river dolphins, and members of the genera *Cephalorhynchus* and *Kogia*—are distinguished as the “high frequency” (HF) hearing group. They have functional hearing from about 200 Hz to 180 kHz (Southall et al. 2007).

Airguns produce a small proportion of their sound at mid- and high-frequencies, although at progressively lower levels with increasing frequency. In general, most of the energy in the sound pulses emitted by airgun arrays is at low frequencies; strongest spectrum levels are below 200 Hz, with considerably lower spectrum levels above 1000 Hz, and smaller amounts of energy emitted up to ~150 kHz (Goold and Fish 1998; Sodal 1999; Goold and Coates 2006; Potter et al. 2007).

Despite the relatively poor sensitivity of small odontocetes at the low frequencies that contribute most of the energy in pulses of sound from airgun arrays, airgun sounds are sufficiently strong, and contain sufficient mid- and high-frequency energy, that their received levels sometimes remain above the hearing thresholds of odontocetes at distances out to several tens of kilometers (Richardson and Würsig 1997). There is no evidence that most small odontocetes react to airgun pulses at such long distances. However, beluga whales do seem quite responsive at intermediate distances (10–20 km) where sound levels are well above the ambient noise level (see below).

In summary, even though odontocete hearing is relatively insensitive to the predominant low frequencies produced by airguns, sounds from airgun arrays are audible to odontocetes, sometimes to distances of 10s of kilometers.

2.2 Baleen Whales (Mysticetes)

The hearing abilities of baleen whales (mysticetes) have not been studied directly. Behavioral and anatomical evidence indicates that they hear well at frequencies below 1 kHz (Richardson et al. 1995; Ketten 2000). Frankel (2005) noted that gray whales reacted to a 21–25 kHz whale-finding sonar. Some baleen whales react to pinger sounds up to 28 kHz, but not to pingers or sonars emitting sounds at 36 kHz or above (Watkins 1986). In addition, baleen whales produce sounds at frequencies up to 8 kHz and, for

humpbacks, with components to >24 kHz (Au et al. 2006). The anatomy of the baleen whale inner ear seems to be well adapted for detection of low-frequency sounds (Ketten 1991, 1992, 1994, 2000; Parks et al. 2007b). Although humpbacks and minke whales (Berta et al. 2009) may have some auditory sensitivity to frequencies above 22 kHz, for baleen whales as a group, the functional hearing range is thought to be about 7 Hz to 22 kHz and they are said to constitute the “low-frequency” (LF) hearing group (Southall et al. 2007). The absolute sound levels that they can detect below 1 kHz are probably limited by increasing levels of natural ambient noise at decreasing frequencies (Clark and Ellison 2004). Ambient noise levels are higher at low frequencies than at mid frequencies. At frequencies below 1 kHz, natural ambient levels tend to increase with decreasing frequency.

The hearing systems of baleen whales are undoubtedly more sensitive to low-frequency sounds than are the ears of the small toothed whales that have been studied directly. Thus, baleen whales are likely to hear airgun pulses farther away than can small toothed whales and, at closer distances, airgun sounds may seem more prominent to baleen than to toothed whales. However, baleen whales have commonly been seen well within the distances where seismic (or other source) sounds would be detectable and often show no overt reaction to those sounds. Behavioral responses by baleen whales to seismic pulses have been documented, but received levels of pulsed sounds necessary to elicit behavioral reactions are typically well above the minimum levels that the whales are assumed to detect (see below).

2.3 Seals and Sea Lions (Pinnipeds)

Underwater audiograms have been obtained using behavioral methods for three species of phocinid seals, two species of monachid seals, two species of otariids, and the walrus (reviewed in Richardson et al. 1995: 211ff; Kastak and Schusterman 1998, 1999; Kastelein et al. 2002, 2009). The functional hearing range for pinnipeds in water is considered to extend from 75 Hz to 75 kHz (Southall et al. 2007), although some individual species—especially the eared seals—do not have that broad an auditory range (Richardson et al. 1995). In comparison with odontocetes, pinnipeds tend to have lower best frequencies, lower high-frequency cutoffs, better auditory sensitivity at low frequencies, and poorer sensitivity at the best frequency.

At least some of the phocid seals have better sensitivity at low frequencies (≤ 1 kHz) than do odontocetes. Below 30–50 kHz, the hearing thresholds of most species tested are essentially flat down to ~ 1 kHz, and range between 60 and 85 dB re $1 \mu\text{Pa}$. Measurements for harbor seals indicate that, below 1 kHz, their thresholds under quiet background conditions deteriorate gradually with decreasing frequency to ~ 75 dB re $1 \mu\text{Pa}$ at 125 Hz (Kastelein et al. 2009).

For the otariid (eared) seals, the high frequency cutoff is lower than for phocinids, and sensitivity at low frequencies (e.g., 100 Hz) is poorer than for seals (harbor seal).

2.4 Manatees and Dugong (Sirenians)

The West Indian manatee can apparently detect sounds and low-frequency vibrations from 15 Hz to 46 kHz, based on a study involving behavioral testing methods (Gerstein et al. 1999, 2004). A more recent study found that, in one Florida manatee, auditory sensitivity extended up to 90.5 kHz (Bauer et al. 2009). Thus, manatees may hear, or at least detect, sounds in the low-frequency range where most seismic energy is released. It is possible that they are able to feel these low-frequency sounds using vibrotactile receptors or because of resonance in body cavities or bone conduction.

Based on measurements of evoked potentials, manatee hearing is apparently best around 1–1.5 kHz (Bullock et al. 1982). However, behavioral tests suggest that best sensitivities are at 6–20 kHz (Gerstein

et al. 1999) or 8–32 kHz (Bauer et al. 2009). The ability to detect high frequencies may be an adaptation to shallow water, where the propagation of low frequency sound is limited (Gerstein et al. 1999, 2004).

2.5 Sea Otter and Polar Bear

No data are available on the hearing abilities of sea otters (Ketten 1998), although the in-air vocalizations of sea otters have most of their energy concentrated at 3–5 kHz (McShane et al. 1995; Thomson and Richardson 1995). Sea otter vocalizations are considered to be most suitable for short-range communication among individuals (McShane et al. 1995). However, Ghoual et al. (2009) noted that the in-air “screams” of sea otters are loud signals (source level of 93–118 dB re 20 μPa_{pk}) that may be used over larger distances; screams have a frequency of maximum energy ranging from 2 to 8 kHz. In-air audiograms for two river otters indicate that this related species has its best hearing sensitivity at the relatively high frequency of 16 kHz, with some sensitivity from about 460 Hz to 33 kHz (Gunn 1988). However, these data apply to a different species of otter, and to in-air rather than underwater hearing.

Data on the specific hearing capabilities of polar bears are limited. A recent study of the in-air hearing of polar bears applied the auditory evoked potential method while tone pips were played to anesthetized bears (Nachtigall et al. 2007). Hearing was tested in $\frac{1}{2}$ octave steps from 1 to 22.5 kHz, and best hearing sensitivity was found between 11.2 and 22.5 kHz. Although low-frequency hearing was not studied, the data suggested that medium- and some high-frequency sounds may be audible to polar bears. However, polar bears’ usual behavior (e.g., remaining on the ice, at the water surface, or on land) reduces or avoids exposure to underwater sounds.

3. Characteristics of Airgun Sounds

Airguns function by venting high-pressure air into the water. The pressure signature of an individual airgun consists of a sharp rise and then fall in pressure, followed by several positive and negative pressure excursions caused by oscillation of the resulting air bubble. The sizes, arrangement, and firing times of the individual airguns in an array are designed and synchronized to suppress the pressure oscillations subsequent to the first cycle. The resulting downward-directed pulse has a duration of only 10–20 ms, with only one strong positive and one strong negative peak pressure (Caldwell and Dragoset 2000). Most energy emitted from airguns is at relatively low frequencies. For example, typical high-energy airgun arrays emit most energy at 10–120 Hz. However, the pulses contain significant energy up to 500–1000 Hz and some energy at higher frequencies (Goold and Fish 1998; Potter et al. 2007). Studies in the Gulf of Mexico have shown that the horizontally-propagating sound can contain significant energy above the frequencies that airgun arrays are designed to emit (DeRuiter et al. 2006; Madsen et al. 2006; Tyack et al. 2006a). Energy at frequencies up to 150 kHz was found in tests of single 60-in³ and 250-in³ airguns (Goold and Coates 2006). Nonetheless, the predominant energy is at low frequencies.

The pulsed sounds associated with seismic exploration have higher peak levels than other industrial sounds (except those from explosions) to which whales and other marine mammals are routinely exposed. The nominal source levels of the 2- to 36-airgun arrays used by Lamont-Doherty Earth Observatory (L-DEO) from the R/V *Maurice Ewing* (now retired) and R/V *Marcus G. Langseth* (36 airguns) are 236–265 dB re 1 $\mu\text{Pa}_{\text{p-p}}$. These are the nominal source levels applicable to downward propagation. The effective source levels for horizontal propagation are lower than those for downward propagation when the source consists of numerous airguns spaced apart from one another. Explosions are the only man-made sources with effective source levels as high as (or higher than) a large array of airguns. However, high-power sonars can have source pressure levels as high as a small array of airguns, and signal duration can be longer for a sonar than for an airgun array, making the source energy levels of some sonars more comparable to those of airgun arrays.

Several important mitigating factors need to be kept in mind. (1) Airgun arrays produce intermittent sounds, involving emission of a strong sound pulse for a small fraction of a second followed by several seconds of near silence. In contrast, some other sources produce sounds with lower peak levels, but their sounds are continuous or discontinuous but continuing for longer durations than seismic pulses. (2) Airgun arrays are designed to transmit strong sounds downward through the seafloor, and the amount of sound transmitted in near-horizontal directions is considerably reduced. Nonetheless, they also emit sounds that travel horizontally toward non-target areas. (3) An airgun array is a distributed source, not a point source. The nominal source level is an estimate of the sound that would be measured from a theoretical point source emitting the same total energy as the airgun array. That figure is useful in calculating the expected received levels in the far field, i.e., at moderate and long distances, but not in the near field. Because the airgun array is not a single point source, there is no one location within the near field (or anywhere else) where the received level is as high as the nominal source level.

The strengths of airgun pulses can be measured in different ways, and it is important to know which method is being used when interpreting quoted source or received levels. Geophysicists usually quote peak-to-peak (p-p) levels, in bar-meters or (less often) dB re 1 $\mu\text{Pa} \cdot \text{m}$. The peak (= zero-to-peak, or 0-p) level for the same pulse is typically ~ 6 dB less. In the biological literature, levels of received airgun pulses are often described based on the “average” or “root-mean-square” (rms) level, where the average is calculated over the duration of the pulse. The rms value for a given airgun pulse is typically ~ 10 dB lower than the peak level, and 16 dB lower than the peak-to-peak value (Greene 1997; McCauley et al. 1998, 2000a). A fourth measure that is increasingly used is the energy, or Sound Exposure Level (SEL), in dB re 1 $\mu\text{Pa}^2 \cdot \text{s}$. Because the pulses, even when stretched by propagation effects (see below), are usually < 1 s in duration, the numerical value of the energy is usually lower than the rms pressure level. However, the units are different.⁶ Because the level of a given pulse will differ substantially depending on which of these measures is being applied, it is important to be aware which measure is in use when interpreting any quoted pulse level. In the past, the U.S. National Marine Fisheries Service (NMFS) has commonly referred to rms levels when discussing levels of pulsed sounds that might “harass” marine mammals.

Seismic sound pulses received at any given point will arrive via a direct path, indirect paths that include reflection from the sea surface and bottom, and often indirect paths including segments through the bottom sediments. Sounds propagating via indirect paths travel longer distances and often arrive later than sounds arriving via a direct path. (However, sound traveling in the bottom may travel faster than that in the water, and thus may, in some situations, arrive slightly earlier than the direct arrival despite traveling a greater distance.) These variations in travel time have the effect of lengthening the duration of the received pulse, or may cause two or more received pulses from a single emitted pulse. Near the source, the predominant part of a seismic pulse is ~ 10 – 20 ms in duration. In comparison, the pulse duration as received at long horizontal distances can be much greater. For example, for one airgun array operating in

⁶ The rms value for a given airgun array pulse, as measured at a horizontal distance on the order of 0.1 km to 1–10 km in the units dB re 1 μPa , usually averages 10–15 dB higher than the SEL value for the same pulse measured in dB re 1 $\mu\text{Pa}^2 \cdot \text{s}$ (e.g., Greene 1997). However, there is considerable variation, and the difference tends to be larger close to the airgun array, and less at long distances (Blackwell et al. 2007; MacGillivray and Hannay 2007a,b). In some cases, generally at longer distances, pulses are “stretched” by propagation effects to the extent that the rms and SEL values (in the respective units mentioned above) become very similar (e.g., MacGillivray and Hannay 2007a,b).

the Beaufort Sea, pulse duration was ~300 ms at a distance of 8 km, 500 ms at 20 km, and 850 ms at 73 km (Greene and Richardson 1988).

The rms level for a given pulse (when measured over the duration of that pulse) depends on the extent to which propagation effects have “stretched” the duration of the pulse by the time it reaches the receiver (e.g., Madsen 2005). As a result, the rms values for various received pulses are not perfectly correlated with the SEL (energy) values for the same pulses. There is increasing evidence that biological effects are more directly related to the received energy (e.g., to SEL) than to the rms values averaged over pulse duration (Southall et al. 2007).

Another important aspect of sound propagation is that received levels of low-frequency underwater sounds diminish close to the surface because of pressure-release and interference phenomena that occur at and near the surface (Urlick 1983; Richardson et al. 1995; Potter et al. 2007). Paired measurements of received airgun sounds at depths of 3 vs. 9 or 18 m have shown that received levels are typically several decibels lower at 3 m (Greene and Richardson 1988). For a mammal whose auditory organs are within 0.5 or 1 m of the surface, the received level of the predominant low-frequency components of the airgun pulses would be further reduced. In deep water, the received levels at deep depths can be considerably higher than those at relatively shallow (e.g., 18 m) depths and the same horizontal distance from the airguns (Tolstoy et al. 2004a,b).

Pulses of underwater sound from open-water seismic exploration are often detected 50–100 km from the source location, even during operations in nearshore waters (Greene and Richardson 1988; Burgess and Greene 1999). At those distances, the received levels are usually low, <120 dB re 1 μ Pa on an approximate rms basis. However, faint seismic pulses are sometimes detectable at even greater ranges (e.g., Bowles et al. 1994; Fox et al. 2002). In fact, low-frequency airgun signals sometimes can be detected thousands of kilometers from their source. For example, sound from seismic surveys conducted offshore of Nova Scotia, the coast of western Africa, and northeast of Brazil were reported as a dominant feature of the underwater noise field recorded along the mid-Atlantic ridge (Nieukirk et al. 2004).

4. Masking Effects of Airgun Sounds

Masking is the obscuring of sounds of interest by interfering sounds, generally at similar frequencies (Richardson et al. 1995). Introduced underwater sound will, through masking, reduce the effective communication distance of a marine mammal species if the frequency of the source is close to that used as a signal by the marine mammal, and if the anthropogenic sound is present for a significant fraction of the time (Richardson et al. 1995). If little or no overlap occurs between the introduced sound and the frequencies used by the species, communication is not expected to be disrupted. Also, if the introduced sound is present only infrequently, communication is not expected to be disrupted much if at all. The duty cycle of airguns is low; the airgun sounds are pulsed, with relatively quiet periods between pulses. In most situations, strong airgun sound will only be received for a brief period (<1 s), with these sound pulses being separated by at least several seconds of relative silence, and longer in the case of deep-penetration surveys or refraction surveys. A single airgun array might cause appreciable masking in only one situation: When propagation conditions are such that sound from each airgun pulse reverberates strongly and persists for much or all of the interval up to the next airgun pulse (e.g., Simard et al. 2005; Clark and Gagnon 2006). Situations with prolonged strong reverberation are infrequent, in our experience. However, it is common for reverberation to cause some lesser degree of elevation of the background level between airgun pulses (e.g., Guerra et al. 2009), and this weaker reverberation presumably reduces the detection range of calls and other natural sounds to some degree.

Although masking effects of pulsed sounds on marine mammal calls and other natural sounds are expected to be limited, there are few specific studies on this. Some whales continue calling in the presence of seismic pulses and whale calls often can be heard between the seismic pulses (e.g., Richardson et al. 1986; McDonald et al. 1995; Greene et al. 1999a,b; Nieu Kirk et al. 2004; Smultea et al. 2004; Holst et al. 2005a,b, 2006; Dunn and Hernandez 2009). However, there is one recent summary report indicating that calling fin whales distributed in one part of the North Atlantic went silent for an extended period starting soon after the onset of a seismic survey in the area (Clark and Gagnon 2006). It is not clear from that preliminary paper whether the whales ceased calling because of masking, or whether this was a behavioral response not directly involving masking. Also, bowhead whales in the Beaufort Sea may decrease their call rates in response to seismic operations, although movement out of the area might also have contributed to the lower call detection rate (Blackwell et al. 2009a,b). In contrast, Di Iorio and Clark (2009) found evidence of *increased* calling by blue whales during operations by a lower-energy seismic source—a sparker.

Among the odontocetes, there has been one report that sperm whales ceased calling when exposed to pulses from a very distant seismic ship (Bowles et al. 1994). However, more recent studies of sperm whales found that they continued calling in the presence of seismic pulses (Madsen et al. 2002; Tyack et al. 2003; Smultea et al. 2004; Holst et al. 2006; Jochens et al. 2008). Madsen et al. (2006) noted that airgun sounds would not be expected to mask sperm whale calls given the intermittent nature of airgun pulses. Dolphins and porpoises are also commonly heard calling while airguns are operating (Gordon et al. 2004; Smultea et al. 2004; Holst et al. 2005a,b; Potter et al. 2007). Masking effects of seismic pulses are expected to be negligible in the case of the smaller odontocetes, given the intermittent nature of seismic pulses plus the fact that sounds important to them are predominantly at much higher frequencies than are the dominant components of airgun sounds.

Pinnipeds, sirenians and sea otters have best hearing sensitivity and/or produce most of their sounds at frequencies higher than the dominant components of airgun sound, but there is some overlap in the frequencies of the airgun pulses and the calls. However, the intermittent nature of airgun pulses presumably reduces the potential for masking.

A few cetaceans are known to increase the source levels of their calls in the presence of elevated sound levels, shift their peak frequencies in response to strong sound signals, or otherwise modify their vocal behavior in response to increased noise (Dahlheim 1987; Au 1993; reviewed in Richardson et al. 1995:233ff, 364ff; Lesage et al. 1999; Terhune 1999; Nieu Kirk et al. 2005; Scheifele et al. 2005; Parks et al. 2007a, 2009; Di Iorio and Clark 2009; Hanser et al. 2009). It is not known how often these types of responses occur upon exposure to airgun sounds. However, blue whales in the St. Lawrence Estuary significantly increased their call rates during sparker operations (Di Iorio and Clark 2009). The sparker, used to obtain seismic reflection data, emitted frequencies of 30–450 Hz with a relatively low source level of 193 dB re 1 $\mu\text{Pa}_{\text{pk-pk}}$. If cetaceans exposed to airgun sounds sometimes respond by changing their vocal behavior, this adaptation, along with directional hearing and preadaptation to tolerate some masking by natural sounds (Richardson et al. 1995), would all reduce the importance of masking by seismic pulses.

5. Disturbance by Seismic Surveys

Disturbance includes a variety of effects, including subtle to conspicuous changes in behavior, movement, and displacement. In the terminology of the 1994 amendments to the U.S. Marine Mammal Protection Act (MMPA), seismic noise could cause “Level B” harassment of certain marine mammals. Level B harassment is defined as “...disruption of behavioral patterns, including, but not limited to, migration, breathing, nursing, breeding, feeding, or sheltering.”

There has been debate regarding how substantial a change in behavior or mammal activity is required before the animal should be deemed to be “taken by Level B harassment”. NMFS has stated that

“...a simple change in a marine mammal’s actions does not always rise to the level of disruption of its behavioral patterns. ... If the only reaction to the [human] activity on the part of the marine mammal is within the normal repertoire of actions that are required to carry out that behavioral pattern, NMFS considers [the human] activity not to have caused a disruption of the behavioral pattern, provided the animal’s reaction is not otherwise significant enough to be considered disruptive due to length or severity. Therefore, for example, a short-term change in breathing rates or a somewhat shortened or lengthened dive sequence that are within the animal’s normal range and that do not have any biological significance (i.e., do not disrupt the animal’s overall behavioral pattern of breathing under the circumstances), do not rise to a level requiring a small take authorization.” (NMFS 2001, p. 9293).

Based on this guidance from NMFS, and on NRC (2005), simple exposure to sound, or brief reactions that do not disrupt behavioral patterns in a potentially significant manner, do not constitute harassment or “taking”. In this analysis, we interpret “potentially significant” to mean in a manner that might have deleterious effects on the well-being of individual marine mammals or their populations.

Even with this guidance, there are difficulties in defining what marine mammals should be counted as “taken by harassment”. Available detailed data on reactions of marine mammals to airgun sounds (and other anthropogenic sounds) are limited to relatively few species and situations (see Richardson et al. 1995; Gordon et al. 2004; Nowacek et al. 2007; Southall et al. 2007). Behavioral reactions of marine mammals to sound are difficult to predict in the absence of site- and context-specific data. Reactions to sound, if any, depend on species, state of maturity, experience, current activity, reproductive state, time of day, and many other factors (Richardson et al. 1995; Wartzok et al. 2004; Southall et al. 2007; Weilgart 2007). If a marine mammal reacts to an underwater sound by changing its behavior or moving a small distance, the impacts of the change are unlikely to be significant to the individual, let alone the stock or population. However, if a sound source displaces marine mammals from an important feeding or breeding area for a prolonged period, impacts on individuals and populations could be significant (e.g., Lusseau and Bejder 2007; Weilgart 2007). Also, various authors have noted that some marine mammals that show no obvious avoidance or behavioral changes may still be adversely affected by noise (Brodie 1981; Richardson et al. 1995:317ff; Romano et al. 2004; Weilgart 2007; Wright et al. 2009). For example, some research suggests that animals in poor condition or in an already stressed state may not react as strongly to human disturbance as would more robust animals (e.g., Beale and Monaghan 2004).

Studies of the effects of seismic surveys have focused almost exclusively on the effects on individual species or related groups of species, with little scientific or regulatory attention being given to broader community-level issues. Parente et al. (2007) suggested that the diversity of cetaceans near the Brazil coast was reduced during years with seismic surveys. However, a preliminary account of a more recent analysis suggests that the trend did not persist when additional years were considered (Britto and Silva Barreto 2009).

Given the many uncertainties in predicting the quantity and types of impacts of sound on marine mammals, it is common practice to estimate how many mammals would be present within a particular distance of human activities and/or exposed to a particular level of anthropogenic sound. In most cases, this approach likely overestimates the numbers of marine mammals that would be affected in some biologically important manner. One of the reasons for this is that the selected distances/isopleths are based on limited studies indicating that some animals exhibited short-term reactions at this distance or

sound level, whereas the calculation assumes that all animals exposed to this level would react in a biologically significant manner.

The definitions of “taking” in the U.S. MMPA, and its applicability to various activities, were slightly altered in November 2003 for military and federal scientific research activities. Also, NMFS is proposing to replace current Level A and B harassment criteria with guidelines based on exposure characteristics that are specific to particular groups of mammal species and to particular sound types (NMFS 2005). Recently, a committee of specialists on noise impact issues has proposed new science-based impact criteria (Southall et al. 2007). Thus, for projects subject to U.S. jurisdiction, changes in procedures may be required in the near future.

The sound criteria used to estimate how many marine mammals might be disturbed to some biologically significant degree by seismic survey activities are primarily based on behavioral observations of a few species. Detailed studies have been done on humpback, gray, bowhead, and sperm whales, and on ringed seals. Less detailed data are available for some other species of baleen whales and small toothed whales, but for many species there are no data on responses to marine seismic surveys.

5.1 Baleen Whales

Baleen whales generally tend to avoid operating airguns, but avoidance radii are quite variable among species, locations, whale activities, oceanographic conditions affecting sound propagation, etc. (reviewed in Richardson et al. 1995; Gordon et al. 2004). Whales are often reported to show no overt reactions to pulses from large arrays of airguns at distances beyond a few kilometers, even though the airgun pulses remain well above ambient noise levels out to much longer distances. However, baleen whales exposed to strong sound pulses from airguns often react by deviating from their normal migration route and/or interrupting their feeding and moving away. Some of the major studies and reviews on this topic are Malme et al. (1984, 1985, 1988); Richardson et al. (1986, 1995, 1999); Ljungblad et al. (1988); Richardson and Malme (1993); McCauley et al. (1998, 2000a,b); Miller et al. (1999, 2005); Gordon et al. (2004); Moulton and Miller (2005); Stone and Tasker (2006); Johnson et al. (2007); Nowacek et al. (2007) and Weir (2008a). Although baleen whales often show only slight overt responses to operating airgun arrays (Stone and Tasker 2006; Weir 2008a), strong avoidance reactions by several species of mysticetes have been observed at ranges up to 6–8 km and occasionally as far as 20–30 km from the source vessel when large arrays of airguns were used. Experiments with a single airgun showed that bowhead, humpback and gray whales all showed localized avoidance to a single airgun of 20–100 in³ (Malme et al. 1984, 1985, 1986, 1988; Richardson et al. 1986; McCauley et al. 1998, 2000a,b).

Studies of gray, bowhead, and humpback whales have shown that seismic pulses with received levels of 160–170 dB re 1 $\mu\text{Pa}_{\text{rms}}$ seem to cause obvious avoidance behavior in a substantial portion of the animals exposed (Richardson et al. 1995). In many areas, seismic pulses from large arrays of airguns diminish to those levels at distances ranging from 4–15 km from the source. More recent studies have shown that some species of baleen whales (bowheads and humpbacks in particular) at times show strong avoidance at received levels lower than 160–170 dB re 1 $\mu\text{Pa}_{\text{rms}}$. The largest avoidance radii involved migrating bowhead whales, which avoided an operating seismic vessel by 20–30 km (Miller et al. 1999; Richardson et al. 1999). In the cases of migrating bowhead (and gray) whales, the observed changes in behavior appeared to be of little or no biological consequence to the animals—they simply avoided the sound source by displacing their migration route to varying degrees, but within the natural boundaries of the migration corridors (Malme et al. 1984; Malme and Miles 1985; Richardson et al. 1995). Feeding bowhead whales, in contrast to migrating whales, show much smaller avoidance distances (Miller et al.

2005; Harris et al. 2007), presumably because moving away from a food concentration has greater cost to the whales than does a course deviation during migration.

The following subsections provide more details on the documented responses of particular species and groups of baleen whales to marine seismic operations.

Humpback Whales.—Responses of humpback whales to seismic surveys have been studied during migration, on the summer feeding grounds, and on Angolan winter breeding grounds; there has also been discussion of effects on the Brazilian wintering grounds. McCauley et al. (1998, 2000a) studied the responses of migrating humpback whales off Western Australia to a full-scale seismic survey with a 16-airgun 2678-in³ array, and to a single 20 in³ airgun with a (horizontal) source level of 227 dB re 1 $\mu\text{Pa} \cdot \text{m}_{\text{p-p}}$. They found that the overall distribution of humpbacks migrating through their study area was unaffected by the full-scale seismic program, although localized displacement varied with pod composition, behavior, and received sound levels. Observations were made from the seismic vessel, from which the maximum viewing distance was listed as 14 km. Avoidance reactions (course and speed changes) began at 4–5 km for traveling pods, with the closest point of approach (CPA) being 3–4 km at an estimated received level of 157–164 dB re 1 $\mu\text{Pa}_{\text{rms}}$ (McCauley et al. 1998, 2000a). A greater stand-off range of 7–12 km was observed for more sensitive resting pods (cow-calf pairs; McCauley et al. 1998, 2000a). The mean received level for initial avoidance of an approaching airgun was 140 dB re 1 $\mu\text{Pa}_{\text{rms}}$ for humpback pods containing females, and at the mean CPA distance the received level was 143 dB re 1 $\mu\text{Pa}_{\text{rms}}$. One startle response was reported at 112 dB re 1 $\mu\text{Pa}_{\text{rms}}$. The initial avoidance response generally occurred at distances of 5–8 km from the airgun array and 2 km from the single airgun. However, some individual humpback whales, especially males, approached within distances of 100–400 m, where the maximum received level was 179 dB re 1 $\mu\text{Pa}_{\text{rms}}$. The McCauley et al. (1998, 2000a,b) studies show evidence of greater avoidance of seismic airgun sounds by pods with females than by other pods during humpback migration off Western Australia.

Humpback whales on their summer feeding grounds in southeast Alaska did not exhibit persistent avoidance when exposed to seismic pulses from a 1.64-L (100 in³) airgun (Malme et al. 1985). Some humpbacks seemed “startled” at received levels of 150–169 dB re 1 μPa . Malme et al. (1985) concluded that there was no clear evidence of avoidance, despite the possibility of subtle effects, at received levels up to 172 re 1 μPa on an approximate rms basis.

Among wintering humpback whales off Angola ($n = 52$ useable groups), there were no significant differences in encounter rates (sightings/hr) when a 24-airgun array (3147 in³ or 5085 in³) was operating vs. silent (Weir 2008a). There was also no significant difference in the mean CPA (closest observed point of approach) distance of the humpback sightings when airguns were on vs. off (3050 m vs. 2700 m, respectively).

It has been suggested that South Atlantic humpback whales wintering off Brazil may be displaced or even strand upon exposure to seismic surveys (Engel et al. 2004). The evidence for this was circumstantial and subject to alternative explanations (IAGC 2004). Also, the evidence was not consistent with subsequent results from the same area of Brazil (Parente et al. 2006), or with direct studies of humpbacks exposed to seismic surveys in other areas and seasons (see above). After allowance for data from subsequent years, there was “no observable direct correlation” between strandings and seismic surveys (IWC 2007, p. 236).

Bowhead Whales.—Responsiveness of bowhead whales to seismic surveys can be quite variable depending on their activity (feeding vs. migrating). Bowhead whales on their summer feeding grounds in the Canadian Beaufort Sea showed no obvious reactions to pulses from seismic vessels at distances of 6–99 km and received sound levels of 107–158 dB on an approximate rms basis (Richardson et al. 1986);

their general activities were indistinguishable from those of a control group. However, subtle but statistically significant changes in surfacing–respiration–dive cycles were evident upon statistical analysis. Bowheads usually did show strong avoidance responses when seismic vessels approached within a few kilometers (~3–7 km) and when received levels of airgun sounds were 152–178 dB (Richardson et al. 1986, 1995; Ljungblad et al. 1988; Miller et al. 2005). They also moved away when a single airgun fired nearby (Richardson et al. 1986; Ljungblad et al. 1988). In one case, bowheads engaged in near-bottom feeding began to turn away from a 30-airgun array with a source level of 248 dB re 1 $\mu\text{Pa} \cdot \text{m}$ at a distance of 7.5 km, and swam away when it came within ~2 km; some whales continued feeding until the vessel was 3 km away (Richardson et al. 1986). This work and subsequent summer studies in the same region by Miller et al. (2005) and Harris et al. (2007) showed that many feeding bowhead whales tend to tolerate higher sound levels than migrating bowhead whales (see below) before showing an overt change in behavior. On the summer feeding grounds, bowhead whales are often seen from the operating seismic ship, though average sighting distances tend to be larger when the airguns are operating. Similarly, preliminary analyses of recent data from the Alaskan Beaufort Sea indicate that bowheads feeding there during late summer and autumn also did not display large-scale distributional changes in relation to seismic operations (Christie et al. 2009; Koski et al. 2009). However, some individual bowheads apparently begin to react at distances a few kilometers away, beyond the distance at which observers on the ship can sight bowheads (Richardson et al. 1986; Citta et al. 2007). The feeding whales may be affected by the sounds, but the need to feed may reduce the tendency to move away until the airguns are within a few kilometers.

Migrating bowhead whales in the Alaskan Beaufort Sea seem more responsive to noise pulses from a distant seismic vessel than are summering bowheads. Bowhead whales migrating west across the Alaskan Beaufort Sea in autumn are unusually responsive, with substantial avoidance occurring out to distances of 20–30 km from a medium-sized airgun source at received sound levels of around 120–130 dB re 1 $\mu\text{Pa}_{\text{rms}}$ (Miller et al. 1999; Richardson et al. 1999; see also Manly et al. 2007). Those results came from 1996–98, when a partially-controlled study of the effect of Ocean Bottom Cable (OBC) seismic surveys on westward-migrating bowheads was conducted in late summer and autumn in the Alaskan Beaufort Sea. At times when the airguns were not active, many bowheads moved into the area close to the inactive seismic vessel. Avoidance of the area of seismic operations did not persist beyond 12–24 h after seismic shooting stopped. Preliminary analysis of recent data on traveling bowheads in the Alaskan Beaufort Sea also showed a stronger tendency to avoid operating airguns than was evident for feeding bowheads (Christie et al. 2009; Koski et al. 2009).

Bowhead whale calls detected in the presence and absence of airgun sounds have been studied extensively in the Beaufort Sea. Early work on the summering grounds in the Canadian Beaufort Sea showed that bowheads continue to produce calls of the usual types when exposed to airgun sounds, although numbers of calls detected may be somewhat lower in the presence of airgun pulses (Richardson et al. 1986). Studies during autumn in the Alaskan Beaufort Sea, one in 1996–1998 and another in 2007–2008, have shown that numbers of calls detected are significantly lower in the presence than in the absence of airgun pulses (Greene et al. 1999a,b; Blackwell et al. 2009a,b; Koski et al. 2009; see also Nations et al. 2009). This decrease could have resulted from movement of the whales away from the area of the seismic survey or a reduction in calling behavior, or a combination of the two. However, concurrent aerial surveys showed that there was strong avoidance of the operating airguns during the 1996–98 study, when most of the whales appeared to be migrating (Miller et al. 1999; Richardson et al. 1999). In contrast, aerial surveys during the 2007–08 study showed less consistent avoidance by the bowheads, many of which appeared to be feeding (Christie et al. 2009; Koski et al. 2009). The reduction in call detection rates during periods of airgun operation may have been more dependent on actual avoidance

during the 1996–98 study and more dependent on reduced calling behavior during the 2007–08 study, but further analysis of the recent data is ongoing.

There are no data on reactions of bowhead whales to seismic surveys in winter or spring.

Gray Whales.—Malme et al. (1986, 1988) studied the responses of feeding eastern gray whales to pulses from a single 100-in³ airgun off St. Lawrence Island in the northern Bering Sea. They estimated, based on small sample sizes, that 50% of feeding gray whales stopped feeding at an average received pressure level of 173 dB re 1 μ Pa on an (approximate) rms basis, and that 10% of feeding whales interrupted feeding at received levels of 163 dB re 1 μ Pa_{rms}. Malme et al. (1986) estimated that an average pressure level of 173 dB occurred at a range of 2.6–2.8 km from an airgun array with a source level of 250 dB re 1 μ Pa_{peak} in the northern Bering Sea. These findings were generally consistent with the results of studies conducted on larger numbers of gray whales migrating off California (Malme et al. 1984; Malme and Miles 1985) and western Pacific gray whales feeding off Sakhalin, Russia (Würsig et al. 1999; Gailey et al. 2007; Johnson et al. 2007; Yazvenko et al. 2007a,b), along with a few data on gray whales off British Columbia (Bain and Williams 2006).

Malme and Miles (1985) concluded that, during migration off California, gray whales showed changes in swimming pattern with received levels of ~160 dB re 1 μ Pa and higher, on an approximate rms basis. The 50% probability of avoidance was estimated to occur at a CPA distance of 2.5 km from a 4000-in³ airgun array operating off central California. This would occur at an average received sound level of ~170 dB re 1 μ Pa_{rms}. Some slight behavioral changes were noted when approaching gray whales reached the distances where received sound levels were 140 to 160 dB re 1 μ Pa_{rms}, but these whales generally continued to approach (at a slight angle) until they passed the sound source at distances where received levels averaged ~170 dB re 1 μ Pa_{rms} (Malme et al. 1984; Malme and Miles 1985).

There was no indication that western gray whales exposed to seismic noise were displaced from their overall feeding grounds near Sakhalin Island during seismic programs in 1997 (Würsig et al. 1999) and in 2001 (Johnson et al. 2007; Meier et al. 2007; Yazvenko et al. 2007a). However, there were indications of subtle behavioral effects among whales that remained in the areas exposed to airgun sounds (Würsig et al. 1999; Gailey et al. 2007; Weller et al. 2006a). Also, there was evidence of localized redistribution of some individuals within the nearshore feeding ground so as to avoid close approaches by the seismic vessel (Weller et al. 2002, 2006b; Yazvenko et al. 2007a). Despite the evidence of subtle changes in some quantitative measures of behavior and local redistribution of some individuals, there was no apparent change in the frequency of feeding, as evident from mud plumes visible at the surface (Yazvenko et al. 2007b). The 2001 seismic program involved an unusually comprehensive combination of real-time monitoring and mitigation measures designed to avoid exposing western gray whales to received levels of sound above about 163 dB re 1 μ Pa_{rms} (Johnson et al. 2007). The lack of strong avoidance or other strong responses was presumably in part a result of the mitigation measures. Effects probably would have been more significant without such intensive mitigation efforts.

Gray whales in British Columbia exposed to seismic survey sound levels up to ~170 dB re 1 μ Pa did not appear to be strongly disturbed (Bain and Williams 2006). The few whales that were observed moved away from the airguns but toward deeper water where sound levels were said to be higher due to propagation effects (Bain and Williams 2006).

Rorquals.—Blue, sei, fin, and minke whales (all of which are members of the genus *Balaenoptera*) often have been seen in areas ensonified by airgun pulses (Stone 2003; MacLean and Haley 2004; Stone and Tasker 2006), and calls from blue and fin whales have been localized in areas with airgun operations (e.g., McDonald et al. 1995; Dunn and Hernandez 2009). Sightings by observers on seismic vessels during 110 large-source seismic surveys off the U.K. from 1997 to 2000 suggest that, during times of good

sightability, sighting rates for mysticetes (mainly fin and sei whales) were similar when large arrays of airguns were shooting vs. silent (Stone 2003; Stone and Tasker 2006). However, these whales tended to exhibit localized avoidance, remaining significantly further (on average) from the airgun array during seismic operations compared with non-seismic periods ($P = 0.0057$; Stone and Tasker 2006). The average CPA distances for baleen whales sighted when large airgun arrays were operating vs. silent were about 1.6 vs. 1.0 km. Baleen whales, as a group, were more often oriented away from the vessel while a large airgun array was shooting compared with periods of no shooting ($P < 0.05$; Stone and Tasker 2006). In addition, fin/sei whales were less likely to remain submerged during periods of seismic shooting (Stone 2003).

In a study off Nova Scotia, Moulton and Miller (2005) found little difference in sighting rates (after accounting for water depth) and initial average sighting distances of baleen whales when airguns were operating (mean = 1324 m) vs. silent (mean = 1303 m). However, there were indications that these whales were more likely to be moving away when seen during airgun operations. Baleen whales at the average sighting distance during airgun operations would have been exposed to sound levels (via direct path) of about 169 dB re 1 $\mu\text{Pa}_{\text{rms}}$ (Moulton and Miller 2005). Similarly, ship-based monitoring studies of blue, fin, sei and minke whales offshore of Newfoundland (Orphan Basin and Laurentian Sub-basin) found no more than small differences in sighting rates and swim directions during seismic vs. non-seismic periods (Moulton et al. 2005, 2006a,b). Analyses of CPA data yielded variable results.⁷ The authors of the Newfoundland reports concluded that, based on observations from the seismic vessel, some mysticetes exhibited localized avoidance of seismic operations (Moulton et al. 2005, 2006a).

Minke whales have occasionally been observed to approach active airgun arrays where received sound levels were estimated to be near 170–180 dB re 1 μPa (McLean and Haley 2004).

Discussion and Conclusions.—Baleen whales generally tend to avoid operating airguns, but avoidance radii are quite variable. Whales are often reported to show no overt reactions to airgun pulses at distances beyond a few kilometers, even though the airgun pulses remain well above ambient noise levels out to much longer distances. However, studies done since the late 1990s of migrating humpback and migrating bowhead whales show reactions, including avoidance, that sometimes extend to greater distances than documented earlier. Avoidance distances often exceed the distances at which boat-based observers can see whales, so observations from the source vessel can be biased. Observations over broader areas may be needed to determine the range of potential effects of some large-source seismic surveys where effects on cetaceans may extend to considerable distances (Richardson et al. 1999; Bain and Williams 2006; Moore and Angliss 2006). Longer-range observations, when required, can sometimes be obtained via systematic aerial surveys or aircraft-based observations of behavior (e.g., Richardson et al. 1986, 1999; Miller et al. 1999, 2005; Yazvenko et al. 2007a,b) or by use of observers on one or more support vessels operating in coordination with the seismic vessel (e.g., Smultea et al. 2004; Johnson et al. 2007). However, the presence of other vessels near the source vessel can, at least at times, reduce sightability of cetaceans from the source vessel (Beland et al. 2009), thus complicating interpretation of sighting data.

⁷ The CPA of baleen whales sighted from the seismic vessels was, on average, significantly closer during non-seismic periods vs. seismic periods in 2004 in the Orphan Basin (means 1526 m vs. 2316 m, respectively; Moulton et al. 2005). In contrast, mean distances without vs. with seismic did not differ significantly in 2005 in either the Orphan Basin (means 973 m vs. 832 m, respectively; Moulton et al. 2006a) or in the Laurentian Sub-basin (means 1928 m vs. 1650 m, respectively; Moulton et al. 2006b). In both 2005 studies, mean distances were greater (though not significantly so) *without* seismic.

Some baleen whales show considerable tolerance of seismic pulses. However, when the pulses are strong enough, avoidance or other behavioral changes become evident. Because the responses become less obvious with diminishing received sound level, it has been difficult to determine the maximum distance (or minimum received sound level) at which reactions to seismic become evident and, hence, how many whales are affected.

Studies of gray, bowhead, and humpback whales have determined that received levels of pulses in the 160–170 dB re 1 $\mu\text{Pa}_{\text{rms}}$ range seem to cause obvious avoidance behavior in a substantial fraction of the animals exposed. In many areas, seismic pulses diminish to these levels at distances ranging from 4 to 15 km from the source. A substantial proportion of the baleen whales within such distances may show avoidance or other strong disturbance reactions to the operating airgun array. However, in other situations, various mysticetes tolerate exposure to full-scale airgun arrays operating at even closer distances, with only localized avoidance and minor changes in activities. At the other extreme, in migrating bowhead whales, avoidance often extends to considerably larger distances (20–30 km) and lower received sound levels (120–130 dB re 1 $\mu\text{Pa}_{\text{rms}}$). Also, even in cases where there is no conspicuous avoidance or change in activity upon exposure to sound pulses from distant seismic operations, there are sometimes subtle changes in behavior (e.g., surfacing–respiration–dive cycles) that are only evident through detailed statistical analysis (e.g., Richardson et al. 1986; Gailey et al. 2007).

Mitigation measures for seismic surveys, especially nighttime seismic surveys, typically assume that many marine mammals (at least baleen whales) tend to avoid approaching airguns, or the seismic vessel itself, before being exposed to levels high enough for there to be any possibility of injury. This assumes that the ramp-up (soft-start) procedure is used when commencing airgun operations, to give whales near the vessel the opportunity to move away before they are exposed to sound levels that might be strong enough to elicit TTS. As noted above, single-airgun experiments with three species of baleen whales show that those species typically do tend to move away when a single airgun starts firing nearby, which simulates the onset of a ramp up. The three species that showed avoidance when exposed to the onset of pulses from a single airgun were *gray whales* (Malme et al. 1984, 1986, 1988); *bowhead whales* (Richardson et al. 1986; Ljungblad et al. 1988); and *humpback whales* (Malme et al. 1985; McCauley et al. 1998, 2000a,b). Since startup of a single airgun is equivalent to the start of a ramp-up (=soft start), this strongly suggests that many baleen whales will begin to move away during the initial stages of a ramp-up.

Data on short-term reactions by cetaceans to impulsive noises are not necessarily indicative of long-term or biologically significant effects. It is not known whether impulsive sounds affect reproductive rate or distribution and habitat use in subsequent days or years. However, gray whales have continued to migrate annually along the west coast of North America despite intermittent seismic exploration (and much ship traffic) in that area for decades (Appendix A in Malme et al. 1984; Richardson et al. 1995), and there has been a substantial increase in the population over recent decades (Allen and Angliss 2010). The western Pacific gray whale population did not seem affected by a seismic survey in its feeding ground during a prior year (Johnson et al. 2007). Similarly, bowhead whales have continued to travel to the eastern Beaufort Sea each summer despite seismic exploration in their summer and autumn range for many years (Richardson et al. 1987), and their numbers have increased notably (Allen and Angliss 2010). Bowheads also have been observed over periods of days or weeks in areas ensonified repeatedly by seismic pulses (Richardson et al. 1987; Harris et al. 2007). However, it is generally not known whether the same individual bowheads were involved in these repeated observations (within and between years) in strongly ensonified areas. In any event, in the absence of some unusual circumstances, the history of coexistence between seismic surveys and baleen whales suggests that brief exposures to sound pulses from any single seismic survey are unlikely to result in prolonged effects.

5.2 Toothed Whales

Little systematic information is available about reactions of toothed whales to noise pulses. Few studies similar to the more extensive baleen whale/seismic pulse work summarized above have been reported for toothed whales. However, there are recent systematic data on sperm whales (e.g., Gordon et al. 2006; Madsen et al. 2006; Winsor and Mate 2006; Jochens et al. 2008; Miller et al. 2009). There is also an increasing amount of information about responses of various odontocetes to seismic surveys based on monitoring studies (e.g., Stone 2003; Smultea et al. 2004; Moulton and Miller 2005; Bain and Williams 2006; Holst et al. 2006; Stone and Tasker 2006; Potter et al. 2007; Hauser et al. 2008; Holst and Smultea 2008; Weir 2008a; Barkaszi et al. 2009; Richardson et al. 2009).

Delphinids (Dolphins and similar) and Monodontids (Beluga).—Seismic operators and marine mammal observers on seismic vessels regularly see dolphins and other small toothed whales near operating airgun arrays, but in general there is a tendency for most delphinids to show some avoidance of operating seismic vessels (e.g., Goold 1996a,b,c; Calambokidis and Osmek 1998; Stone 2003; Moulton and Miller 2005; Holst et al. 2006; Stone and Tasker 2006; Weir 2008a; Richardson et al. 2009; see also Barkaszi et al. 2009). In most cases, the avoidance radii for delphinids appear to be small, on the order of 1 km or less, and some individuals show no apparent avoidance. Studies that have reported cases of small toothed whales close to the operating airguns include Duncan (1985), Arnold (1996), Stone (2003), and Holst et al. (2006). When a 3959 in³, 18-airgun array was firing off California, toothed whales behaved in a manner similar to that observed when the airguns were silent (Arnold 1996). Some dolphins seem to be attracted to the seismic vessel and floats, and some ride the bow wave of the seismic vessel even when a large array of airguns is firing (e.g., Moulton and Miller 2005). Nonetheless, small toothed whales more often tend to head away, or to maintain a somewhat greater distance from the vessel, when a large array of airguns is operating than when it is silent (e.g., Stone and Tasker 2006; Weir 2008a).

Weir (2008b) noted that a group of short-finned pilot whales initially showed an avoidance response to ramp up of a large airgun array, but that this response was limited in time and space. Although the ramp-up procedure is a widely-used mitigation measure, it remains uncertain how effective it is at alerting marine mammals (especially odontocetes) and causing them to move away from seismic operations (Weir 2008b).

Goold (1996a,b,c) studied the effects on common dolphins of 2D seismic surveys in the Irish Sea. Passive acoustic surveys were conducted from the “guard ship” that towed a hydrophone. The results indicated that there was a local displacement of dolphins around the seismic operation. However, observations indicated that the animals were tolerant of the sounds at distances outside a 1-km radius from the airguns (Goold 1996a). Initial reports of larger-scale displacement were later shown to represent a normal autumn migration of dolphins through the area, and were not attributable to seismic surveys (Goold 1996a,b,c).

The beluga is a species that (at least at times) shows long-distance avoidance of seismic vessels. Aerial surveys conducted in the southeastern Beaufort Sea in summer found that sighting rates of belugas were significantly lower at distances 10–20 km compared with 20–30 km from an operating airgun array (Miller et al. 2005). The low number of beluga sightings by marine mammal observers on the vessel seemed to confirm there was a strong avoidance response to the 2250 in³ airgun array. More recent seismic monitoring studies in the same area have confirmed that the apparent displacement effect on belugas extended farther than has been shown for other small odontocetes exposed to airgun pulses (e.g., Harris et al. 2007).

Observers stationed on seismic vessels operating off the U.K. from 1997 to 2000 have provided data on the occurrence and behavior of various toothed whales exposed to seismic pulses (Stone 2003;

Gordon et al. 2004; Stone and Tasker 2006). Dolphins of various species often showed more evidence of avoidance of operating airgun arrays than has been reported previously for small odontocetes. Sighting rates of white-sided dolphins, white-beaked dolphins, *Lagenorhynchus* spp., and all small odontocetes combined were significantly lower during periods when large-volume⁸ airgun arrays were shooting. Except for the pilot whale and bottlenose dolphin, CPA distances for all of the small odontocete species tested, including killer whales, were significantly farther from large airgun arrays during periods of shooting compared with periods of no shooting. Pilot whales were less responsive than other small odontocetes in the presence of seismic surveys (Stone and Tasker 2006). For small odontocetes as a group, and most individual species, orientations differed between times when large airgun arrays were operating vs. silent, with significantly fewer animals traveling towards and/or more traveling away from the vessel during shooting (Stone and Tasker 2006). Observers' records suggested that fewer cetaceans were feeding and fewer were interacting with the survey vessel (e.g., bow-riding) during periods with airguns operating, and small odontocetes tended to swim faster during periods of shooting (Stone and Tasker 2006). For most types of small odontocetes sighted by observers on seismic vessels, the median CPA distance was ≥ 0.5 km larger during airgun operations (Stone and Tasker 2006). Killer whales appeared to be more tolerant of seismic shooting in deeper waters.

Data collected during seismic operations in the Gulf of Mexico and off Central America show similar patterns. A summary of vessel-based monitoring data from the Gulf of Mexico during 2003–2008 showed that delphinids were generally seen farther from the vessel during seismic than during non-seismic periods (based on Barkaszi et al. 2009, excluding sperm whales). Similarly, during two NSF-funded L-DEO seismic surveys that used a large 20 airgun array (~ 7000 in³), sighting rates of delphinids were lower and initial sighting distances were farther away from the vessel during seismic than non-seismic periods (Smultea et al. 2004; Holst et al. 2005a, 2006; Richardson et al. 2009). Monitoring results during a seismic survey in the Southeast Caribbean showed that the mean CPA of delphinids was 991 m during seismic operations vs. 172 m when the airguns were not operational (Smultea et al. 2004). Surprisingly, nearly all acoustic detections via a towed passive acoustic monitoring (PAM) array, including both delphinids and sperm whales, were made when the airguns were operating (Smultea et al. 2004). Although the number of sightings during monitoring of a seismic survey off the Yucatán Peninsula, Mexico, was small ($n = 19$), the results showed that the mean CPA distance of delphinids there was 472 m during seismic operations vs. 178 m when the airguns were silent (Holst et al. 2005a). The acoustic detection rates were nearly 5 times higher during non-seismic compared with seismic operations (Holst et al. 2005a).

For two additional NSF-funded L-DEO seismic surveys in the Eastern Tropical Pacific, both using a large 36-airgun array (~ 6600 in³), the results are less easily interpreted (Richardson et al. 2009). During both surveys, the delphinid detection rate was lower during seismic than during non-seismic periods, as found in various other projects, but the mean CPA distance of delphinids was closer (not farther) during seismic periods (Hauser et al. 2008; Holst and Smultea 2008).

During two seismic surveys off Newfoundland and Labrador in 2004–05, dolphin sighting rates were lower during seismic periods than during non-seismic periods after taking temporal factors into account, although the difference was statistically significant only in 2004 (Moulton et al. 2005, 2006a). In 2005, the mean CPA distance of dolphins was significantly farther during seismic periods (807 vs. 652 m); in 2004, the corresponding difference was not significant.

⁸ Large volume means at least 1300 in³, with most (79%) at least 3000 in³.

Among Atlantic spotted dolphins off Angola ($n = 16$ useable groups), marked short-term and localized displacement was found in response to seismic operations conducted with a 24-airgun array (3147 in³ or 5085 in³) (Weir 2008a). Sample sizes were low, but CPA distances of dolphin groups were significantly larger when airguns were on (mean 1080 m) vs. off (mean 209 m). No Atlantic spotted dolphins were seen within 500 m of the airguns when they were operating, whereas all sightings when airguns were silent occurred within 500 m, including the only recorded “positive approach” behaviors.

Reactions of toothed whales to a single airgun or other small airgun source are not well documented, but tend to be less substantial than reactions to large airgun arrays (e.g., Stone 2003; Stone and Tasker 2006). During 91 site surveys off the U.K. in 1997–2000, sighting rates of all small odontocetes combined were significantly lower during periods the low-volume⁹ airgun sources were operating, and effects on orientation were evident for all species and groups tested (Stone and Tasker 2006). Results from four NSF-funded L-DEO seismic surveys using small arrays (up to 3 GI guns and 315 in³) were inconclusive. During surveys in the Eastern Tropical Pacific (Holst et al. 2005a) and in the Northwest Atlantic (Haley and Koski 2004), detection rates were slightly lower during seismic compared to non-seismic periods. However, mean CPAs were closer during seismic operations during one cruise (Holst et al. 2005a), and greater during the other cruise (Haley and Koski 2004). Interpretation of the data was confounded by the fact that survey effort and/or number of sightings during non-seismic periods during both surveys was small. Results from another two small-array surveys were even more variable (MacLean and Koski 2005; Smultea and Holst 2008).

Captive bottlenose dolphins and beluga whales exhibited changes in behavior when exposed to strong pulsed sounds similar in duration to those typically used in seismic surveys (Finneran et al. 2000, 2002, 2005). Finneran et al. (2002) exposed a captive bottlenose dolphin and beluga to single impulses from a water gun (80 in³). As compared with airgun pulses, water gun impulses were expected to contain proportionally more energy at higher frequencies because there is no significant gas-filled bubble, and thus little low-frequency bubble-pulse energy (Hutchinson and Detrick 1984). The captive animals sometimes vocalized after exposure and exhibited reluctance to station at the test site where subsequent exposure to impulses would be implemented (Finneran et al. 2002). Similar behaviors were exhibited by captive bottlenose dolphins and a beluga exposed to single underwater pulses designed to simulate those produced by distant underwater explosions (Finneran et al. 2000). It is uncertain what relevance these observed behaviors in captive, trained marine mammals exposed to single transient sounds may have to free-ranging animals exposed to multiple pulses. In any event, the animals tolerated rather high received levels of sound before exhibiting the aversive behaviors mentioned above.

Odontocete responses (or lack of responses) to noise pulses from underwater explosions (as opposed to airgun pulses) may be indicative of odontocete responses to very strong noise pulses. During the 1950s, small explosive charges were dropped into an Alaskan river in attempts to scare belugas away from salmon. Success was limited (Fish and Vania 1971; Frost et al. 1984). Small explosive charges were “not always effective” in moving bottlenose dolphins away from sites in the Gulf of Mexico where larger demolition blasts were about to occur (Klima et al. 1988). Odontocetes may be attracted to fish killed by explosions, and thus attracted rather than repelled by “scare” charges. Captive false killer whales showed no obvious reaction to single noise pulses from small (10 g) charges; the received level was ~185 dB re 1 μ Pa (Akamatsu et al. 1993). Jefferson and Curry (1994) reviewed several additional studies that found limited or no effects of noise pulses from small explosive charges on killer whales and

⁹ For low volume arrays, maximum volume was 820 in³, with most (87%) \leq 180 in³.

other odontocetes. Aside from the potential for causing auditory impairment (see below), the tolerance to these charges may indicate a lack of effect, or the failure to move away may simply indicate a stronger desire to feed, regardless of circumstances.

Phocoenids (Porpoises).—Porpoises, like delphinids, show variable reactions to seismic operations, and reactions apparently depend on species. The limited available data suggest that harbor porpoises show stronger avoidance of seismic operations than Dall’s porpoises (Stone 2003; MacLean and Koski 2005; Bain and Williams 2006). In Washington State waters, the harbor porpoise—despite being considered a high-frequency specialist—appeared to be the species affected by the lowest received level of airgun sound (<145 dB re $1 \mu\text{Pa}_{\text{rms}}$ at a distance >70 km; Bain and Williams 2006). Similarly, during seismic surveys with large airgun arrays off the U.K. in 1997–2000, there were significant differences in directions of travel by harbor porpoises during periods when the airguns were shooting vs. silent (Stone 2003; Stone and Tasker 2006). A captive harbor porpoise exposed to single sound pulses from a small airgun showed aversive behavior upon receipt of a pulse with received level above 174 dB re $1 \mu\text{Pa}_{\text{pk-pk}}$ or SEL >145 dB re $1 \mu\text{Pa}^2 \cdot \text{s}$ (Lucke et al. 2009). In contrast, Dall’s porpoises seem relatively tolerant of airgun operations (MacLean and Koski 2005; Bain and Williams 2006), although they too have been observed to avoid large arrays of operating airguns (Calambokidis and Osmeck 1998; Bain and Williams 2006). The apparent tendency for greater responsiveness in the harbor porpoise is consistent with their relative responsiveness to boat traffic and some other acoustic sources (Richardson et al. 1995; Southall et al. 2007).

Beaked Whales.—There are almost no specific data on the behavioral reactions of beaked whales to seismic surveys. Most beaked whales tend to avoid approaching vessels of other types (e.g., Würsig et al. 1998). They may also dive for an extended period when approached by a vessel (e.g., Kasuya 1986), although it is uncertain how much longer such dives may be as compared to dives by undisturbed beaked whales, which also are often quite long (Baird et al. 2006; Tyack et al. 2006b). In any event, it is likely that most beaked whales would also show strong avoidance of an approaching seismic vessel, regardless of whether or not the airguns are operating. However, this has not been documented explicitly. Northern bottlenose whales sometimes are quite tolerant of slow-moving vessels not emitting airgun pulses (Reeves et al. 1993; Hooker et al. 2001). The few detections (acoustic or visual) of northern bottlenose whales from seismic vessels during recent seismic surveys off Nova Scotia have been during times when the airguns were shut down; no detections were reported when the airguns were operating (Moulton and Miller 2005; Potter et al. 2007). However, other visual and acoustic studies indicated that some northern bottlenose whales remained in the general area and continued to produce high-frequency clicks when exposed to sound pulses from distant seismic surveys (Gosselin and Lawson 2004; Laurinoli and Cochran 2005; Simard et al. 2005).

There are increasing indications that some beaked whales tend to strand when military exercises involving mid-frequency sonar operation are ongoing nearby (e.g., Simmonds and Lopez-Jurado 1991; Frantzis 1998; NOAA and USN 2001; Jepson et al. 2003; Barlow and Gisiner 2006; see also the “Strandings and Mortality” subsection, later). These strandings are apparently at least in part a disturbance response, although auditory or other injuries or other physiological effects may also be a factor. Whether beaked whales would ever react similarly to seismic surveys is unknown. Seismic survey sounds are quite different from those of the sonars in operation during the above-cited incidents. No conclusive link has been established between seismic surveys and beaked whale strandings. There was a stranding of two Cuvier’s beaked whales in the Gulf of California (Mexico) in September 2002 when the R/V *Maurice Ewing* was conducting a seismic survey in the general area (e.g., Malakoff 2002; Hildebrand 2005). However, NMFS did not establish a cause and effect relationship between this stranding and the seismic survey activities (Hogarth 2002). Cox et al. (2006) noted the “lack of knowledge regard-

ing the temporal and spatial correlation between the [stranding] and the sound source”. Hildebrand (2005) illustrated the approximate temporal-spatial relationships between the stranding and the *Ewing*'s tracks, but the time of the stranding was not known with sufficient precision for accurate determination of the CPA distance of the whales to the *Ewing*. Another stranding of Cuvier's beaked whales in the Galápagos occurred during a seismic survey in April 2000; however “There is no obvious mechanism that bridges the distance between this source and the stranding site” (Gentry [ed.] 2002).

Sperm Whales.—All three species of sperm whales have been reported to show avoidance reactions to standard vessels not emitting airgun sounds (e.g., Richardson et al. 1995; Würsig et al. 1998; McAlpine 2002; Baird 2005). However, most studies of the sperm whale *Physeter macrocephalus* exposed to airgun sounds indicate that this species shows considerable tolerance of airgun pulses. The whales usually do not show strong avoidance (i.e., they do not leave the area) and they continue to call.

There were some early and limited observations suggesting that sperm whales in the Southern Ocean ceased calling during some (but not all) times when exposed to weak noise pulses from extremely distant (>300 km) seismic exploration. However, other operations in the area could also have been a factor (Bowles et al. 1994). This “quieting” was suspected to represent a disturbance effect, in part because sperm whales exposed to pulsed man-made sounds at higher frequencies often cease calling (Watkins and Schevill 1975; Watkins et al. 1985). Also, there was an early preliminary account of possible long-range avoidance of seismic vessels by sperm whales in the Gulf of Mexico (Mate et al. 1994). However, this has not been substantiated by subsequent more detailed work in that area (Gordon et al. 2006; Winsor and Mate 2006; Jochens et al. 2008; Miller et al. 2009).

Recent and more extensive data from vessel-based monitoring programs in U.K. waters and off Newfoundland and Angola suggest that sperm whales in those areas show little evidence of avoidance or behavioral disruption in the presence of operating seismic vessels (Stone 2003; Stone and Tasker 2006; Moulton et al. 2005, 2006a; Weir 2008a). Among sperm whales off Angola ($n = 96$ useable groups), there were no significant differences in encounter rates (sightings/hr) when a 24-airgun array (3147 in³ or 5085 in³) was operating vs. silent (Weir 2008a). There was also no significant difference in the CPA distances of the sperm whale sightings when airguns were on vs. off (means 3039 m vs. 2594 m, respectively). Encounter rate tended to increase over the 10-month duration of the seismic survey. These types of observations are difficult to interpret because the observers are stationed on or near the seismic vessel, and may underestimate reactions by some of the more responsive animals, which may be beyond visual range. However, these results do seem to show considerable tolerance of seismic surveys by at least some sperm whales. Also, a study off northern Norway indicated that sperm whales continued to call when exposed to pulses from a distant seismic vessel. Received levels of the seismic pulses were up to 146 dB re 1 μPa_{p-p} (Madsen et al. 2002).

Similarly, a study conducted off Nova Scotia that analyzed recordings of sperm whale vocalizations at various distances from an active seismic program did not detect any obvious changes in the distribution or behavior of sperm whales (McCall Howard 1999).

Sightings of sperm whales by observers on seismic vessels operating in the Gulf of Mexico during 2003–2008 were at very similar average distances regardless of the airgun operating conditions (Barkaszi et al. 2009). For example, the mean sighting distance was 1839 m when the airgun array was in full operation ($n=612$) vs. 1960 m when all airguns were off ($n=66$).

A controlled study of the reactions of tagged sperm whales to seismic surveys was done recently in the Gulf of Mexico — the Sperm Whale Seismic Study or SWSS (Gordon et al. 2006; Madsen et al. 2006; Winsor and Mate 2006; Jochens et al. 2008; Miller et al. 2009). During SWSS, D-tags (Johnson and Tyack 2003) were used to record the movement and acoustic exposure of eight foraging sperm whales

before, during, and after controlled exposures to sound from airgun arrays (Jochens et al. 2008; Miller et al. 2009). Whales were exposed to maximum received sound levels of 111–147 dB re 1 $\mu\text{Pa}_{\text{rms}}$ (131–162 dB re 1 $\mu\text{Pa}_{\text{pk-pk}}$) at ranges of ~1.4–12.8 km from the sound source (Miller et al. 2009). Although the tagged whales showed no discernible horizontal avoidance, some whales showed changes in diving and foraging behavior during full-array exposure, possibly indicative of subtle negative effects on foraging (Jochens et al. 2008; Miller et al. 2009; Tyack 2009). Two indications of foraging that they studied were oscillations in pitch and occurrence of echolocation buzzes, both of which tend to occur when a sperm whale closes-in on prey. "Oscillations in pitch generated by swimming movements during foraging dives were on average 6% lower during exposure than during the immediately following post-exposure period, with all 7 foraging whales exhibiting less pitching ($P = 0.014$). Buzz rates, a proxy for attempts to capture prey, were 19% lower during exposure..." (Miller et al. 2009). Although the latter difference was not statistically significant ($P = 0.141$), the percentage difference in buzz rate during exposure vs. post-exposure conditions appeared to be strongly correlated with airgun-whale distance (Miller et al. 2009: Fig. 5; Tyack 2009).

Discussion and Conclusions.—Dolphins and porpoises are often seen by observers on active seismic vessels, occasionally at close distances (e.g., bow riding). However, some studies near the U.K., Newfoundland and Angola, in the Gulf of Mexico, and off Central America have shown localized avoidance. Also, belugas summering in the Canadian Beaufort Sea showed larger-scale avoidance, tending to avoid waters out to 10–20 km from operating seismic vessels. In contrast, recent studies show little evidence of conspicuous reactions by sperm whales to airgun pulses, contrary to earlier indications.

There are almost no specific data on responses of beaked whales to seismic surveys, but it is likely that most if not all species show strong avoidance. There is increasing evidence that some beaked whales may strand after exposure to strong noise from sonars. Whether they ever do so in response to seismic survey noise is unknown. Northern bottlenose whales seem to continue to call when exposed to pulses from distant seismic vessels.

Overall, odontocete reactions to large arrays of airguns are variable and, at least for delphinids and some porpoises, seem to be confined to a smaller radius than has been observed for some mysticetes. However, other data suggest that some odontocetes species, including belugas and harbor porpoises, may be more responsive than might be expected given their poor low-frequency hearing. Reactions at longer distances may be particularly likely when sound propagation conditions are conducive to transmission of the higher-frequency components of airgun sound to the animals' location (DeRuiter et al. 2006; Goold and Coates 2006; Tyack et al. 2006a; Potter et al. 2007).

For delphinids, and possibly the Dall's porpoise, the available data suggest that a ≥ 170 dB re 1 $\mu\text{Pa}_{\text{rms}}$ disturbance criterion (rather than ≥ 160 dB) would be appropriate. With a medium-to-large airgun array, received levels typically diminish to 170 dB within 1–4 km, whereas levels typically remain above 160 dB out to 4–15 km (e.g., Tolstoy et al. 2009). Reaction distances for delphinids are more consistent with the typical 170 dB re 1 $\mu\text{Pa}_{\text{rms}}$ distances. The 160 dB (rms) criterion currently applied by NMFS was developed based primarily on data from gray and bowhead whales. Avoidance distances for delphinids and Dall's porpoises tend to be shorter than for those two mysticete species. For delphinids and Dall's porpoises, there is no indication of strong avoidance or other disruption of behavior at distances beyond those where received levels would be ~ 170 dB re 1 $\mu\text{Pa}_{\text{rms}}$.

5.3 Pinnipeds

Few studies of the reactions of pinnipeds to noise from open-water seismic exploration have been published (for review of the early literature, see Richardson et al. 1995). However, pinnipeds have been

observed during a number of seismic monitoring studies. Monitoring in the Beaufort Sea during 1996–2002 provided a substantial amount of information on avoidance responses (or lack thereof) and associated behavior. Additional monitoring of that type has been done in the Beaufort and Chukchi Seas in 2006–2009. Pinnipeds exposed to seismic surveys have also been observed during seismic surveys along the U.S. west coast. Some limited data are available on physiological responses of pinnipeds exposed to seismic sound, as studied with the aid of radio telemetry. Also, there are data on the reactions of pinnipeds to various other related types of impulsive sounds.

Early observations provided considerable evidence that pinnipeds are often quite tolerant of strong pulsed sounds. During seismic exploration off Nova Scotia, gray seals exposed to noise from airguns and linear explosive charges reportedly did not react strongly (J. Parsons *in* Greene et al. 1985). An airgun caused an initial startle reaction among South African fur seals but was ineffective in scaring them away from fishing gear (Anonymous 1975). Pinnipeds in both water and air sometimes tolerate strong noise pulses from non-explosive and explosive scaring devices, especially if attracted to the area for feeding or reproduction (Mate and Harvey 1987; Reeves et al. 1996). Thus, pinnipeds are expected to be rather tolerant of, or to habituate to, repeated underwater sounds from distant seismic sources, at least when the animals are strongly attracted to the area.

In the U.K., a radio-telemetry study demonstrated short-term changes in the behavior of harbor (=common) and gray seals exposed to airgun pulses (Thompson et al. 1998). Harbor seals were exposed to seismic pulses from a 90-in³ array (3 × 30 in³ airguns), and behavioral responses differed among individuals. One harbor seal avoided the array at distances up to 2.5 km from the source and only resumed foraging dives after seismic stopped. Another harbor seal exposed to the same small airgun array showed no detectable behavioral response, even when the array was within 500 m. Gray seals exposed to a single 10-in³ airgun showed an avoidance reaction: they moved away from the source, increased swim speed and/or dive duration, and switched from foraging dives to predominantly transit dives. These effects appeared to be short-term as gray seals either remained in, or returned at least once to, the foraging area where they had been exposed to seismic pulses. These results suggest that there are interspecific as well as individual differences in seal responses to seismic sounds.

Off California, visual observations from a seismic vessel showed that California sea lions “typically ignored the vessel and array. When [they] displayed behavior modifications, they often appeared to be reacting visually to the sight of the towed array. At times, California sea lions were attracted to the array, even when it was on. At other times, these animals would appear to be actively avoiding the vessel and array” (Arnold 1996). In Puget Sound, sighting distances for harbor seals and California sea lions tended to be larger when airguns were operating; both species tended to orient away whether or not the airguns were firing (Calambokidis and Osmek 1998). Bain and Williams (2006) also stated that their small sample of harbor seals and sea lions tended to orient and/or move away upon exposure to sounds from a large airgun array.

Monitoring work in the Alaskan Beaufort Sea during 1996–2001 provided considerable information regarding the behavior of seals exposed to seismic pulses (Harris et al. 2001; Moulton and Lawson 2002). Those seismic projects usually involved arrays of 6–16 airguns with total volumes 560–1500 in³. Subsequent monitoring work in the Canadian Beaufort Sea in 2001–2002, with a somewhat larger airgun system (24 airguns, 2250 in³), provided similar results (Miller et al. 2005). The combined results suggest that some seals avoid the immediate area around seismic vessels. In most survey years, ringed seal sightings averaged somewhat farther away from the seismic vessel when the airguns were operating than when they were not (Moulton and Lawson 2002). Also, seal sighting rates at the water surface were lower during airgun array operations than during no-airgun periods in each survey year except 1997.

However, the avoidance movements were relatively small, on the order of 100 m to (at most) a few hundreds of meters, and many seals remained within 100–200 m of the trackline as the operating airgun array passed by.

The operation of the airgun array had minor and variable effects on the behavior of seals visible at the surface within a few hundred meters of the airguns (Moulton and Lawson 2002). The behavioral data indicated that some seals were more likely to swim away from the source vessel during periods of airgun operations and more likely to swim towards or parallel to the vessel during non-seismic periods. No consistent relationship was observed between exposure to airgun noise and proportions of seals engaged in other recognizable behaviors, e.g., “looked” and “dove”. Such a relationship might have occurred if seals seek to reduce exposure to strong seismic pulses, given the reduced airgun noise levels close to the surface where “looking” occurs (Moulton and Lawson 2002).

Monitoring results from the Canadian Beaufort Sea during 2001–2002 were more variable (Miller et al. 2005). During 2001, sighting rates of seals (mostly ringed seals) were similar during all seismic states, including periods without airgun operations. However, seals tended to be seen closer to the vessel during non-seismic than seismic periods. In contrast, during 2002, sighting rates of seals were higher during non-seismic periods than seismic operations, and seals were seen farther from the vessel during non-seismic compared to seismic activity (a marginally significant result). The combined data for both years showed that sighting rates were higher during non-seismic periods compared to seismic periods, and that sighting distances were similar during both seismic states. Miller et al. (2005) concluded that seals showed very limited avoidance to the operating airgun array.

Vessel-based monitoring also took place in the Alaskan Chukchi and Beaufort seas during 2006–2008 (Reiser et al. 2009). Observers on the seismic vessels saw phocid seals less frequently while airguns were operating than when airguns were silent. Also, during airgun operations, those observers saw seals less frequently than did observers on nearby vessels without airguns. Finally, observers on the latter “no-airgun” vessels saw seals more often when the nearby source vessels’ airguns were operating than when they were silent. All of these observations are indicative of a tendency for phocid seals to exhibit localized avoidance of the seismic source vessel when airguns are firing (Reiser et al. 2009).

In summary, visual monitoring from seismic vessels has shown only slight (if any) avoidance of airguns by pinnipeds, and only slight (if any) changes in behavior. These studies show that many pinnipeds do not avoid the area within a few hundred meters of an operating airgun array. However, based on the studies with large sample size, or observations from a separate monitoring vessel, or radio telemetry, it is apparent that some phocid seals do show localized avoidance of operating airguns. The limited nature of this tendency for avoidance is a concern. It suggests that one cannot rely on pinnipeds to move away, or to move very far away, before received levels of sound from an approaching seismic survey vessel approach those that may cause hearing impairment (see below).

5.4 Sirenians, Sea Otter and Polar Bear

We are not aware of any information on the reactions of sirenians to airgun sounds.

Behavior of sea otters along the California coast was monitored by Riedman (1983, 1984) while they were exposed to a single 100 in³ airgun and a 4089 in³ airgun array. No disturbance reactions were evident when the airgun array was as close as 0.9 km. Sea otters also did not respond noticeably to the single airgun. These results suggest that sea otters may be less responsive to marine seismic pulses than some other marine mammals, such as mysticetes and odontocetes (summarized above). Also, sea otters spend a great deal of time at the surface feeding and grooming (Riedman 1983, 1984). While at the

surface, the potential noise exposure of sea otters would be much reduced by pressure-release and interference (Lloyd's mirror) effects at the surface (Greene and Richardson 1988; Richardson et al. 1995).

Airgun effects on polar bears have not been studied. However, polar bears on the ice would be largely unaffected by underwater sound. Sound levels received by polar bears in the water would be attenuated because polar bears generally do not dive much below the surface and received levels of airgun sounds are reduced near the surface because of the aforementioned pressure release and interference effects at the water's surface.

6. Hearing Impairment and Other Physical Effects of Seismic Surveys

Temporary or permanent hearing impairment is a possibility when marine mammals are exposed to very strong sounds. Temporary threshold shift (TTS) has been demonstrated and studied in certain captive odontocetes and pinnipeds exposed to strong sounds (reviewed in Southall et al. 2007). However, there has been no specific documentation of TTS let alone permanent hearing damage, i.e. permanent threshold shift (PTS), in free-ranging marine mammals exposed to sequences of airgun pulses during realistic field conditions. Current NMFS policy regarding exposure of marine mammals to high-level sounds is that cetaceans and pinnipeds should not be exposed to impulsive sounds ≥ 180 and 190 dB re $1 \mu\text{Pa}_{\text{rms}}$, respectively (NMFS 2000). Those criteria have been used in establishing the safety (=shut-down) radii planned for numerous seismic surveys conducted under U.S. jurisdiction. However, those criteria were established before there was any information about the minimum received levels of sounds necessary to cause auditory impairment in marine mammals. As discussed below,

- the 180-dB criterion for cetaceans is probably quite precautionary, i.e., lower than necessary to avoid temporary auditory impairment let alone permanent auditory injury, at least for delphinids.
- TTS is not injury and does not constitute "Level A harassment" in U.S. MMPA terminology.
- the minimum sound level necessary to cause permanent hearing impairment ("Level A harassment") is higher, by a variable and generally unknown amount, than the level that induces barely-detectable TTS.
- the level associated with the onset of TTS is often considered to be a level below which there is no danger of permanent damage. The actual PTS threshold is likely to be well above the level causing onset of TTS (Southall et al. 2007).

Recommendations for new science-based noise exposure criteria for marine mammals, frequency-weighting procedures, and related matters were published recently (Southall et al. 2007). Those recommendations have not, as of late 2009, been formally adopted by NMFS for use in regulatory processes and during mitigation programs associated with seismic surveys. However, some aspects of the recommendations have been taken into account in certain EISs and small-take authorizations. NMFS has indicated that it may issue new noise exposure criteria for marine mammals that account for the now-available scientific data on TTS, the expected offset between the TTS and PTS thresholds, differences in the acoustic frequencies to which different marine mammal groups are sensitive, and other relevant factors. Preliminary information about possible changes in the regulatory and mitigation requirements, and about the possible structure of new criteria, was given by Wieting (2004) and NMFS (2005).

Several aspects of the monitoring and mitigation measures that are now often implemented during seismic survey projects are designed to detect marine mammals occurring near the airgun array, and to avoid exposing them to sound pulses that might, at least in theory, cause hearing impairment. In addition, many cetaceans and (to a limited degree) pinnipeds show some avoidance of the area where received levels of airgun sound are high enough such that hearing impairment could potentially occur. In those

cases, the avoidance responses of the animals themselves will reduce or (most likely) avoid the possibility of hearing impairment.

Non-auditory physical effects may also occur in marine mammals exposed to strong underwater pulsed sound. Possible types of non-auditory physiological effects or injuries that might (in theory) occur include stress, neurological effects, bubble formation, and other types of organ or tissue damage. It is possible that some marine mammal species (i.e., beaked whales) may be especially susceptible to injury and/or stranding when exposed to strong pulsed sounds. The following subsections summarize available data on noise-induced hearing impairment and non-auditory physical effects.

6.1 Temporary Threshold Shift (TTS)

TTS is the mildest form of hearing impairment that can occur during exposure to a strong sound (Kryter 1985). While experiencing TTS, the hearing threshold rises and a sound must be stronger in order to be heard. It is a temporary phenomenon, and (especially when mild) is not considered to represent physical damage or “injury” (Southall et al. 2007). Rather, the onset of TTS is an indicator that, if the animal is exposed to higher levels of that sound, physical damage is ultimately a possibility.

The magnitude of TTS depends on the level and duration of noise exposure, and to some degree on frequency, among other considerations (Kryter 1985; Richardson et al. 1995; Southall et al. 2007). For sound exposures at or somewhat above the TTS threshold, hearing sensitivity recovers rapidly after exposure to the noise ends. In terrestrial mammals, TTS can last from minutes or hours to (in cases of strong TTS) days. Only a few data have been obtained on sound levels and durations necessary to elicit mild TTS in marine mammals (none in mysticetes), and none of the published data concern TTS elicited by exposure to multiple pulses of sound during operational seismic surveys (Southall et al. 2007).

Toothed Whales.—There are empirical data on the sound exposures that elicit onset of TTS in captive bottlenose dolphins and belugas. The majority of these data concern non-impulse sound, but there are some limited published data concerning TTS onset upon exposure to a single pulse of sound from a watergun (Finneran et al. 2002). A detailed review of all TTS data from marine mammals can be found in Southall et al. (2007). The following summarizes some of the key results from odontocetes.

Recent information corroborates earlier expectations that the effect of exposure to strong transient sounds is closely related to the total amount of acoustic energy that is received. Finneran et al. (2005) examined the effects of tone duration on TTS in bottlenose dolphins. Bottlenose dolphins were exposed to 3 kHz tones (non-impulsive) for periods of 1, 2, 4 or 8 s, with hearing tested at 4.5 kHz. For 1-s exposures, TTS occurred with SELs of 197 dB, and for exposures >1 s, SEL >195 dB resulted in TTS (SEL is equivalent to energy flux, in dB re 1 $\mu\text{Pa}^2 \cdot \text{s}$). At an SEL of 195 dB, the mean TTS (4 min after exposure) was 2.8 dB. Finneran et al. (2005) suggested that an SEL of 195 dB is the likely threshold for the onset of TTS in dolphins and belugas exposed to tones of durations 1–8 s (i.e., TTS onset occurs at a near-constant SEL, independent of exposure duration). That implies that, at least for non-impulsive tones, a doubling of exposure time results in a 3 dB lower TTS threshold.

The assumption that, in marine mammals, the occurrence and magnitude of TTS is a function of cumulative acoustic energy (SEL) is probably an oversimplification. Kastak et al. (2005) reported preliminary evidence from pinnipeds that, for prolonged non-impulse noise, higher SELs were required to elicit a given TTS if exposure duration was short than if it was longer, i.e., the results were not fully consistent with an equal-energy model to predict TTS onset. Mooney et al. (2009a) showed this in a bottlenose dolphin exposed to octave-band non-impulse noise ranging from 4 to 8 kHz at SPLs of 130 to 178 dB re 1 μPa for periods of 1.88 to 30 min. Higher SELs were required to induce a given TTS if exposure duration short than if it was longer. Exposure of the aforementioned bottlenose dolphin to a sequence of

brief sonar signals showed that, with those brief (but non-impulse) sounds, the received energy (SEL) necessary to elicit TTS was higher than was the case with exposure to the more prolonged octave-band noise (Mooney et al. 2009b). Those authors concluded that, when using (non-impulse) acoustic signals of duration ~ 0.5 s, SEL must be at least 210–214 dB re $1 \mu\text{Pa}^2 \cdot \text{s}$ to induce TTS in the bottlenose dolphin.

On the other hand, the TTS threshold for odontocetes exposed to a single impulse from a watrgun (Finneran et al. 2002) appeared to be somewhat lower than for exposure to non-impulse sound. This was expected, based on evidence from terrestrial mammals showing that broadband pulsed sounds with rapid rise times have greater auditory effect than do non-impulse sounds (Southall et al. 2007). The received energy level of a single seismic pulse that caused the onset of mild TTS in the beluga, as measured without frequency weighting, was ~ 186 dB re $1 \mu\text{Pa}^2 \cdot \text{s}$ or 186 dB SEL (Finneran et al. 2002).¹⁰ The rms level of an airgun pulse (in dB re $1 \mu\text{Pa}$ measured over the duration of the pulse) is typically 10–15 dB higher than the SEL for the same pulse when received within a few kilometers of the airguns. Thus, a single airgun pulse might need to have a received level of ~ 196 – 201 dB re $1 \mu\text{Pa}_{\text{rms}}$ in order to produce brief, mild TTS. Exposure to several strong seismic pulses that each has a flat-weighted received level near 190 dB_{rms} (175–180 dB SEL) could result in cumulative exposure of ~ 186 dB SEL (flat-weighted) or ~ 183 dB SEL (M_{mf} -weighted), and thus slight TTS in a small odontocete. That assumes that the TTS threshold upon exposure to multiple pulses is (to a first approximation) a function of the total received pulse energy, without allowance for any recovery between pulses.

The above TTS information for odontocetes is derived from studies on the bottlenose dolphin and beluga. For the one harbor porpoise tested, the received level of airgun sound that elicited onset of TTS was lower. The animal was exposed to single pulses from a small (20 in^3) airgun, and auditory evoked potential methods were used to test the animal's hearing sensitivity at frequencies of 4, 32, or 100 kHz after each exposure (Lucke et al. 2009). Based on the measurements at 4 kHz, TTS occurred upon exposure to one airgun pulse with received level ~ 200 dB re $1 \mu\text{Pa}_{\text{pk-pk}}$ or an SEL of 164.3 dB re $1 \mu\text{Pa}^2 \cdot \text{s}$. If these results from a single animal are representative, it is inappropriate to assume that onset of TTS occurs at similar received levels in all odontocetes (*cf.* Southall et al. 2007). Some cetaceans may incur TTS at lower sound exposures than are necessary to elicit TTS in the beluga or bottlenose dolphin.

Insofar as we are aware, there are no published data confirming that the auditory effect of a sequence of airgun pulses received by an odontocete is a function of their cumulative energy. Southall et al. (2007) consider that to be a reasonable, but probably somewhat precautionary, assumption. It is precautionary because, based on data from terrestrial mammals, one would expect that a given energy exposure would have somewhat less effect if separated into discrete pulses, with potential opportunity for partial auditory recovery between pulses. However, as yet there has been little study of the rate of recovery from TTS in marine mammals, and in humans and other terrestrial mammals the available data on recovery are quite variable. Southall et al. (2007) concluded that—until relevant data on recovery are available from marine mammals—it is appropriate not to allow for any assumed recovery during the intervals between pulses within a pulse sequence.

Additional data are needed to determine the received sound levels at which small odontocetes would start to incur TTS upon exposure to repeated, low-frequency pulses of airgun sound with variable received levels. To determine how close an airgun array would need to approach in order to elicit TTS, it

¹⁰ If the low-frequency components of the watrgun sound used in the experiments of Finneran et al. (2002) are downweighted as recommended by Southall et al. (2007) using their M_{mf} -weighting curve, the effective exposure level for onset of mild TTS was 183 dB re $1 \mu\text{Pa}^2 \cdot \text{s}$ (Southall et al. 2007).

is necessary to determine the total energy that a mammal would receive as an airgun array approaches, passes at various CPA distances, and moves away (e.g., Erbe and King 2009). At the present state of knowledge, it is also necessary to assume that the effect is directly related to total received energy even though that energy is received in multiple pulses separated by gaps. The lack of data on the exposure levels necessary to cause TTS in toothed whales when the signal is a series of pulsed sounds, separated by silent periods, remains a data gap, as is the lack of published data on TTS in odontocetes other than the beluga, bottlenose dolphin, and harbor porpoise.

Baleen Whales.—There are no data, direct or indirect, on levels or properties of sound that are required to induce TTS in any baleen whale. The frequencies to which mysticetes are most sensitive are assumed to be lower than those to which odontocetes are most sensitive, and natural background noise levels at those low frequencies tend to be higher. As a result, auditory thresholds of baleen whales within their frequency band of best hearing are believed to be higher (less sensitive) than are those of odontocetes at their best frequencies (Clark and Ellison 2004). From this, it is suspected that received levels causing TTS onset may also be higher in mysticetes (Southall et al. 2007). However, based on preliminary simulation modeling that attempted to allow for various uncertainties in assumptions and variability around population means, Gedamke et al. (2008) suggested that some baleen whales whose closest point of approach to a seismic vessel is 1 km or more could experience TTS or even PTS.

In practice during seismic surveys, few if any cases of TTS are expected given the strong likelihood that baleen whales would avoid the approaching airguns (or vessel) before being exposed to levels high enough for there to be any possibility of TTS (see above for evidence concerning avoidance responses by baleen whales). This assumes that the ramp-up (soft-start) procedure is used when commencing airgun operations, to give whales near the vessel the opportunity to move away before they are exposed to sound levels that might be strong enough to elicit TTS. As discussed earlier, single-airgun experiments with bowhead, gray, and humpback whales show that those species do tend to move away when a single airgun starts firing nearby, which simulates the onset of a ramp up.

Pinnipeds.—In pinnipeds, TTS thresholds associated with exposure to brief pulses (single or multiple) of underwater sound have not been measured. Two California sea lions did not incur TTS when exposed to single brief pulses with received levels of ~178 and 183 dB re 1 $\mu\text{Pa}_{\text{rms}}$ and total energy fluxes of 161 and 163 dB re 1 $\mu\text{Pa}^2 \cdot \text{s}$ (Finneran et al. 2003). However, initial evidence from more prolonged (non-pulse) exposures suggested that some pinnipeds (harbor seals in particular) incur TTS at somewhat lower received levels than do small odontocetes exposed for similar durations (Kastak et al. 1999, 2005; Ketten et al. 2001). Kastak et al. (2005) reported that the amount of threshold shift increased with increasing SEL in a California sea lion and harbor seal. They noted that, for non-impulse sound, doubling the exposure duration from 25 to 50 min (i.e., a +3 dB change in SEL) had a greater effect on TTS than an increase of 15 dB (95 vs. 80 dB) in exposure level. Mean threshold shifts ranged from 2.9–12.2 dB, with full recovery within 24 hr (Kastak et al. 2005). Kastak et al. (2005) suggested that, for non-impulse sound, SELs resulting in TTS onset in three species of pinnipeds may range from 183 to 206 dB re 1 $\mu\text{Pa}^2 \cdot \text{s}$, depending on the absolute hearing sensitivity.

As noted above for odontocetes, it is expected that—for impulse as opposed to non-impulse sound—the onset of TTS would occur at a lower cumulative SEL given the assumed greater auditory effect of broadband impulses with rapid rise times. The threshold for onset of mild TTS upon exposure of a harbor seal to impulse sounds has been estimated indirectly as being an SEL of ~171 dB re 1 $\mu\text{Pa}^2 \cdot \text{s}$ (Southall et al. 2007). That would be approximately equivalent to a single pulse with received level ~181–186 dB re 1 $\mu\text{Pa}_{\text{rms}}$, or a series of pulses for which the highest rms values are a few dB lower.

At least for non-impulse sounds, TTS onset occurs at appreciably higher received levels in California sea lions and northern elephant seals than in harbor seals (Kastak et al. 2005). Thus, the former two species would presumably need to be closer to an airgun array than would a harbor seal before TTS is a possibility. Insofar as we are aware, there are no data to indicate whether the TTS thresholds of other pinniped species are more similar to those of the harbor seal or to those of the two less-sensitive species.

Sirenians, Sea Otter and Polar Bear.—There are no available data on TTS in sea otters and polar bears. However, TTS is unlikely to occur in sea otters or polar bears if they are on the water surface, given the pressure release and Lloyd's mirror effects at the water's surface. Furthermore, sea otters tend to inhabit shallow coastal habitats where large seismic survey vessels towing large spreads of streamers may be unable to operate. TTS is also considered unlikely to occur in sirenians as a result of exposure to sounds from a seismic survey. They, like sea otters, tend to inhabit shallow coastal habitats and rarely range far from shore, whereas seismic survey vessels towing large arrays of airguns and (usually) even larger arrays of streamers normally must remain farther offshore because of equipment clearance and maneuverability limitations. Exposures of sea otters and sirenians to seismic surveys are more likely to involve smaller seismic sources that can be used in shallow and confined waters. The impacts of these are inherently less than would occur from a larger source of the types often used farther offshore.

Likelihood of Incurring TTS.—Most cetaceans show some degree of avoidance of seismic vessels operating an airgun array (see above). It is unlikely that these cetaceans would be exposed to airgun pulses at a sufficiently high level for a sufficiently long period to cause more than mild TTS, given the relative movement of the vessel and the marine mammal. TTS would be more likely in any odontocetes that bow- or wake-ride or otherwise linger near the airguns. However, while bow- or wake-riding, odontocetes would be at the surface and thus not exposed to strong sound pulses given the pressure-release and Lloyd Mirror effects at the surface. But if bow- or wake-riding animals were to dive intermittently near airguns, they would be exposed to strong sound pulses, possibly repeatedly.

If some cetaceans did incur mild or moderate TTS through exposure to airgun sounds in this manner, this would very likely be a temporary and reversible phenomenon. However, even a temporary reduction in hearing sensitivity could be deleterious in the event that, during that period of reduced sensitivity, a marine mammal needed its full hearing sensitivity to detect approaching predators, or for some other reason.

Some pinnipeds show avoidance reactions to airguns, but their avoidance reactions are generally not as strong or consistent as those of cetaceans. Pinnipeds occasionally seem to be attracted to operating seismic vessels. There are no specific data on TTS thresholds of pinnipeds exposed to single or multiple low-frequency pulses. However, given the indirect indications of a lower TTS threshold for the harbor seal than for odontocetes exposed to impulse sound (see above), it is possible that some pinnipeds close to a large airgun array could incur TTS.

NMFS (1995, 2000) concluded that cetaceans should not be exposed to pulsed underwater noise at received levels >180 dB re $1 \mu\text{Pa}_{\text{rms}}$. The corresponding limit for pinnipeds has been set by NMFS at 190 dB, although the HESS Team (HESS 1999) recommended a 180-dB limit for pinnipeds in California. The 180 and 190 dB re $1 \mu\text{Pa}_{\text{rms}}$ levels have not been considered to be the levels above which TTS might occur. Rather, they were the received levels above which, in the view of a panel of bioacoustics specialists convened by NMFS before TTS measurements for marine mammals started to become available, one could not be certain that there would be no injurious effects, auditory or otherwise, to marine mammals. As summarized above, data that are now available imply that TTS is unlikely to occur in various odontocetes (and probably mysticetes as well) unless they are exposed to a sequence of several airgun pulses stronger than 190 dB re $1 \mu\text{Pa}_{\text{rms}}$. On the other hand, for the harbor seal, harbor porpoise, and perhaps

some other species, TTS may occur upon exposure to one or more airgun pulses whose received level equals the NMFS “do not exceed” value of 190 dB re 1 $\mu\text{Pa}_{\text{rms}}$. That criterion corresponds to a single-pulse SEL of 175–180 dB re 1 $\mu\text{Pa}^2 \cdot \text{s}$ in typical conditions, whereas TTS is suspected to be possible in harbor seals and harbor porpoises with a cumulative SEL of ~ 171 and ~ 164 dB re 1 $\mu\text{Pa}^2 \cdot \text{s}$, respectively.

It has been shown that most large whales and many smaller odontocetes (especially the harbor porpoise) show at least localized avoidance of ships and/or seismic operations (see above). Even when avoidance is limited to the area within a few hundred meters of an airgun array, that should usually be sufficient to avoid TTS based on what is currently known about thresholds for TTS onset in cetaceans. In addition, ramping up airgun arrays, which is standard operational protocol for many seismic operators, should allow cetaceans near the airguns at the time of startup (if the sounds are aversive) to move away from the seismic source and to avoid being exposed to the full acoustic output of the airgun array (see above). Thus, most baleen whales likely will not be exposed to high levels of airgun sounds provided the ramp-up procedure is applied. Likewise, many odontocetes close to the trackline are likely to move away before the sounds from an approaching seismic vessel become sufficiently strong for there to be any potential for TTS or other hearing impairment. Therefore, there is little potential for baleen whales or odontocetes that show avoidance of ships or airguns to be close enough to an airgun array to experience TTS. In the event that a few individual cetaceans did incur TTS through exposure to strong airgun sounds, this is a temporary and reversible phenomenon unless the exposure exceeds the TTS-onset threshold by a sufficient amount for PTS to be incurred (see below). If TTS but not PTS were incurred, it would most likely be mild, in which case recovery is expected to be quick (probably within minutes).

6.2 Permanent Threshold Shift (PTS)

When PTS occurs, there is physical damage to the sound receptors in the ear. In some cases, there can be total or partial deafness, whereas in other cases, the animal has an impaired ability to hear sounds in specific frequency ranges (Kryter 1985). Physical damage to a mammal’s hearing apparatus can occur if it is exposed to sound impulses that have very high peak pressures, especially if they have very short rise times. (Rise time is the interval required for sound pressure to increase from the baseline pressure to peak pressure.)

There is no specific evidence that exposure to pulses of airgun sound can cause PTS in any marine mammal, even with large arrays of airguns. However, given the likelihood that some mammals close to an airgun array might incur at least mild TTS (see above), there has been further speculation about the possibility that some individuals occurring very close to airguns might incur PTS (e.g., Richardson et al. 1995, p. 372ff; Gedamke et al. 2008). Single or occasional occurrences of mild TTS are not indicative of permanent auditory damage, but repeated or (in some cases) single exposures to a level well above that causing TTS onset might elicit PTS.

Relationships between TTS and PTS thresholds have not been studied in marine mammals, but are assumed to be similar to those in humans and other terrestrial mammals (Southall et al. 2007). Based on data from terrestrial mammals, a precautionary assumption is that the PTS threshold for impulse sounds (such as airgun pulses as received close to the source) is at least 6 dB higher than the TTS threshold on a peak-pressure basis, and probably >6 dB higher (Southall et al. 2007). The low-to-moderate levels of TTS that have been induced in captive odontocetes and pinnipeds during controlled studies of TTS have been confirmed to be temporary, with no measurable residual PTS (Kastak et al. 1999; Schlundt et al. 2000; Finneran et al. 2002, 2005; Nachtigall et al. 2003, 2004). However, very prolonged exposure to sound strong enough to elicit TTS, or shorter-term exposure to sound levels well above the TTS threshold, can cause PTS, at least in terrestrial mammals (Kryter 1985). In terrestrial mammals, the received sound level from a single non-impulsive sound exposure must be far above the TTS threshold for

any risk of permanent hearing damage (Kryter 1994; Richardson et al. 1995; Southall et al. 2007). However, there is special concern about strong sounds whose pulses have very rapid rise times. In terrestrial mammals, there are situations when pulses with rapid rise times (e.g., from explosions) can result in PTS even though their peak levels are only a few dB higher than the level causing slight TTS. The rise time of airgun pulses is fast, but not as fast as that of an explosion.

Some factors that contribute to onset of PTS, at least in terrestrial mammals, are as follows:

- exposure to single very intense sound,
- fast rise time from baseline to peak pressure,
- repetitive exposure to intense sounds that individually cause TTS but not PTS, and
- recurrent ear infections or (in captive animals) exposure to certain drugs.

Cavanagh (2000) reviewed the thresholds used to define TTS and PTS. Based on this review and SACLANT (1998), it is reasonable to assume that PTS might occur at a received sound level 20 dB or more above that inducing mild TTS. However, for PTS to occur at a received level only 20 dB above the TTS threshold, the animal probably would have to be exposed to a strong sound for an extended period, or to a strong sound with rather rapid rise time.

More recently, Southall et al. (2007) estimated that received levels would need to exceed the TTS threshold by at least 15 dB, on an SEL basis, for there to be risk of PTS. Thus, for cetaceans exposed to a sequence of sound pulses, they estimate that the PTS threshold might be an M-weighted SEL (for the sequence of received pulses) of ~ 198 dB re $1 \mu\text{Pa}^2 \cdot \text{s}$ (15 dB higher than the M_{mf} -weighted TTS threshold, in a beluga, for a watergun impulse). Additional assumptions had to be made to derive a corresponding estimate for pinnipeds, as the only available data on TTS-thresholds in pinnipeds pertained to non-impulse sound (see above). Southall et al. (2007) estimated that the PTS threshold could be a cumulative M_{pw} -weighted SEL of ~ 186 dB re $1 \mu\text{Pa}^2 \cdot \text{s}$ in the case of a harbor seal exposed to impulse sound. The PTS threshold for the California sea lion and northern elephant seal would probably be higher given the higher TTS thresholds in those species. Southall et al. (2007) also note that, regardless of the SEL, there is concern about the possibility of PTS if a cetacean or pinniped received one or more pulses with peak pressure exceeding 230 or 218 dB re $1 \mu\text{Pa}$, respectively. Thus, PTS might be expected upon exposure of cetaceans to either SEL ≥ 198 dB re $1 \mu\text{Pa}^2 \cdot \text{s}$ or peak pressure ≥ 230 dB re $1 \mu\text{Pa}$. Corresponding proposed dual criteria for pinnipeds (at least harbor seals) are ≥ 186 dB SEL and ≥ 218 dB peak pressure (Southall et al. 2007). These estimates are all first approximations, given the limited underlying data, assumptions, species differences, and evidence that the “equal energy” model is not entirely correct.

Sound impulse duration, peak amplitude, rise time, number of pulses, and inter-pulse interval are the main factors thought to determine the onset and extent of PTS. Ketten (1994) has noted that the criteria for differentiating the sound pressure levels that result in PTS (or TTS) are location and species-specific. PTS effects may also be influenced strongly by the health of the receiver’s ear.

As described above for TTS, in estimating the amount of sound energy required to elicit the onset of TTS (and PTS), it is assumed that the auditory effect of a given cumulative SEL from a series of pulses is the same as if that amount of sound energy were received as a single strong sound. There are no data from marine mammals concerning the occurrence or magnitude of a potential partial recovery effect between pulses. In deriving the estimates of PTS (and TTS) thresholds quoted here, Southall et al. (2007) made the precautionary assumption that no recovery would occur between pulses.

The TTS section (above) concludes that exposure to several strong seismic pulses that each have flat-weighted received levels near 190 dB re $1 \mu\text{Pa}_{\text{rms}}$ (175–180 dB re $1 \mu\text{Pa}^2 \cdot \text{s}$ SEL) could result in cumulative exposure of ~ 186 dB SEL (flat-weighted) or ~ 183 dB SEL (M_{mf} -weighted), and thus slight

TTS in a small odontocete. Allowing for the assumed 15 dB offset between PTS and TTS thresholds, expressed on an SEL basis, exposure to several strong seismic pulses that each have flat-weighted received levels near 205 dB_{rms} (190–195 dB SEL) could result in cumulative exposure of ~198 dB SEL (M_{mf} -weighted), and thus slight PTS in a small odontocete. However, the levels of successive pulses that will be received by a marine mammal that is below the surface as a seismic vessel approaches, passes and moves away will tend to increase gradually and then decrease gradually, with periodic decreases superimposed on this pattern when the animal comes to the surface to breathe. To estimate how close an odontocete's CPA distance would have to be for the cumulative SEL to exceed 198 dB SEL (M_{mf} -weighted), one would (as a minimum) need to allow for the sequence of distances at which airgun shots would occur, and for the dependence of received SEL on distance in the region of the seismic operation (e.g., Erbe and King 2009).

It is unlikely that an odontocete would remain close enough to a large airgun array for sufficiently long to incur PTS. There is some concern about bowriding odontocetes, but for animals at or near the surface, auditory effects are reduced by Lloyd's mirror and surface release effects. The presence of the vessel between the airgun array and bow-riding odontocetes could also, in some but probably not all cases, reduce the levels received by bow-riding animals (e.g., Gabriele and Kipple 2009). The TTS (and thus PTS) thresholds of baleen whales are unknown but, as an interim measure, assumed to be no lower than those of odontocetes. Also, baleen whales generally avoid the immediate area around operating seismic vessels, so it is unlikely that a baleen whale could incur PTS from exposure to airgun pulses. The TTS (and thus PTS) thresholds of some pinnipeds (e.g., harbor seal) as well as the harbor porpoise may be lower (Kastak et al. 2005; Southall et al. 2007; Lucke et al. 2009). If so, TTS and potentially PTS may extend to a somewhat greater distance for those animals. Again, Lloyd's mirror and surface release effects will ameliorate the effects for animals at or near the surface.

Although it is unlikely that airgun operations during most seismic surveys would cause PTS in many marine mammals, caution is warranted given

- the limited knowledge about noise-induced hearing damage in marine mammals, particularly baleen whales, pinnipeds, and sea otters;
- the seemingly greater susceptibility of certain species (e.g., harbor porpoise and harbor seal) to TTS and presumably also PTS; and
- the lack of knowledge about TTS and PTS thresholds in many species, including various species closely related to the harbor porpoise and harbor seal.

The avoidance reactions of many marine mammals, along with commonly-applied monitoring and mitigation measures (visual and passive acoustic monitoring, ramp ups, and power downs or shut downs when mammals are detected within or approaching the "safety radii"), would reduce the already-low probability of exposure of marine mammals to sounds strong enough to induce PTS.

6.3 Strandings and Mortality

Marine mammals close to underwater detonations of high explosives can be killed or severely injured, and the auditory organs are especially susceptible to injury (Ketten et al. 1993; Ketten 1995). However, explosives are no longer used in marine waters for commercial seismic surveys or (with rare exceptions) for seismic research; they have been replaced by airguns and other non-explosive sources. Airgun pulses are less energetic and have slower rise times, and there is no specific evidence that they can cause serious injury, death, or stranding even in the case of large airgun arrays. However, the association of mass strandings of beaked whales with naval exercises and, in one case, a seismic survey (Malakoff 2002; Cox et al. 2006), has raised the possibility that beaked whales exposed to strong "pulsed" sounds

may be especially susceptible to injury and/or behavioral reactions that can lead to stranding (e.g., Hildebrand 2005; Southall et al. 2007). Hildebrand (2005) reviewed the association of cetacean strandings with high-intensity sound events and found that deep-diving odontocetes, primarily beaked whales, were by far the predominant (95%) cetaceans associated with these events, with 2% mysticete whales (minke). However, as summarized below, there is no definitive evidence that airguns can lead to injury, strandings, or mortality even for marine mammals in close proximity to large airgun arrays.

Specific sound-related processes that lead to strandings and mortality are not well documented, but may include (1) swimming in avoidance of a sound into shallow water; (2) a change in behavior (such as a change in diving behavior that might contribute to tissue damage, gas bubble formation, hypoxia, cardiac arrhythmia, hypertensive hemorrhage or other forms of trauma; (3) a physiological change such as a vestibular response leading to a behavioral change or stress-induced hemorrhagic diathesis, leading in turn to tissue damage; and (4) tissue damage directly from sound exposure, such as through acoustically mediated bubble formation and growth or acoustic resonance of tissues. Some of these mechanisms are unlikely to apply in the case of impulse sounds. However, there are increasing indications that gas-bubble disease (analogous to “the bends”), induced in supersaturated tissue by a behavioral response to acoustic exposure, could be a pathologic mechanism for the strandings and mortality of some deep-diving cetaceans exposed to sonar. The evidence for this remains circumstantial and associated with exposure to naval mid-frequency sonar, not seismic surveys (Cox et al. 2006; Southall et al. 2007).

Seismic pulses and mid-frequency sonar signals are quite different, and some mechanisms by which sonar sounds have been hypothesized to affect beaked whales are unlikely to apply to airgun pulses. Sounds produced by airgun arrays are broadband impulses with most of the energy below 1 kHz. Typical military mid-frequency sonars emit non-impulse sounds at frequencies of 2–10 kHz, generally with a relatively narrow bandwidth at any one time (though the frequency may change over time). Thus, it is not appropriate to assume that the effects of seismic surveys on beaked whales or other species would be the same as the apparent effects of military sonar. For example, resonance effects (Gentry 2002) and acoustically-mediated bubble-growth (Crum et al. 2005) are implausible in the case of exposure to broadband airgun pulses. Nonetheless, evidence that sonar signals can, in special circumstances, lead (at least indirectly) to physical damage and mortality (e.g., Balcomb and Claridge 2001; NOAA and USN 2001; Jepson et al. 2003; Fernández et al. 2004, 2005; Hildebrand 2005; Cox et al. 2006) suggests that caution is warranted when dealing with exposure of marine mammals to any high-intensity “pulsed” sound. One of the hypothesized mechanisms by which naval sonars lead to strandings might, in theory, also apply to seismic surveys: If the strong sounds sometimes cause deep-diving species to alter their surfacing–dive cycles in a way that causes bubble formation in tissue, that hypothesized mechanism might apply to seismic surveys as well as mid-frequency naval sonars. However, there is no specific evidence of this upon exposure to airgun pulses.

There is no conclusive evidence of cetacean strandings or deaths at sea as a result of exposure to seismic surveys, but a few cases of strandings in the general area where a seismic survey was ongoing have led to speculation concerning a possible link between seismic surveys and strandings. • Suggestions that there was a link between seismic surveys and strandings of humpback whales in Brazil (Engel et al. 2004) were not well founded (IAGC 2004; IWC 2007). • In Sept. 2002, there was a stranding of two Cuvier’s beaked whales in the Gulf of California, Mexico, when the L-DEO seismic vessel R/V *Maurice Ewing* was operating a 20-airgun, 8490-in³ airgun array in the general area. The evidence linking the stranding to the seismic survey was inconclusive and not based on any physical evidence (Hogarth 2002; Yoder 2002). The ship was also operating its multibeam echosounder at the same time, but this had much less potential than the aforementioned naval sonars to affect beaked whales, given its downward-directed beams, much shorter pulse durations, and lower duty cycle. Nonetheless, the Gulf of California incident

plus the beaked whale strandings near naval exercises involving use of mid-frequency sonar suggest a need for caution in conducting seismic surveys in areas occupied by beaked whales until more is known about effects of seismic surveys on those species (Hildebrand 2005).

6.4 Non-Auditory Physiological Effects

Based on evidence from terrestrial mammals and humans, sound is a potential source of stress (Wright and Kuczaj 2007; Wright et al. 2007a,b, 2009). However, almost no information is available on sound-induced stress in marine mammals, or on its potential (alone or in combination with other stressors) to affect the long-term well-being or reproductive success of marine mammals (Fair and Becker 2000; Hildebrand 2005; Wright et al. 2007a,b). Such long-term effects, if they occur, would be mainly associated with chronic noise exposure, which is characteristic of some seismic surveys and exposure situations (McCauley et al. 2000a:62ff; Nieuwkerk et al. 2009) but not of some others.

Available data on potential stress-related impacts of anthropogenic noise on marine mammals are extremely limited, and additional research on this topic is needed. We know of only two specific studies of noise-induced stress in marine mammals. (1) Romano et al. (2004) examined the effects of single underwater impulse sounds from a seismic water gun (source level up to 228 dB re 1 $\mu\text{Pa} \cdot \text{m}_{\text{p-p}}$) and single short-duration pure tones (sound pressure level up to 201 dB re 1 μPa) on the nervous and immune systems of a beluga and a bottlenose dolphin. They found that neural-immune changes to noise exposure were minimal. Although levels of some stress-released substances (e.g., catecholamines) changed significantly with exposure to sound, levels returned to baseline after 24 hr. (2) During playbacks of recorded drilling noise to four captive beluga whales, Thomas et al. (1990) found no changes in blood levels of stress-related hormones. Long-term effects were not measured, and no short-term effects were detected. For both studies, caution is necessary when extrapolating these results to wild animals and to real-world situations given the small sample sizes, use of captive animals, and other technical limitations of the two studies.

Aside from stress, other types of physiological effects that might, in theory, be involved in beaked whale strandings upon exposure to naval sonar (Cox et al. 2006), such as resonance and gas bubble formation, have not been demonstrated and are not expected upon exposure to airgun pulses (see preceding subsection). If seismic surveys disrupt diving patterns of deep-diving species, this might perhaps result in bubble formation and a form of “the bends”, as speculated to occur in beaked whales exposed to sonar. However, there is no specific evidence that exposure to airgun pulses has this effect.

In summary, very little is known about the potential for seismic survey sounds (or other types of strong underwater sounds) to cause non-auditory physiological effects in marine mammals. Such effects, if they occur at all, would presumably be limited to short distances and to activities that extend over a prolonged period. The available data do not allow identification of a specific exposure level above which non-auditory effects can be expected (Southall et al. 2007), or any meaningful quantitative predictions of the numbers (if any) of marine mammals that might be affected in these ways.

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APPENDIX C:

REVIEW OF THE EFFECTS OF AIRGUN SOUNDS ON SEA TURTLES¹¹

The following subsections review relevant information concerning the potential effects of airgun sounds on sea turtles. This information is included here as background. Much of this information has also been included in varying formats in other reviews, assessments, and regulatory applications prepared by LGL Ltd.

1. Sea Turtle Hearing

Although there have been a limited number of studies on sea turtle hearing (see review by Southwood et al. 2008), the available data are not very comprehensive. However, these data demonstrate that sea turtles appear to be low-frequency specialists (see Table C-1).

Sea turtle auditory perception occurs through a combination of both bone and water conduction rather than air conduction (Lenhardt 1982; Lenhardt and Harkins 1983). Detailed descriptions of sea turtle ear anatomy are found in Ridgway et al. (1969), Lenhardt et al. (1985), and Bartol and Musick (2003). Sea turtles do not have external ears, but the middle ear is well adapted as a peripheral component of a bone conduction system. The thick tympanum is disadvantageous as an aerial receptor, but enhances low-frequency bone conduction hearing (Lenhardt et al. 1985; Bartol et al. 1999; Bartol and Musick 2003). A layer of subtympanic fat emerging from the middle ear is fused to the tympanum (Ketten et al. 2006; Bartol 2004, 2008). A cartilaginous disk, the extracolumella, is found under the tympanic membrane and is attached to the columella (Bartol 2004, 2008). The columella is a long rod that expands to form the stapes, and fibrous strands connect the stapes to the sacule (Bartol 2004, 2008). When the tympanum is depressed, the vibrations are conveyed via the fibrous stapedo-sacular strands to the sacule (Lenhardt et al. 1985). This arrangement of fat deposits and bone enables sea turtles to hear low-frequency sounds while underwater and makes them relatively insensitive to sound above water. Vibrations, however, can be conducted through the bones of the carapace to reach the middle ear.

A variety of audiometric methods are available to assess hearing abilities. Electrophysiological measures of hearing (e.g., auditory brainstem response or ABR) provide good information about relative sensitivity to different frequencies. However, this approach may underestimate the frequency range to which the animal is sensitive and may be imprecise at determining absolute hearing thresholds (e.g., Wolski et al. 2003). Nevertheless, when time is critical and only untrained animals are available, this method can provide useful information on sea turtle hearing (e.g., Wolski et al. 2003).

Ridgway et al. (1969) obtained the first direct measurements of sea turtle hearing sensitivity (Table C-1). They used an electrophysiological technique (cochlear potentials) to determine the response of green sea turtles (*Chelonia mydas*) to aerial- and vibrational-stimuli consisting of tones with frequencies 30 to 700 Hz. They found that green turtles exhibit maximum hearing sensitivity between 300 and 500 Hz Hz, and speculated that the turtles had a useful hearing range of 60–1000 Hz. (However, there was some response to strong vibrational signals at frequencies down to the lowest one tested — 30 Hz.)

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TABLE C-1. Hearing capabilities of sea turtles as measured using behavioral and electro-physiological techniques. ABR: auditory brainstem response; NA: no empirical data available.

Sea Turtle Species	Hearing		Technique	Source
	Range (Hz)	Highest Sensitivity (Hz)		
Green	60-1000	300-500	Cochlear Potentials ^a	Ridgway et al. 1969
	100-800	600-700 (juveniles) 200-400 (subadults)	ABR ^w	Bartol & Ketten 2006; Ketten & Bartol 2006
	50-1600	50-400	ABR ^{a,w}	Dow et al. 2008
Hawksbill	NA	NA	NA	NA
Loggerhead	250-1000	250	ABR ^a	Bartol et al. 1999
Olive ridley	NA	NA	NA	NA
Kemp's ridley	100-500	100-200	ABR ^w	Bartol & Ketten 2006; Ketten & Bartol 2006
Leatherback	NA	NA	NA	NA
Flatback	NA	NA	NA	NA

^a measured in air; ^w measured underwater

Bartol et al. (1999) tested the in-air hearing of juvenile loggerhead turtles *Caretta caretta* (Table C-1). The authors used ABR to determine the response of the sea turtle ear to two types of vibrational stimuli: (1) brief, low-frequency broadband clicks, and (2) brief tone bursts at four frequencies from 250 to 1000 Hz. They demonstrated that loggerhead sea turtles hear well between 250 and 1000 Hz; within that frequency range the turtles were most sensitive at 250 Hz. The authors did not measure hearing sensitivity below 250 Hz or above 1000 Hz. There was an extreme decrease in response to stimuli above 1000 Hz, and the vibrational intensities required to elicit a response may have damaged the turtle's ear. The signals used in this study were very brief — 0.6 ms for the clicks and 0.8–5.5 ms for the tone bursts. In other animals, auditory thresholds decrease with increasing signal duration up to ~100–200 ms. Thus, sea turtles probably could hear weaker signals than demonstrated in the study if the signal duration were longer.

Lenhardt (2002) exposed loggerhead turtles while they were near the bottom of holding tanks at a depth of 1 m to tones from 35 to 1000 Hz. The turtles exhibited startle responses (neck contractions) to these tones. The lowest thresholds were in the 400–500 Hz range (106 dB SPL re 1 μ Pa), and thresholds in the 100–200 Hz range were ~124 dB (Lenhardt 2002). Thresholds at 735 and 100 Hz were 117 and 156 dB, respectively (Lenhardt 2002). Diving behaviour occurred at 30 Hz and 164 dB.

More recently, ABR techniques have been used to determine the underwater hearing capabilities of six subadult green turtles, two juvenile green turtles, and two juvenile Kemp's ridley (*Lepidochelys kempii*) turtles (Ketten and Bartol 2006; Bartol and Ketten 2006; Table C-1). The turtles were physically restrained in a small box tank with their ears below the water surface and the top of the head exposed above the surface. Pure-tone acoustic stimuli were presented to the animals, though the exact frequencies of these tones were not indicated. The six subadult green turtles detected sound at frequencies 100–500 Hz, with the most sensitive hearing at 200–400 Hz. In contrast, the two juvenile green turtles exhibited a

slightly expanded overall hearing range of 100–800 Hz, with their most sensitive hearing occurring at 600–700 Hz. The most restricted range of sensitive hearing (100–200 Hz) was found in the two juvenile Kemp’s ridleys turtles, whose overall frequency range was 100–500 Hz.

Preliminary data from a similar study of a trained, captive green turtle indicate that the animal heard and responded behaviorally to underwater tones ranging in frequency from 100 to 500 Hz. At 200 Hz, the threshold was between 107 and 119 dB, and at 400 Hz the threshold was between 121 and 131 dB [reference units not provided] (Streeter 2003; ONR N.D.).

In summary, the limited available data indicate that the frequency range of best hearing sensitivity of sea turtles extends from ~200 to 700 Hz. Sensitivity deteriorates as one moves away from this range to either lower or higher frequencies. However, there is some sensitivity to frequencies as low as 60 Hz, and probably as low as 30 Hz (Ridgway et al. 1969). Thus, there is substantial overlap in the frequencies that sea turtles detect vs. the dominant frequencies in airgun pulses. Given that, plus the high energy levels of airgun pulses, sea turtles undoubtedly hear airgun sounds. We are not aware of measurements of the absolute hearing thresholds of any sea turtle to waterborne sounds similar to airgun pulses. Given the high source levels of airgun pulses and the substantial received levels even at distances many km away from the source, sea turtles probably can also hear distant seismic vessels. However, in the absence of relevant absolute threshold data, we cannot estimate how far away an airgun array might be audible to a sea turtle.

2. Effects of Airgun Pulses on Behavior and Movement

The effects of exposure to airgun pulses on the behavior and distribution of various marine animals have been studied over the past three decades. Most such studies have concerned marine mammals (e.g., see reviews by Richardson et al. 1995; Gordon et al. 2004; Nowacek et al. 2007; Southall et al. 2007), but also fish (e.g., reviewed by Thomson et al. 2001; Herata 2007; Payne et al. 2008). There have been far fewer studies on the effects of airgun noise (or indeed any type of noise) on sea turtles, and little is known about the sound levels that will or will not elicit various types of behavioral reactions. There have been four directed studies that focused on short-term behavioral responses of sea turtles in enclosures to single airguns. However, comparisons of results among studies are difficult because experimental designs and reporting procedures have varied greatly, and few studies provided specific information about the levels of the airgun pulses received by the turtles. Although monitoring studies are now providing some information on responses (or lack of responses) of free-ranging sea turtles to seismic surveys, we are not aware of any directed studies on responses of free-ranging sea turtles to seismic sounds or on the long-term effects of seismic or other sounds on sea turtles.

Directed Studies.—The most recent of the studies of caged sea turtles exposed to airgun pulses was a study by McCauley et al. (2000a,b) off Western Australia. The authors exposed caged green and loggerhead sea turtles (one of each) to pulses from an approaching and then receding 20 in³ airgun operating at 1500 psi and a 5-m airgun depth. The single airgun fired every 10 s. There were two trials separated by two days; the first trial involved ~2 h of airgun exposure and the second ~1 h. The results from the two trials showed that, above a received level of 166 dB re 1 μ Pa (rms)¹², the turtles noticeably

¹² rms = root mean square. This measure represents the average received sound pressure over the duration of the pulse, with duration being defined in a specific way (from the time when 5% of the pulse energy has been received to the time when 95% of the energy has been received). The rms received level of a seismic pulse is typically about 10 dB less than its peak level, and about 16 dB less than its peak-to-peak level (Greene et al. 1997, 2000; McCauley et al. 1998, 2000a,b).

increased their swim speed relative to periods when no airguns were operating. The behavior of the sea turtles became more erratic when received levels exceeded 175 dB re 1 μ Pa rms. The authors suggested that the erratic behavior exhibited by the caged sea turtles would likely, in unrestrained turtles, be expressed as an avoidance response (McCauley et al. 2000a,b).

O'Hara and Wilcox (1990) tested the reactions to airguns by loggerhead sea turtles held in a 300×45 m area of a canal in Florida with a bottom depth of 10 m. Nine turtles were tested at different times. The sound source consisted of one 10 in³ airgun plus two 0.8 in³ "poppers" operating at 2000 psi¹³ and an airgun-depth of 2 m for prolonged periods of 20–36 h. The turtles maintained a standoff range of about 30 m when exposed to airgun pulses every 15 or 7.5 s. Some turtles may have remained on the bottom of the enclosure when exposed to airgun pulses. O'Hara and Wilcox (1990) did not measure the received airgun sound levels. McCauley et al. (2000a,b) estimated that "the level at which O'Hara saw avoidance was around 175–176 dB re 1 μ Pa rms." The levels received by the turtles in the Florida study probably were actually a few dB less than 175–176 dB because the calculations by McCauley et al. apparently did not allow for the shallow 2-m airgun depth in the Florida study. The effective source level of airguns is less when they are at a depth of 2 m vs. 5 m (Greene et al. 2000).

Moein et al. (1994) investigated the avoidance behavior and physiological responses of loggerhead turtles exposed to an operating airgun, as well as the effects on their hearing. The turtles were held in a netted enclosure ~18 m by 61 m by 3.6 m deep, with an airgun of unspecified size at each end. Only one airgun was operated at any one time; the firing rate was one shot every 5–6 s. Ten turtles were tested individually, and seven of these were retested several days later. The airgun was initially discharged when the turtles were near the center of the enclosure and the subsequent movements of the turtles were documented. The turtles exhibited avoidance during the first presentation of airgun sounds at a mean range of 24 m, but the avoidance response waned quickly. Additional trials conducted on the same turtles several days later did not show statistically significant avoidance reactions. However, there was an indication of slight initial avoidance followed by rapid waning of the avoidance response which the authors described as "habituation". Their auditory study indicated that exposure to the airgun pulses may have resulted in temporary threshold shift (TTS; see later section). Reduced hearing sensitivity may also have contributed to the waning response upon continued exposure. Based on physiological measurements, there was some evidence of increased stress in the sea turtles, but this stress could also have resulted from handling of the turtles.

Inconsistencies in reporting procedures and experimental design prevent direct comparison of this study with either McCauley et al. (2000a,b) or O'Hara and Wilcox (1990). Moein et al. (1994) stated, without further details, that "three different decibel levels (175, 177, 179) were utilized" during each test. These figures probably are received levels in dB re 1 μ Pa, and probably relate to the initial exposure distance (mean 24 m), but these details were not specified. Also, it was not specified whether these values were measured or estimated, or whether they are expressed in peak-peak, peak, rms, SEL, or some other units. Given the shallow water in the enclosure (3.6 m), any estimates based on simple assumptions about propagation would be suspect.

¹³ There was no significant reaction by five turtles during an initial series of tests with the airguns operating at the unusually low pressure of 1000 psi. The source and received levels of airgun sounds would have been substantially lower when the air pressure was only 1000 psi than when it was at the more typical operating pressure of 2000 psi.

Lenhardt (2002) exposed captive loggerhead sea turtles while underwater to seismic airgun (Bolt 600) sounds in a large net enclosure. At received levels of 151–161 dB, turtles were found to increase swimming speeds. Similar to the McCauley et al. studies (2000a,b--see above), near a received level of ~175 dB, an avoidance reaction was common in initial trials, but habituation then appeared to occur. Based on ABRs measured pre- and post-airgun exposures, a TTS of over 15 dB was found in one animal, with recovery two weeks later. Lenhardt (2002) suggested that exposure of sea turtles to airguns at water depths >10 m may result in exposure to more energy in the low frequencies with unknown biological effects.

Despite the problems in comparing these studies, they are consistent in showing that, at some received level, sea turtles show avoidance of an operating airgun. McCauley et al. (2000a,b) found evidence of behavioral responses when the received level from a single small airgun was 166 dB re 1 μ Pa rms and avoidance responses at 175 dB re 1 μ Pa rms. Based on these data, McCauley et al. estimated that, for a typical airgun array (2678 in³, 12 elements) operating in 100–120 m water depth, sea turtles may exhibit behavioral changes at ~2 km and avoidance around 1 km. These estimates are subject to great variation, depending on the seismic source and local propagation conditions.

A further potential complication is that sea turtles on or near the bottom may receive sediment-borne “headwave” signals from the airguns (McCauley et al. 2000a,b). As previously discussed, it is believed that sea turtles use bone conduction to hear. It is unknown how sea turtles might respond to the headwave component of an airgun impulse or to bottom vibrations.

Related studies involving stimuli other than airguns may also be relevant. **(1)** Two loggerhead turtles resting on the bottom of shallow tanks responded repeatedly to low-frequency (20–80 Hz) tones by becoming active and swimming to the surface. They remained at the surface or only slightly submerged for the remainder of the 1-min trial (Lenhardt 1994). Although no detailed data on sound levels at the bottom vs. surface were reported, the surfacing response probably reduced the levels of underwater sound to which the turtles were exposed. **(2)** In a separate study, a loggerhead and a Kemp’s ridley sea turtle responded similarly when vibratory stimuli at 250 or 500 Hz were applied to the head for 1 s (Lenhardt et al. 1983). There appeared to be rapid habituation to these vibratory stimuli. **(3)** Turtles in tanks showed agitated behaviour when exposed to simulated boat noise and recordings from the U.S. Navy’s Low Frequency Active (LFA) sonar (Samuel et al. 2005, 2006). The tones and vibratory stimuli used in these two studies were quite different from airgun pulses. However, it is possible that resting sea turtles may exhibit a similar “alarm” response, possibly including surfacing or alternatively diving, when exposed to any audible noise, regardless of whether it is a pulsed sound or tone.

Monitoring Results.—Data on sea turtle behavior near airgun operations have also been collected during marine mammal and sea turtle monitoring and mitigation programs associated with various seismic operations around the world. Although the primary objectives concerned marine mammals, sea turtle sightings have also been documented in some of monitoring projects. Results suggest that some sea turtles exhibit behavioral changes and/or avoidance within an area of unknown size near a seismic vessel. However, avoidance of approaching seismic vessels is sufficiently limited and small-scale such that sea turtles are often seen from operating seismic vessels. Also, average distances from the airguns to these sea turtles are usually not greatly increased when the airguns are operating as compared with times when airguns are silent.

For example, during six large-source (10–20 airguns; 3050–8760 in³) and small-source (up to six airguns or three GI guns; 75–1350 in³) surveys conducted by L-DEO during 2003–2005, the mean closest point of approach (CPA) for turtles was closer during non-seismic than seismic periods: 139 m vs. 228 m and 120 m vs. 285 m, respectively (Holst et al. 2006). During a large-source L-DEO seismic survey off

the Pacific coast of Central America in 2008, the turtle sighting rate during non-seismic periods was seven times greater than that during seismic periods (Holst and Smultea 2008). In addition, distances of turtles seen from the seismic vessel were significantly farther from the airgun array when it was operating (mean 159 m, $n = 77$) than when the airguns were off (mean 118 m, $n = 69$; Mann-Whitney U test, $P < 0.001$) (Holst and Smultea 2008). During another L-DEO survey in the Eastern Tropical Pacific in 2008, the turtle sighting rate during non-seismic periods was 1.5 times greater than that during seismic periods; however, turtles tended to be seen closer to the airgun array when it was operating, but this difference was not statistically significant (Hauser et al. 2008).

Weir (2007) reported on the behavior of sea turtles near seismic exploration operations off Angola, West Africa. A total of 240 sea turtles were seen during 676 h of vessel-based monitoring, mainly for associated marine mammals mitigation and monitoring observations. Airgun arrays with total volumes of 5085 and 3147 in^3 were used at different times during the seismic program. Sea turtles tended to be seen slightly closer to the seismic source, and at sighting rates twice as high, during non-seismic vs. seismic periods (Weir 2007). However, there was no significant difference in the median distance of turtle sightings from the array during non-seismic vs. seismic periods, with means of 743 m ($n = 112$) and 779 m ($n = 57$).

Off northeastern Brazil, 46 sea turtles were seen during 2028 h of vessel-based monitoring of seismic exploration using 4–8 GI airguns (Parente et al. 2006). There were no apparent differences in turtle sighting rates during seismic and non-seismic periods, but detailed behavioral data during seismic operations were lacking (Parente et al. 2006).

Behavioral responses of marine mammals and fish to seismic surveys sometimes vary depending on species, time of year, activity of the animal, and other unknown factors. The same species may show different responses at different times of year or even on different days (e.g., Richardson et al. 1995; Thomson et al. 2001). Sea turtles of different ages vary in size, behavior, feeding habits, and preferred water depths. Nothing specific is known about the ways in which these factors may be related to airgun sound effects in sea turtles. However, it is reasonable to expect lesser effects in young turtles concentrated near the surface (where levels of airgun sounds are attenuated) as compared with older turtles that spend more time at depth where airgun sounds are generally stronger.

3. Possible Effects of Airgun Sounds on Distribution

In captive enclosures, sea turtles generally respond to seismic noise by startling, increasing swimming speed, and/or swimming away from the noise source. Animals resting on the bottom often become active and move toward the surface where received sound levels normally will be reduced, although some turtles dive upon exposure. Unfortunately, quantitative data for free-ranging sea turtles exposed to seismic pulses are very limited, and potential long-term behavioral effects of seismic exposure have not been investigated. The paucity of data precludes clear predictions of sea turtle responses to seismic noise. Available evidence suggests that localized behavioral and distributional effects on sea turtles are likely during seismic operations, including responses to the seismic vessel, airguns, and other gear (e.g., McCauley 1994; Pendoley 1997; Weir 2007). Pendoley (1997) summarized potential effects of seismic operations on the behavior and distribution of sea turtles and identified biological periods and habitats considered most sensitive to potential disturbance. The possible responses of free-ranging sea turtles to seismic pulses could include

- avoiding the entire seismic survey area to the extent that turtles move to less preferred habitat;
- avoiding only the immediate area around the active seismic vessel (i.e., local avoidance of the source vessel but remain in the general area); and
- exhibiting no appreciable avoidance, although short-term behavioral reactions are likely.

Complete avoidance of an area, if it occurred, could exclude sea turtles from their preferred foraging area and could displace them to areas where foraging is sub-optimal. Avoidance of a preferred foraging area may prevent sea turtles from obtaining preferred prey species and hence could impact their nutritional status. The potential alteration of a migration route might also have negative impacts. However, it is not known whether avoidance by sea turtles would ever be on a sufficient geographic scale, or be sufficiently prolonged, to prevent turtles from reaching an important destination.

Available evidence suggests that the zone of avoidance around seismic sources is not likely to exceed a few kilometers (McCauley et al. 2000a,b). Avoidance reactions on that scale could prevent sea turtles from using an important coastal area or bay if there was a prolonged seismic operation in the area, particularly in shallow waters (e.g., Pendoley 1997). Sea turtles might be excluded from the area for the duration of the seismic operation, or they might remain but exhibit abnormal behavioral patterns (e.g., lingering longer than normal at the surface where received sound levels are lower). Whether those that were displaced would return quickly after the seismic operation ended is unknown.

It is unclear whether exclusion from a particular nesting beach by seismic operations, if it occurred, would prevent or decrease reproductive success. It is believed that females migrate to the region of their birth and select a nesting beach (Miller 1997). However, the degree of site fidelity varies between species and also intra-seasonally by individuals. If a sea turtle is excluded from a particular beach, it may select a more distant, undisturbed nesting site in the general area (Miller 1997). For instance, Bjorndal et al. (1983) reported a maximal intra-seasonal distance between nesting sites of 290 km, indicating that turtles use multiple nesting sites spaced up to a few hundred kilometers apart. Also, it is uncertain whether a turtle that failed to go ashore because of seismic survey activity would abandon the area for that full breeding cycle, or would simply delay going ashore until the seismic vessel moved to a different area.

Shallow coastal waters can contain relatively high densities of sea turtles during nesting, hatching, and foraging periods. Thus, seismic operations in these areas could correspondingly impact a relatively higher number of individual turtles during sensitive biological periods. Samuel et al. (2005) noted that anthropogenic noise in vital sea turtle habitats, such as a major coastal foraging area off Long Island, NY, could affect sea turtle behaviour and ecology. There are no specific data that demonstrate the consequences to sea turtles if seismic operations with large or small arrays of airguns occur in important areas at biologically important times of year. However, a number of mitigation measures can, on a case-by-case basis, be considered for application in areas important to sea turtles (e.g., Pendoley 1997).

4. Possible Impacts of Airgun Sounds on Hearing

Noise-induced hearing damage can be either temporary or permanent. In general, the received sound must be strong for either to occur, and must be especially strong and/or prolonged for permanent impairment to occur.

Few studies have directly investigated hearing or noise-induced hearing loss in sea turtles. Moein et al. (1994) used an evoked potential method to test the hearing of loggerhead sea turtles exposed to a few hundred pulses from a single airgun. Turtle hearing was tested before, within 24 h after, and two weeks after exposure to pulses of airgun sound. Levels of airgun sound to which the turtles were exposed were not specifically reported. The authors concluded that five turtles exhibited some change in their hearing when tested within 24 h after exposure relative to pre-exposure hearing, and that hearing had reverted to normal when tested two weeks after exposure. The results are consistent with the occurrence of TTS upon exposure of the turtles to airgun pulses. Unfortunately, the report did not state the size of the airgun used, or the received sound levels at various distances. The distances of the turtles from the airgun were also variable during the tests; the turtle was about 30 m from the airgun at the start of each trial, but

it could then either approach the airgun or move away to a maximum of about 65 m during subsequent airgun pulses. Thus, the levels of airgun sounds that apparently elicited TTS are not known. Nonetheless, it is noteworthy that there was evidence of TTS from exposure to pulses from a single airgun. However, the turtles were confined and unable to move more than about 65 m away. Similarly, Lenhardt (2002) exposed loggerhead turtles in a large net enclosure to airgun pulses. A TTS of >15 dB was evident for one loggerhead turtle, with recovery occurring in two weeks. Turtles in the open sea might have moved away from an airgun operating at a fixed location, and in the more typical case of a towed airgun or airgun array, very few shots would occur at or around one location. Thus, exposure to underwater sound during net-enclosure experiments was not typical of that expected during an operational seismic survey.

Studies with terrestrial reptiles have demonstrated that exposure to airborne impulse noise can cause hearing loss. For example, desert tortoises (*Gopherus agassizii*) exhibited TTS after exposure to repeated high-intensity sonic booms (Bowles et al. 1999). Recovery from these temporary hearing losses was usually rapid (<1 h), which suggested that tortoises can tolerate these exposures without permanent injury (Bowles et al. 1999).

The results from captive, restrained sea turtles exposed repeatedly to seismic sounds in enclosed areas indicate that TTS is possible under these artificial conditions. However, there are no data to indicate whether there are any plausible field situations in which exposure to repeated airgun pulses at close range could cause permanent threshold shift (PTS) or hearing impairment in sea turtles. Hearing impairment (whether temporary or permanent) from seismic sounds is considered unlikely to occur at sea; turtles are unlikely to be exposed to more than a few strong pulses close to the sound source, as individuals are mobile and the vessel travels relatively quickly compared to the swimming speed of a sea turtle. However, in the absence of specific information on received levels of impulse sound necessary to elicit TTS and PTS in sea turtles, it is uncertain whether there are circumstances where these effects could occur in the field. If sea turtles exhibit little or no behavioral avoidance, or if they acclimate to seismic noise to the extent that avoidance reactions cease, sea turtles might sustain hearing loss if they are close enough to seismic sources. Similarly, in the absence of quantitative data on behavioral responses, it is unclear whether turtles in the area of seismic operations prior to start-up move out of the area when standard ramp-up (=soft-start) procedures are in effect. It has been proposed that sea turtles require a longer ramp-up period because of their relatively slow swimming speeds (Eckert 2000). However, it is unclear at what distance (if any) from a seismic source sea turtles could sustain hearing impairment, and whether there would ever be a possibility of exposure to sufficiently high levels for a sufficiently long period to cause permanent hearing damage.

In theory, a reduction in hearing sensitivity, either temporary or permanent, may be harmful for sea turtles. However, very little is known about the role of sound perception in the sea turtle's normal activities. While it is not possible to estimate how much of a problem it would be for a turtle to have either temporary or permanent hearing impairment, there is some evidence indicating that hearing plays an important role in sea turtle survival. **(1)** It has been suggested (Eckert et al. 1998; Eckert 2000) that sea turtles may use passive reception of acoustic signals to detect the hunting sonar of killer whales (*Orcinus orca*), a known predator of leatherback sea turtles *Dermochelys coriacea* (Fertl and Fulling 2007). Further investigation is needed before this hypothesis can be accepted. Some communication calls of killer whales include components at frequencies low enough to overlap the frequency range where sea turtles hear. However, the echolocation signals of killer whales are at considerably higher frequencies and may be inaudible to sea turtles (e.g., Simon et al. 2007). **(2)** Hearing impairment, either temporary or permanent, might inhibit a turtle's ability to avoid injury from vessels. A recent study found that green sea turtles often responded behaviorally to close, oncoming small vessels and that the nature of the

response was related to vessel speed, with fewer turtles displaying a flee response as vessel speed increased (Hazel et al. 2007). However, Hazel et al. (2007) suggested that a turtles' ability to detect an approaching vessel was vision-dependent. **(3) Hearing** may play a role in navigation. For example, it has been proposed that sea turtles may identify their breeding beaches by their acoustic signature (Lenhardt et al. 1983). However, available evidence suggests that visual, wave, and magnetic cues are the main navigational cues used by sea turtles, at least in the case of hatchlings and juveniles (Lohmann et al. 1997, 2001; Lohmann and Lohmann 1998).

5. Other Physical Effects

Other potential direct physical effects to sea turtles during seismic operations include entanglement with seismic gear (e.g., cables, buoys, streamers, etc.) and ship strikes (Pendoley 1997; Ketos Ecology 2007; Weir 2007; Hazel et al. 2007). Entanglement of sea turtles with marine debris, fishing gear, and other equipment has been documented; turtles can become entangled in cables, lines, nets, or other objects suspended in the water column and can become injured or fatally wounded, drowned, or suffocated (e.g., Lutcavage et al. 1997). Seismic-survey personnel have reported that sea turtles (number unspecified) became fatally entrapped between gaps in tail-buoys associated with industrial seismic vessel gear deployed off West Africa in 2003 (Weir 2007). However, no incidents of entanglement of sea turtles have been documented during NSF-funded seismic surveys, which since 2003 have included dedicated ship-based monitoring by trained biological observers, in some cases in areas with many sea turtles (e.g., Holst et al. 2005a,b; Holst and Smultea 2008; Hauser et al. 2008).

6. Conclusions

Based on available data concerning sea turtles and other marine animals, it is likely that some sea turtles exhibit behavioral changes and/or avoidance within an area of unknown size near an operating seismic survey vessel. There is also the possibility of temporary hearing impairment or perhaps even permanent hearing damage to turtles close to the airguns. However, there are very few data on temporary hearing loss and no data on permanent hearing loss in sea turtles exposed to airgun pulses. Although some information is available about effects of exposure to sounds from a single airgun on captive sea turtles, the long term acoustic effects (if any) of a full-scale marine seismic operation on free-ranging sea turtles are unknown. Entanglement of turtles in seismic gear and vessel strikes during seismic survey operations are also possible but do not seem to be common. The greatest impact is likely to occur if seismic operations occur in or near areas where turtles concentrate, and at seasons when turtles are concentrated there. However, there are no specific data that demonstrate the consequences of such seismic operations to sea turtles. Until more data become available, it would be prudent to avoid seismic operations near important nesting beaches or in areas of known concentrated feeding during times of year when those areas are in use by many sea turtles.

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APPENDIX D: REVIEW OF THE EFFECTS OF AIRGUN SOUNDS ON FISHES¹⁴

Here we review literature about the effects of airgun sounds on fishes during seismic surveys. The potential effect of seismic sounds on fish has been studied with a variety of taxa, including marine, freshwater, and anadromous species (reviewed by Fay and Popper 2000; Ladich and Popper 2004; Hastings and Popper 2005; Popper and Hastings 2009a,b).

It is sometimes difficult to interpret studies on the effects of underwater sound on marine animals because authors often do not provide enough information, including received sound levels, source sound levels, and specific characteristics of the sound. Specific characteristics of the sound include units and references, whether the sound is continuous or impulsive, and its frequency range. Underwater sound pressure levels are typically reported as a number of decibels referenced to a reference level, usually 1 micro-Pascal (μPa). However, the sound pressure dB number can represent multiple types of measurements, including “zero to peak”, “peak to peak”, or averaged (“rms”). Sound exposure levels (SEL) may also be reported as dB. The SEL is the integration of all the acoustic energy contained within a single sound event. Unless precise measurement types are reported, it can be impossible to directly compare results from two or more independent studies.

1. Acoustic Capabilities

Sensory systems – like those that allow for hearing – provide information about an animal’s physical, biological, and social environments, in both air and water. Extensive work has been done to understand the structures, mechanisms, and functions of animal sensory systems in aquatic environments (Atema et al. 1988; Kapoor and Hara 2001; Collin and Marshall 2003). All fish species have hearing and skin-based mechanosensory systems (inner ear and lateral line systems, respectively) that provide information about their surroundings (Fay and Popper 2000). Fay (2009) and some others refer to the ambient sounds to which fishes are exposed as ‘underwater soundscapes’. Anthropogenic sounds can have important negative consequences for fish survival and reproduction if they disrupt an individual’s ability to sense its soundscape, which often tells of predation risk, prey items, or mating opportunities. Potential negative effects include masking of key environmental sounds or social signals, displacement of fish from their habitat, or interference with sensory orientation and navigation.

Fish hearing via the inner ear is typically restricted to low frequencies. As with other vertebrates, fish hearing involves a mechanism whereby the beds of hair cells (Howard et al. 1988; Hudspeth and Markin 1994) located in the inner ear are mechanically affected and cause a neural discharge (Popper and Fay 1999). At least two major pathways for sound transmittance between sound source and the inner ear have been identified for fishes. The most primitive pathway involves direct transmission to the inner ear’s otolith, a calcium carbonate mass enveloped by sensory hairs. The inertial difference between the dense otolith and the less-dense inner ear causes the otolith to stimulate the surrounding sensory hair cells. This motion differential is interpreted by the central nervous system as sound.

The second transmission pathway between sound source and the inner ear of fishes is via the swim bladder, a gas-filled structure that is much less dense than the rest of the fish’s body. The swim bladder, being more compressible and expandable than either water or fish tissue, will differentially contract and expand relative to the rest of the fish in a sound field. The pulsating swim bladder transmits this

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mechanical disturbance directly to the inner ear (discussed below). Such a secondary source of sound detection may be more or less effective at stimulating the inner ear depending on the amplitude and frequency of the pulsation, and the distance and mechanical coupling between the swim bladder and the inner ear (Popper and Fay 1993).

A recent paper by Popper and Fay (2010) discusses the designation of fishes based on sound detection capabilities. They suggest that the designations ‘hearing specialist’ and ‘hearing generalist’ no longer be used for fishes because of their vague and sometimes contradictory definitions, and that there is instead a range of hearing capabilities across species that is more like a continuum, presumably based on the relative contributions of pressure to the overall hearing capabilities of a species.

According to Popper and Fay (2010), one end of this continuum is represented by fishes that only detect particle motion because they lack pressure-sensitive gas bubbles (e.g., swim bladder). These species include elasmobranchs (e.g., sharks) and jawless fishes, and some teleosts including flatfishes. Fishes at this end of the continuum are typically capable of detecting sound frequencies below 1500 Hz.

The other end of the fish hearing continuum is represented by fishes with highly specialized otophysic connections between pressure receptive organs, such as the swim bladder, and the inner ear. These fishes include some squirrelfish, mormyrids, herrings, and otophysan fishes (freshwater fishes with Weberian apparatus, an articulated series of small bones that extend from the swim bladder to the inner ear). Rather than being limited to 1.5 kHz or less in hearing, these fishes can typically hear up to several kHz. One group of fish in the anadromous herring sub-family Alosinae (shads and menhaden) can detect sounds to well over 180 kHz (Mann et al. 1997, 1998, 2001). This may be the widest hearing range of any vertebrate that has been studied to date. While the specific reason for this very high frequency hearing is not totally clear, there is strong evidence that this capability evolved for the detection of the ultrasonic sounds produced by echolocating dolphins to enable the fish to detect, and avoid, predation (Mann et al. 1997; Plachta and Popper 2003).

All other fishes have hearing capabilities that fall somewhere between these two extremes of the continuum. Some have unconnected swim bladders located relatively far from the inner ear (e.g., salmonids, tuna) while others have unconnected swim bladders located relatively close to the inner ear (e.g., Atlantic cod, *Gadus morhua*). There has also been the suggestion that Atlantic cod can detect 38 kHz (Astrup and Møhl 1993). However, the general consensus was that this was not hearing with the ear; probably the fish were responding to exceedingly high pressure signals from the 38-kHz source through some other receptor in the skin, such as touch receptors (Astrup and Møhl 1998).

It is important to recognize that the swim bladder itself is not a sensory end organ, but rather an intermediate part of the sound pathway between sound source and the inner ear of some fishes. The inner ear of fishes is ultimately the organ that translates the particle displacement component into neural signals for the brain to interpret as sound.

A third mechanosensory pathway found in most bony fishes and elasmobranchs (i.e., cartilaginous fishes) involves the lateral line system. It too relies on sensitivity to water particle motion. The basic sensory unit of the lateral line system is the neuromast, a bundle of sensory and supporting cells whose projecting cilia, similar to those in the ears, are encased in a gelatinous cap. Neuromasts detect distorted sound waves in the immediate vicinity of fishes. Generally, fishes use the lateral line system to detect the particle displacement component of low frequency acoustic signals (up to 160 to 200 Hz) over a distance of one to two body lengths. The lateral line is used in conjunction with other sensory systems, including hearing (Sand 1981; Coombs and Montgomery 1999).

2. Potential Effects on Fishes

Review papers on the effects of anthropogenic sources of underwater sound on fishes have been published recently (Popper 2009; Popper and Hastings 2009a,b). These papers consider various sources of anthropogenic sound, including seismic airguns. For the purposes of this review, only the effects of seismic airgun sound are considered.

2.1 Marine Fishes

Evidence for airgun-induced damage to fish ears has come from studies using pink snapper *Pagrus auratus* (McCauley et al. 2000a,b, 2003). In these experiments, fish were caged and exposed to the sound of a single moving seismic airgun every 10 s over a period of 1 h and 41 min. The source SPL at 1 m was about 223 dB re 1 $\mu\text{Pa} \cdot \text{m}_{\text{p-p}}$, and the received SPLs ranged from 165 to 209 dB re 1 $\mu\text{Pa}_{\text{p-p}}$. The sound energy was highest over the 20–70 Hz frequency range. The pink snapper were exposed to more than 600 airgun discharges during the study. In some individual fish, the sensory epithelium of the inner ear sustained extensive damage as indicated by ablated hair cells. Damage was more extensive in fish examined 58 days post-exposure compared to those examined 18 h post-exposure. There was no evidence of repair or replacement of damaged sensory cells up to 58 days post-exposure. McCauley et al. (2000a,b, 2003) included the following caveats in the study reports: (1) fish were caged and unable to swim away from the seismic source, (2) only one species of fish was examined, (3) the impact on the ultimate survival of the fish is unclear, and (4) airgun exposure specifics required to cause the observed damage were not obtained (i.e., a few high SPL signals or the cumulative effect of many low to moderate SPL signals).

The fish exposed to sound from a single airgun in this study also exhibited startle responses to short range start up and high-level airgun signals (i.e., with received SPLs of 182 to 195 dB re 1 $\mu\text{Pa}_{\text{rms}}$ (McCauley et al. 2000a,b). Smaller fish were more likely to display a startle response. Responses were observed above received SPLs of 156 to 161 dB re 1 $\mu\text{Pa}_{\text{rms}}$. The occurrence of both startle response (classic C-turn response) and alarm responses (e.g., darting movements, flash school expansion, fast swimming) decreased over time. Other observations included downward distributional shift that was restricted by the 10 m x 6 m x 3 m cages, increase in swimming speed, and the formation of denser aggregations. Fish behavior appeared to return to pre-exposure state 15–30 min after cessation of seismic firing.

Pearson et al. (1992) investigated the effects of seismic airgun sound on the behavior of captive rockfishes (*Sebastes* sp.) exposed to the sound of a single stationary airgun at a variety of distances. The airgun used in the study had a source SPL at 1 m of 223 dB re 1 $\mu\text{Pa} \cdot \text{m}_{0\text{-p}}$, and measured received SPLs ranged from 137 to 206 dB re 1 $\mu\text{Pa}_{0\text{-p}}$. The authors reported that rockfishes reacted to the airgun sounds by exhibiting varying degrees of startle and alarm responses, depending on the species of rockfish and the received SPL. Startle responses were observed at a minimum received SPL of 200 dB re 1 $\mu\text{Pa}_{0\text{-p}}$, and alarm responses occurred at a minimum received SPL of 177 dB re 1 $\mu\text{Pa}_{0\text{-p}}$. Other observed behavioral changes included the tightening of schools, downward distributional shift, and random movement and orientation. Some fishes ascended in the water column and commenced to mill (i.e., “eddy”) at increased speed, while others descended to the bottom of the enclosure and remained motionless. Pre-exposure behavior was reestablished from 20 to 60 min after cessation of seismic airgun discharge. Pearson et al. (1992) concluded that received SPL thresholds for overt rockfish behavioral response and more subtle rockfish behavioral response are 180 dB re 1 $\mu\text{Pa}_{0\text{-p}}$ and 161 dB re 1 $\mu\text{Pa}_{0\text{-p}}$, respectively.

Using an experimental hook and line fishery approach, Skalski et al. (1992) studied the potential effects of seismic airgun sound on the distribution and catchability of rockfishes. The source SPL of the

single airgun used in the study was 223 dB re $1 \mu\text{Pa} \cdot \text{m}_{0-p}$, and the received SPLs at the bases of the rockfish aggregations ranged from 186 to 191 dB re $1 \mu\text{Pa}_{0-p}$. Characteristics of the fish aggregations were assessed using echosounders. During long-term stationary seismic airgun discharge, there was an overall downward shift in fish distribution. The authors also observed a significant decline in total catch of rockfishes during seismic discharge. It should be noted that this experimental approach was quite different from an actual seismic survey, in that duration of exposure was much longer.

In another study, caged European sea bass (*Dicentrarchus labrax*) were exposed to multiple discharges from a moving seismic airgun array with a source SPL of about 256 dB re $1 \mu\text{Pa} \cdot \text{m}_{0-p}$ (unspecified measure type) (Santulli et al. 1999). The airguns were discharged every 25 s during a 2-h period. The minimum distance between fish and seismic source was 180 m. The authors did not indicate any observed pathological injury to the sea bass. Blood was collected from both exposed fish (6 h post-exposure) and control fish (6 h pre-exposure) and subsequently analyzed for cortisol, glucose, and lactate levels. Levels of cortisol, glucose, and lactate were significantly higher in the sera of exposed fish compared to sera of control fish. The elevated levels of all three chemicals returned to pre-exposure levels within 72 h of exposure (Santulli et al. 1999).

Santulli et al. (1999) also used underwater video cameras to monitor fish response to seismic airgun discharge. Resultant video indicated slight startle responses by some of the sea bass when the seismic airgun array discharged as far as 2.5 km from the cage. The proportion of sea bass that exhibited startle response increased as the airgun sound source approached the cage. Once the seismic array was within 180 m of the cage, the sea bass were densely packed at the middle of the enclosure, exhibiting random orientation, and appearing more active than they had been under pre-exposure conditions. Normal behavior resumed about 2 h after airgun discharge nearest the fish (Santulli et al. 1999).

Boeger et al. (2006) reported observations of coral reef fishes in field enclosures before, during and after exposure to seismic airgun sound. This Brazilian study used an array of eight airguns that was presented to the fishes as both a mobile sound source and a static sound source. Minimum distances between the sound source and the fish cage ranged from 0 to 7 m. Received sound levels were not reported by Boeger et al. (2006). Neither mortality nor external damage to the fishes was observed in any of the experimental scenarios. Most of the airgun array discharges resulted in startle responses although these behavioral changes lessened with repeated exposures, suggesting habituation.

Chapman and Hawkins (1969) investigated the reactions of free ranging whiting (silver hake), *Merluccius bilinearis*, to an intermittently discharging stationary airgun with a source SPL of 220 dB re $1 \mu\text{Pa} \cdot \text{m}_{0-p}$. Received SPLs were estimated to be 178 dB re $1 \mu\text{Pa}_{0-p}$. The whiting were monitored with an echosounder. Prior to any airgun discharge, the fish were located at a depth range of 25 to 55 m. In apparent response to the airgun sound, the fish descended, forming a compact layer at depths greater than 55 m. After an hour of exposure to the airgun sound, the fish appeared to have habituated as indicated by their return to the pre-exposure depth range, despite the continuing airgun discharge. Airgun discharge ceased for a time and upon its resumption, the fish again descended to greater depths, indicating only temporary habituation.

Hassel et al. (2003, 2004) studied the potential effects of exposure to airgun sound on the behavior of captive lesser sandeel, *Ammodytes marinus*. Depth of the study enclosure used to hold the sandeel was about 55 m. The moving airgun array had an estimated source SPL of 256 dB re $1 \mu\text{Pa} \cdot \text{m}$ (unspecified measure type). Received SPLs were not measured. Exposures were conducted over a 3-day period in a $10 \text{ km} \times 10 \text{ km}$ area with the cage at its center. The distance between airgun array and fish cage ranged from 55 m when the array was overhead to 7.5 km. No mortality attributable to exposure to the airgun sound was noted. Behavior of the fish was monitored using underwater video cameras, echosounders,

and commercial fishery data collected close to the study area. The approach of the seismic vessel appeared to cause an increase in tail-beat frequency although the sandeels still appeared to swim calmly. During seismic airgun discharge, many fish exhibited startle responses, followed by flight from the immediate area. The frequency of occurrence of startle response seemed to increase as the operating seismic array moved closer to the fish. The sandeels stopped exhibiting the startle response once the airgun discharge ceased. The sandeel tended to remain higher in the water column during the airgun discharge, and none of them were observed burying themselves in the soft substrate. The commercial fishery catch data were inconclusive with respect to behavioral effects.

Various species of demersal fishes, blue whiting, and some small pelagic fishes were exposed to a moving seismic airgun array with a source SPL of about 250 dB re 1 $\mu\text{Pa} \cdot \text{m}$ (unspecified measure type) (Dalen and Knutsen 1986). Received SPLs estimated using the assumption of spherical spreading ranged from 200 to 210 dB re 1 μPa (unspecified measure type). Seismic sound exposures were conducted every 10 s during a one week period. The authors used echosounders and sonars to assess the pre- and post-exposure fish distributions. The acoustic mapping results indicated a significant decrease in abundance of demersal fish (36%) after airgun discharge but comparative trawl catches did not support this. Non-significant reductions in the abundances of blue whiting and small pelagic fish were also indicated by post-exposure acoustic mapping.

La Bella et al. (1996) studied the effects of exposure to seismic airgun sound on fish distribution using echosounder monitoring and changes in catch rate of hake by trawl, and clupeoids by gill netting. The seismic array used was composed of 16 airguns and had a source SPL of 256 dB re 1 $\mu\text{Pa} \cdot \text{m}_{0-p}$. The shot interval was 25 s, and exposure durations ranged from 4.6 to 12 h. Horizontal distributions did not appear to change as a result of exposure to seismic discharge, but there was some indication of a downward shift in the vertical distribution. The catch rates during experimental fishing did not differ significantly between pre- and post-seismic fishing periods.

Wardle et al. (2001) used video and telemetry to make behavioral observations of marine fishes (primarily juvenile saithe, adult pollock, juvenile cod, and adult mackerel) inhabiting an inshore reef off Scotland before, during, and after exposure to discharges of a stationary airgun. The received SPLs ranged from about 195 to 218 dB re 1 μPa_{0-p} . Pollock did not move away from the reef in response to the seismic airgun sound, and their diurnal rhythm did not appear to be affected. However, there was an indication of a slight effect on the long-term day-to-night movements of the pollock. Video camera observations indicated that fish exhibited startle responses (“C-starts”) to all received levels. There were also indications of behavioral responses to visual stimuli. If the seismic source was visible to the fish, they fled from it. However, if the source was not visible to the fish, they often continued to move toward it.

The potential effects of exposure to seismic sound on fish abundance and distribution were also investigated by Slotte et al. (2004). Twelve days of seismic survey operations spread over a period of 1 month used a seismic airgun array with a source SPL of 222.6 dB re 1 $\mu\text{Pa} \cdot \text{m}_{p-p}$. The SPLs received by the fish were not measured. Acoustic surveys of the local distributions of various kinds of pelagic fish, including herring, blue whiting, and mesopelagic species, were conducted during the seismic surveys. There was no strong evidence of short-term horizontal distributional effects. With respect to vertical distribution, blue whiting and mesopelagics were distributed deeper (20 to 50 m) during the seismic survey compared to pre-exposure. The average densities of fish aggregations were lower within the seismic survey area, and fish abundances appeared to increase in accordance with increasing distance from the seismic survey area.

Fertilized capelin (*Mallotus villosus*) eggs and monkfish (*Lophius americanus*) larvae were exposed to seismic airgun sound and subsequently examined and monitored for possible effects of the exposure (Payne et al. 2009). The laboratory exposure studies involved a single airgun. Approximate received SPLs measured in the capelin egg and monkfish larvae exposures were 199 to 205 dB re 1 μPa_{p-p} and 205 dB re 1 μPa_{p-p} , respectively. The capelin eggs were exposed to either 10 or 20 airgun discharges, and the monkfish larvae were exposed to either 10 or 30 discharges. No statistical differences in mortality/morbidity between control and exposed subjects were found at 1 to 4 days post-exposure in any of the exposure trials for either the capelin eggs or the monkfish larvae.

In uncontrolled experiments, Kostyvchenko (1973) exposed the eggs of numerous fish species (anchovy, red mullet, crucian carp, blue runner) to various sound sources, including seismic airguns. With the seismic airgun discharge as close as 0.5 m from the eggs, over 75% of them survived the exposure. Egg survival rate increased to over 90% when placed 10 m from the airgun sound source. The range of received SPLs was about 215 to 233 dB re 1 μPa_{0-p} .

Eggs, yolk sac larvae, post-yolk sac larvae, post-larvae, and fry of various commercially important fish species (cod, saithe, herring, turbot, and plaice) were exposed to received SPLs ranging from 220 to 242 dB re 1 μPa (unspecified measure type) (Booman et al. 1996). These received levels corresponded to exposure distances ranging from 0.75 to 6 m. The authors reported some cases of injury and mortality but most of these occurred as a result of exposures at very close range (i.e., <15 m). The rigor of anatomical and pathological assessments was questionable.

Saetre and Ona (1996) applied a “worst-case scenario” mathematical model to investigate the effects of seismic sound on fish eggs and larvae. They concluded that mortality rates caused by exposure to seismic airgun sound are so low compared to the natural mortality that the impact of seismic surveying on recruitment to a fish stock must be regarded as insignificant.

2.2 Freshwater Fishes

Popper et al. (2005) tested the hearing sensitivity of three Mackenzie River fish species after exposure to five discharges from a seismic airgun. The mean received peak SPL was 205 to 209 dB re 1 μPa per discharge, and the approximate mean received SEL was 176 to 180 dB re 1 $\mu\text{Pa}^2 \cdot \text{s}$ per discharge. While the broad whitefish showed no Temporary Threshold Shift (TTS) as a result of the exposure, adult northern pike and lake chub exhibited TTSs of 10 to 15 dB, followed by complete recovery within 24 h of exposure. The same animals were also examined to determine whether there were observable effects on the sensory cells of the inner ear as a result of exposure to seismic sound (Song et al. 2008). No damage to the ears of the fishes was found, including those that exhibited TTS.

In another part of the same Mackenzie River project, Jorgenson and Gyselman (2009) investigated the behavioral responses of arctic riverine fishes to seismic airgun sound. They used hydroacoustic survey techniques to determine whether fish behavior upon exposure to airgun sound can either mitigate or enhance the potential impact of the sound. The study indicated that fish behavioral characteristics were generally unchanged by the exposure to airgun sound. The tracked fish did not exhibit herding behavior in front of the mobile airgun array and, therefore, were not exposed to sustained high sound levels.

2.3 Anadromous Fishes

In uncontrolled experiments using a very small sample of different groups of young salmonids, including Arctic cisco, fish were caged and exposed to various types of sound. One sound type was either a single firing or a series of four firings 10 to 15 s apart of a 300-in³ seismic airgun at 2000 to 2200 psi (Falk and Lawrence 1973). Swim bladder damage was reported but no mortality was observed when fish

were exposed within 1 to 2 m of an airgun source with source level, as estimated by Turnpenny and Nedwell (1994), of ~230 dB re 1 $\mu\text{Pa} \cdot \text{m}$ (unspecified measure).

Thomsen (2002) exposed rainbow trout and Atlantic salmon held in aquaculture enclosures to the sounds from a small airgun array. Received SPLs were 142 to 186 dB re 1 $\mu\text{Pa}_{\text{p-p}}$. The fish were exposed to 124 pulses over a 3-day period. In addition to monitoring fish behavior with underwater video cameras, the authors also analyzed cod and haddock catch data from a longline fishing vessel operating in the immediate area. Only eight of the 124 shots appeared to evoke behavioral reactions by the salmonids, but overall impacts were minimal. No fish mortality was observed during or immediately after exposure. The author reported no significant effects on cod and haddock catch rates, and the behavioral effects were hard to differentiate from normal behavior.

Weinhold and Weaver (1972, cited in Turnpenny et al. 1994) exposed caged coho salmon smolts to impulses from 330 and 660-in³ airguns at distances ranging from 1 to 10 m, resulting in received levels estimated at ~214 to 216 dB (units not given). No lethal effects were observed.

It should be noted that, in a recent and comprehensive review, Hastings and Popper (2005) take issue with many of the authors cited above for problems with experimental design and execution, measurements, and interpretation. Hastings and Popper (2005) deal primarily with possible effects of pile-driving sounds (which, like airgun sounds, are impulsive and repetitive). However, that review provides an excellent and critical review of the impacts to fish from other underwater anthropogenic sounds.

3. Indirect Effects on Fisheries

The most comprehensive experimentation on the effects of seismic airgun sound on catchability of fishes was conducted in the Barents Sea by Engås et al. (1993, 1996). They investigated the effects of seismic airgun sound on distributions, abundances, and catch rates of cod and haddock using acoustic mapping and experimental fishing with trawls and longlines. The maximum source SPL was about 248 dB re 1 $\mu\text{Pa} \cdot \text{m}_{\text{0-p}}$ based on back-calculations from measurements collected via a hydrophone at depth 80 m. No measurements of the received SPLs were made. Davis et al. (1998) estimated the received SPL at the sea bottom immediately below the array and at 18 km from the array to be 205 dB re 1 $\mu\text{Pa}_{\text{0-p}}$ and 178 dB re 1 $\mu\text{Pa}_{\text{0-p}}$, respectively. Engås et al. (1993, 1996) concluded that there were indications of distributional change during and immediately following the seismic airgun discharge (45 to 64% decrease in acoustic density according to sonar data). The lowest densities were observed within 9.3 km of the seismic discharge area. The authors indicated that trawl catches of both cod and haddock declined after the seismic operations. While longline catches of haddock also showed decline after seismic airgun discharge, those for cod increased.

Løkkeborg (1991), Løkkeborg and Soldal (1993), and Dalen and Knutsen (1986) also examined the effects of seismic airgun sound on demersal fish catches. Løkkeborg (1991) examined the effects on cod catches. The source SPL of the airgun array used in his study was 239 dB re 1 $\mu\text{Pa} \cdot \text{m}$ (unspecified measure type), but received SPLs were not measured. Approximately 43 h of seismic airgun discharge occurred during an 11-day period, with a five-second interval between pulses. Catch rate decreases ranging from 55 to 80% within the seismic survey area were observed. This apparent effect persisted for at least 24 h within about 10 km of the survey area.

Turnpenny et al. (1994) examined results of these studies as well as the results of other studies on rockfish. They used rough estimations of received SPLs at catch locations and concluded that catchability is reduced when received SPLs exceed 160 to 180 dB re 1 $\mu\text{Pa}_{\text{0-p}}$. They also concluded that reaction thresholds of fishes lacking a swim bladder (e.g., flatfish) would likely be about 20 dB higher. Given the

considerable variability in sound transmission loss between different geographic locations, the SPLs that were assumed in these studies were likely quite inaccurate.

Turnpenny and Nedwell (1994) also reported on the effects of seismic airgun discharge on inshore bass fisheries in shallow U.K. waters (5 to 30 m deep). The airgun array used had a source level of 250 dB re 1 $\mu\text{Pa} \cdot \text{m}_{0-p}$. Received levels in the fishing areas were estimated to be 163–191 dB re 1 μPa_{0-p} . Using fish tagging and catch record methodologies, they concluded that there was not any distinguishable migration from the ensonified area, nor was there any reduction in bass catches on days when seismic airguns were discharged. The authors concluded that effects on fisheries would be smaller in shallow nearshore waters than in deep water because attenuation of sound is more rapid in shallow water.

Skalski et al. (1992) used a 100-in³ airgun with a source level of 223 dB re 1 $\mu\text{Pa} \cdot \text{m}_{0-p}$ to examine the potential effects of airgun sound on the catchability of rockfishes. The moving airgun was discharged along transects in the study fishing area, after which a fishing vessel deployed a set line, ran three echosounder transects, and then deployed two more set lines. Each fishing experiment lasted 1 h 25 min. Received SPLs at the base of the rockfish aggregations ranged from 186 to 191 dB re 1 μPa_{0-p} . The catch-per-unit-effort (CPUE) for rockfish declined on average by 52.4% when the airguns were operating. Skalski et al. (1992) believed that the reduction in catch resulted from a change in behavior of the fishes. The fish schools descended towards the bottom and their swimming behavior changed during airgun discharge. Although fish dispersal was not observed, the authors hypothesized that it could have occurred at a different location with a different bottom type. Skalski et al. (1992) did not continue fishing after cessation of airgun discharge. They speculated that CPUE would quickly return to normal in the experimental area, because fish behavior appeared to normalize within minutes of cessation of airgun discharge. However, in an area where exposure to airgun sound might have caused the fish to disperse, the authors suggested that a lower CPUE might persist for a longer period.

European sea bass were exposed to sound from seismic airgun arrays with a source SPL of 262 dB re 1 $\mu\text{Pa} \cdot \text{m}_{0-p}$ (Pickett et al. 1994). The seismic survey was conducted over a period of 4 to 5 months. The study was intended to investigate the effects of seismic airgun discharge on inshore bass fisheries. Information was collected through a tag and release program, and from the logbooks of commercial fishermen. Most of the 152 recovered fish from the tagging program were caught within 10 km of the release site, and it was suggested that most of these bass did not leave the area for a prolonged period. With respect to the commercial fishery, no significant changes in catch rate were observed (Pickett et al. 1994).

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APPENDIX E:

REVIEW OF THE EFFECTS OF AIRGUN SOUNDS ON MARINE INVERTEBRATES¹⁵

This review provides a detailed summary of the limited data and available literature on the observed effects (or lack of effects) of exposure to airgun sound on marine invertebrates. Specific conditions and results of the studies, including sound exposure levels and sound thresholds of responses, are discussed when available.

Sound caused by underwater seismic survey equipment results in energy pulses with very high peak pressures (Richardson et al. 1995). This was especially true when chemical explosives were used for underwater surveys. Virtually all underwater seismic surveying conducted today uses airguns which typically have lower peak pressures and longer rise times than chemical explosives. However, sound levels from underwater airgun discharges might still be high enough to potentially injure or kill animals located close to the source. Also, there is a potential for disturbance to normal behavior upon exposure to airgun sound. The following sections provide an overview of sound production and detection in marine invertebrates, and information on the effects of exposure to sound on marine invertebrates, with an emphasis on seismic survey sound. In addition, Fisheries and Oceans Canada has published two internal documents that provide a literature review of the effects of seismic and other underwater sound on invertebrates (Moriyasu et al. 2004; Payne et al. 2008). The available information as reviewed in those documents and here includes results of studies of varying degrees of scientific rigor as well as anecdotal information.

1. Sound Production

Much of the available information on acoustic abilities of marine invertebrates pertains to crustaceans, specifically lobsters, crabs and shrimps. Other acoustic-related studies have been conducted on cephalopods. Many invertebrates are capable of producing sound, including barnacles, amphipods, shrimp, crabs, and lobsters (Au and Banks 1998; Tolstoganova 2002). Invertebrates typically produce sound by scraping or rubbing various parts of their bodies, although they also produce sound in other ways. Sounds made by marine invertebrates may be associated with territorial behavior, mating, courtship, and aggression. On the other hand, some of these sounds may be incidental and not have any biological relevance. Sounds known to be produced by marine invertebrates have frequencies ranging from 87 Hz to 200 kHz, depending on the species.

Both male and female American lobsters *Homarus americanus* produce a buzzing vibration with the carapace when grasped (Pye and Watson III 2004; Henninger and Watson III 2005). Larger lobsters vibrate more consistently than smaller lobsters, suggesting that sound production may be involved with mating behavior. Sound production by other species of lobsters has also been studied. Among deep-sea lobsters, sound level was more variable at night than during the day, with the highest levels occurring at the lowest frequencies.

While feeding, king crab *Paralithodes camtschaticus* produce impulsive sounds that appear to stimulate movement by other crabs, including approach behavior (Tolstoganova 2002). King crab also appeared to produce 'discomfort' sounds when environmental conditions were manipulated. These discomfort sounds differ from the feeding sounds in terms of frequency range and pulse duration.

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Snapping shrimp *Synalpheus parneomeris* are among the major sources of biological sound in temperate and tropical shallow-water areas (Au and Banks 1998). By rapidly closing one of its frontal chelae (claws), a snapping shrimp generates a forward jet of water and the cavitation of fast moving water produces a sound. Both the sound and the jet of water may function in feeding and territorial behaviors of alpheididae shrimp. Measured source sound pressure levels (SPLs) for snapping ship were 183–189 dB re $1 \mu\text{Pa} \cdot \text{m}_{\text{p-p}}$ and extended over a frequency range of 2–200 kHz.

2. Sound Detection

There is considerable debate about the hearing capabilities of aquatic invertebrates. Whether they are able to hear or not depends on how underwater sound and underwater hearing are defined. In contrast to the situation in fish and marine mammals, no physical structures have been discovered in aquatic invertebrates that are stimulated by the pressure component of sound. However, vibrations (i.e., mechanical disturbances of the water) are also characteristic of sound waves. Rather than being pressure-sensitive, aquatic invertebrates appear to be most sensitive to the vibrational component of sound (Breithaupt 2002). Statocyst organs may provide one means of vibration detection for aquatic invertebrates.

More is known about the acoustic detection capabilities in decapod crustaceans than in any other marine invertebrate group, although cephalopod acoustic capabilities are now becoming a focus of study. Crustaceans appear to be most sensitive to sounds of low frequencies, i.e., <1000 Hz (Budelmann 1992; Popper et al. 2001). A study by Lovell et al. (2005) suggests greater sensitivity of the prawn *Palaemon serratus* to low-frequency sound than previously thought. Lovell et al. (2006) showed that *P. serratus* is capable of detecting a 500 Hz tone regardless of the prawn's body size and the related number and size of statocyst hair cells. Studies of American lobsters suggest that these crustaceans are more sensitive to higher frequency sounds than previously realized (Pye and Watson III 2004).

It is possible that statocyst hair cells of cephalopods are directionally sensitive in a way that is similar to the responses of hair cells of the vertebrate vestibular and lateral line systems (Budelmann and Williamson 1994; Budelmann 1996). Kaifu et al. (2008) provided evidence that the cephalopod *Octopus ocellatus* detects particle motion with its statocyst. Studies by Packard et al. (1990), Rawizza (1995) and Komak et al. (2005) have tested the sensitivities of various cephalopods to water-borne vibrations, some of which were generated by low-frequency sound. Using the auditory brainstem response (ABR) approach, Hu et al. (2009) showed that auditory evoked potentials can be obtained in the frequency ranges 400 to 1500 Hz for the squid *Sepiotheutis lessoniana* and 400 to 1000 Hz for the octopus *Octopus vulgaris*, higher than frequencies previously observed to be detectable by cephalopods.

In summary, only a few studies have been conducted on the sensitivity of certain invertebrate species to underwater sound. Available data suggest that they are capable of detecting vibrations but they do not appear to be capable of detecting pressure fluctuations.

3. Potential Seismic Effects

In marine invertebrates, potential effects of exposure to sound can be categorized as pathological, physiological, and behavioral. Pathological effects include lethal and sub-lethal injury to the animals, physiological effects include temporary primary and secondary stress responses, and behavioral effects refer to changes in exhibited behaviors (i.e., disturbance). The three categories should not be considered as independent of one another and are likely interrelated in complex ways.

Pathological Effects.—In water, acute injury or death of organisms as a result of exposure to sound appears to depend on two features of the sound source: (1) the received peak pressure, and (2) the time required for the pressure to rise and decay. Generally, the higher the received pressure and the less

time it takes for the pressure to rise and decay, the greater the chance of acute pathological effects. Considering the peak pressure and rise/decay time characteristics of seismic airgun arrays used today, the associated pathological zone for invertebrates would be expected to be small (i.e., within a few meters of the seismic source, at most). Few studies have assessed the potential for pathological effects on invertebrates from exposure to seismic sound.

The pathological impacts of seismic survey sound on marine invertebrates were investigated in a pilot study on snow crabs *Chionoecetes opilio* (Christian et al. 2003, 2004). Under controlled field experimental conditions, captive adult male snow crabs, egg-carrying female snow crabs, and fertilized snow crab eggs were exposed to variable SPLs (191–221 dB re 1 μPa_{0-p}) and sound energy levels (SELs) (<130–187 dB re 1 $\mu\text{Pa}^2 \cdot \text{s}$). Neither acute nor chronic (12 weeks post-exposure) mortality was observed for the adult crabs. However, a significant difference in development rate was noted between the exposed and unexposed fertilized eggs/embryos. The egg mass exposed to seismic energy had a higher proportion of less-developed eggs than did the unexposed mass. It should be noted that both egg masses came from a single female and any measure of natural variability was unattainable (Christian et al. 2003, 2004).

In 2003, a collaborative study was conducted in the southern Gulf of St. Lawrence, Canada, to investigate the effects of exposure to sound from a commercial seismic survey on egg-bearing female snow crabs (DFO 2004). This study had design problems that impacted interpretation of some of the results (Chadwick 2004). Caged animals were placed on the ocean bottom at a location within the survey area and at a location outside of the survey area. The maximum received SPL was ~195 dB re 1 μPa_{0-p} . The crabs were exposed for 132 hr of the survey, equivalent to thousands of seismic shots of varying received SPLs. The animals were retrieved and transferred to laboratories for analyses. Neither acute nor chronic lethal or sub-lethal injury to the female crabs or crab embryos was indicated. DFO (2004) reported that some exposed individuals had short-term soiling of gills, antennules and statocysts, bruising of the hepatopancreas and ovary, and detached outer membranes of oocytes. However, these differences could not be linked conclusively to exposure to seismic survey sound. Boudreau et al. (2009) presented the proceedings of a workshop held to evaluate the results of additional studies conducted to answer some questions arising from the original study discussed in DFO (2004). Proceedings of the workshop did not include any more definitive conclusions regarding the original results.

Payne et al. (2007) recently conducted a pilot study of the effects of exposure to airgun sound on various health endpoints of the American lobster. Adult lobsters were exposed either 20 to 200 times to 202 dB re 1 μPa_{p-p} or 50 times to 227 dB re 1 μPa_{p-p} , and then monitored for changes in survival, food consumption, turnover rate, serum protein level, serum enzyme levels, and serum calcium level. Observations extended over a period of a few days to several months. Results showed no delayed mortality or damage to the mechanosensory systems associated with animal equilibrium and posture (as assessed by turnover rate).

In a field study, Pearson et al. (1994) exposed Stage II larvae of the Dungeness crab *Cancer magister* to single discharges from a seven-airgun array and compared their mortality and development rates with those of unexposed larvae. No statistically significant differences were found in immediate survival, long-term survival, or time to molt between the exposed and unexposed larvae, even those exposed within 1 m of the seismic source.

In 2001 and 2003, there were two incidents of multiple strandings of the giant squid *Architeuthis dux* on the north coast of Spain, and there was speculation that the strandings were caused by exposure to geophysical seismic survey sounds occurring at about the same time in the Bay of Biscay (Guerra et al. 2004). A total of nine giant squid, either stranded or moribund and floating at the surface, were collected at these times. However, Guerra et al. (2004) did not present any evidence that conclusively links the

giant squid strandings and floaters to seismic activity in the area. Based on necropsies of seven (six females and one male) specimens, there was evidence of acute tissue damage. The authors speculated that one female with extensive tissue damage was affected by the impact of acoustic waves. However, little is known about the impact of strong airgun signals on cephalopods and the authors did not describe the seismic sources, locations, and durations of the Bay of Biscay surveys. In addition, there were no controls, the observations were circumstantial, and the examined animals had been dead long enough for commencement of tissue degradation.

McCauley et al. (2000a,b) exposed caged cephalopods to noise from a single 20-in³ airgun with maximum SPLs of >200 dB re 1 μPa_{0-p} . Statocysts were removed and preserved, but at the time of publication, results of the statocyst analyses were not available. No squid or cuttlefish mortalities were reported as a result of these exposures.

Physiological Effects.—Biochemical responses by marine invertebrates to acoustic exposure have also been studied to a limited degree. Such studies of stress responses could possibly provide some indication of the physiological consequences of acoustic exposure and perhaps any subsequent chronic detrimental effects. Stress responses could potentially affect animal populations by reducing reproductive capacity and adult abundance.

Stress indicators in the haemolymph of adult male snow crabs were monitored immediately after exposure of the animals to seismic survey sound (Christian et al. 2003, 2004) and at various intervals after exposure. No significant acute or chronic differences were found between exposed and unexposed animals in which various stress indicators (e.g., proteins, enzymes, cell type count) were measured.

Payne et al. (2007), in their study of the effects of exposure of adult American lobsters to airgun sound, noted decreases in the levels of serum protein, particular serum enzymes and serum calcium, in the haemolymph of animals exposed to the sound pulses. Statistically significant differences ($P=0.05$) were noted in serum protein at 12 days post-exposure, serum enzymes at 5 days post-exposure, and serum calcium at 12 days post-exposure. During the histological analysis conducted 4 months post-exposure, Payne et al. (2007) noted more deposits of PAS-stained material, likely glycogen, in the hepatopancreas of some of the exposed lobsters. Accumulation of glycogen could be due to stress or disturbance of cellular processes.

Price (2007) found that blue mussels *Mytilus edulis* responded to a 10 kHz pure tone continuous signal by decreasing respiration. Smaller mussels did not appear to react until exposed for 30 min whereas larger mussels responded after 10 min of exposure. The oxygen uptake rate tended to be reduced to a greater degree in the larger mussels than in the smaller animals.

In general, the limited studies done to date on the effects of acoustic exposure on marine invertebrates have not demonstrated any serious pathological and physiological effects.

Behavioral Effects.—Some recent studies have focused on potential behavioral effects on marine invertebrates.

Christian et al. (2003) investigated the behavioral effects of exposure to airgun sound on snow crabs. Eight animals were equipped with ultrasonic tags, released, and monitored for multiple days prior to exposure and after exposure. Received SPL and SEL were ~ 191 dB re 1 μPa_{0-p} and <130 dB re 1 $\mu\text{Pa}^2 \cdot \text{s}$, respectively. The crabs were exposed to 200 discharges over a 33-min period. None of the tagged animals left the immediate area after exposure to the seismic survey sound. Five animals were captured in the snow crab commercial fishery the following year, one at the release location, one 35 km from the release location, and three at intermediate distances from the release location.

Another study approach used by Christian et al. (2003) involved monitoring snow crabs with a remote video camera during their exposure to airgun sound. The caged animals were placed on the ocean bottom at a depth of 50 m. Received SPL and SEL were ~ 202 dB re $1 \mu\text{Pa}_{0-p}$ and 150 dB re $1 \mu\text{Pa}^2 \cdot \text{s}$, respectively. The crabs were exposed to 200 discharges over a 33-min period. They did not exhibit any overt startle response during the exposure period.

Christian et al. (2003) also investigated the pre- and post-exposure catchability of snow crabs during a commercial fishery. Received SPLs and SELs were not measured directly and likely ranged widely considering the area fished. Maximum SPL and SEL were likely similar to those measured during the telemetry study. There were seven pre-exposure and six post-exposure trap sets. Unfortunately, there was considerable variability in set duration because of poor weather. Results indicated that the catch-per-unit-effort did not decrease after the crabs were exposed to seismic survey sound.

Parry and Gason (2006) statistically analyzed data related to rock lobster *Jasus edwardsii* commercial catches and seismic surveying in Australian waters from 1978 to 2004. They did not find any evidence that lobster catch rates were affected by seismic surveys.

Caged female snow crabs exposed to airgun sound associated with a recent commercial seismic survey conducted in the southern Gulf of St. Lawrence, Canada, exhibited a higher rate of ‘righting’ than those crabs not exposed to seismic survey sound (J. Payne, Research Scientist, DFO, St. John’s, Nfld., pers. comm.). ‘Righting’ refers to a crab’s ability to return itself to an upright position after being placed on its back. Christian et al. (2003) made the same observation in their study.

Payne et al. (2007), in their study of the effects of exposure to airgun sound on adult American lobsters, noted a trend for increased food consumption by the animals exposed to seismic sound.

Andriguetto-Filho et al. (2005) attempted to evaluate the impact of seismic survey sound on artisanal shrimp fisheries off Brazil. Bottom trawl yields were measured before and after multiple-day shooting of an airgun array. Water depth in the experimental area ranged between 2 and 15 m. Results of the study did not indicate any significant deleterious impact on shrimp catches. Anecdotal information from Newfoundland, Canada, indicated that catch rates of snow crabs showed a significant reduction immediately following a pass by a seismic survey vessel (G. Chidley, Newfoundland fisherman, pers. comm.). Additional anecdotal information from Newfoundland indicated that a school of shrimp observed via a fishing vessel sonar shifted downwards and away from a nearby seismic airgun sound source (H. Thorne, Newfoundland fisherman, pers. comm.). This observed effect was temporary.

Caged brown shrimp *Crangon crangon* reared under different acoustical conditions exhibited differences in aggressive behavior and feeding rate (Lagardère 1982). Those exposed to a continuous sound source showed more aggression and less feeding behavior. It should be noted that behavioral responses by caged animals may differ from behavioral responses of animals in the wild.

McCauley et al. (2000a,b) provided the first evidence of the behavioral response of southern calamari squid *Sepioteuthis australis* exposed to seismic survey sound. McCauley et al. reported on the exposure of caged cephalopods (50 squid and two cuttlefish) to noise from a single 20-in³ airgun. The cephalopods were exposed to both stationary and mobile sound sources. The two-run total exposure times during the three trials ranged from 69 to 119 min. at a firing rate of once every 10–15 s. The maximum SPL was >200 dB re $1 \mu\text{Pa}_{0-p}$. Some of the squid fired their ink sacs apparently in response to the first shot of one of the trials and then moved quickly away from the airgun. In addition to the above-described startle responses, some squid also moved towards the water surface as the airgun approached. McCauley et al. (2000a,b) reported that the startle and avoidance responses occurred at a received SPL of 174 dB re $1 \mu\text{Pa}_{\text{rms}}$. They also exposed squid to a ramped approach-depart airgun signal whereby the received SPL was gradually increased over time. No strong startle response (i.e., ink discharge) was

observed, but alarm responses, including increased swimming speed and movement to the surface, were observed once the received SPL reached a level in the 156–161 dB re 1 $\mu\text{Pa}_{\text{rms}}$ range.

Komak et al. (2005) also reported the results of a study of cephalopod behavioral responses to local water movements. In this case, juvenile cuttlefish *Sepia officinalis* exhibited various behavioral responses to local sinusoidal water movements of different frequencies between 0.01 and 1000 Hz. These responses included body pattern changing, movement, burrowing, reorientation, and swimming. Similarly, the behavioral responses of the octopus *Octopus ocellatus* to non-impulse sound have been investigated by Kaifu et al. (2007). The sound stimuli, reported as having levels 120 dB re 1 μPa rms, were at various frequencies: 50, 100, 150, 200 and 1000 Hz. The respiratory activity of the octopus changed when exposed to sound in the 50–150 Hz range but not for sound at 200–1,000 Hz. Respiratory suppression by the octopus might have represented a means of escaping detection by a predator.

Low-frequency sound (<200 Hz) has also been used as a means of preventing settling/fouling by aquatic invertebrates such as zebra mussels *Dreissena polymorpha* (Donskoy and Ludyanskiy 1995) and balanoid barnacles *Balanus* sp. (Branscomb and Rittschof 1984). Price (2007) observed that blue mussels *Mytilus edulis* closed their valves upon exposure to 10 kHz pure tone continuous sound.

Although not demonstrated in the invertebrate literature, masking can be considered a potential effect of anthropogenic underwater sound on marine invertebrates. Some invertebrates are known to produce sounds (Au and Banks 1998; Tolstoganova 2002; Latha et al. 2005). The functionality and biological relevance of these sounds are not understood (Jeffs et al. 2003, 2005; Lovell et al. 2005; Radford et al. 2007). If some of the sounds are of biological significance to some invertebrates, then masking of those sounds or of sounds produced by predators, at least the particle displacement component, could potentially have adverse effects on marine invertebrates. However, even if masking does occur in some invertebrates, the intermittent nature of airgun sound is expected to result in less masking effect than would occur with continuous sound.

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